

# Multi-Multigrid: A Parallelized Multigrid Solver for Python

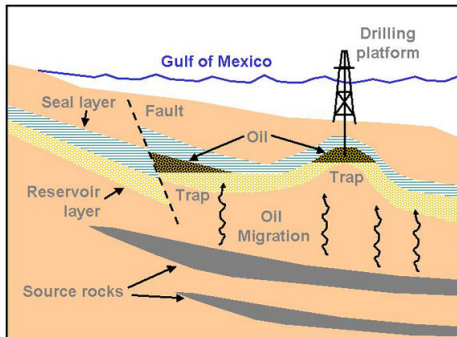
Tom S Bertalan, Chemical and Biological Engineering;  
Faculty Mentor: Roger B Sidje, Mathematics  
The University of Alabama

9 April, 2012

# Outline

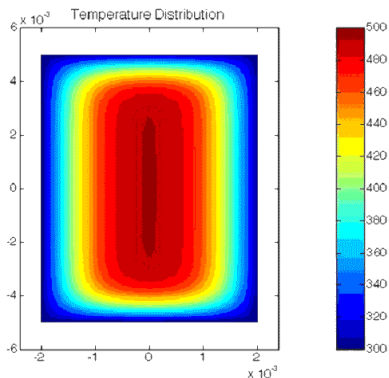
- 1 Motivation: Real-Life Examples
- 2 Mathematical Formulation
- 3 Multigrid
- 4 Future Work
- 5 ACK

# Petroleum Engineering: pressure driven flow



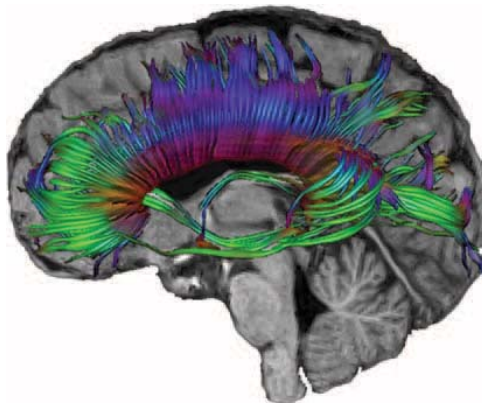
Cross-section of an oil deposit. Photo credit: NOAA, J.Bratton.

# Mechanical Engineering: heat transfer



Temperature across a 2D plate in a time-stepping simulation with a Dirichlet boundary condition.

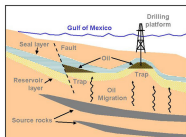
## Medical Imaging: anisotropic diffusion



Diffusion Tensor Magnetic Resonance Imaging (DTMRI) uses the diffusion paths of magnetically active particles to map neural tracts in the brain.

# Constitutive Equations

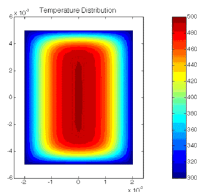
## Petroleum Engineering



Darcy's Law:

$$-\frac{\kappa}{\mu} \nabla P = q$$

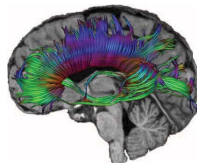
## Mechanical Engineering



Heat Equation:

$$\alpha \nabla^2 u = \frac{\partial u}{\partial t}$$

## Medical Imaging

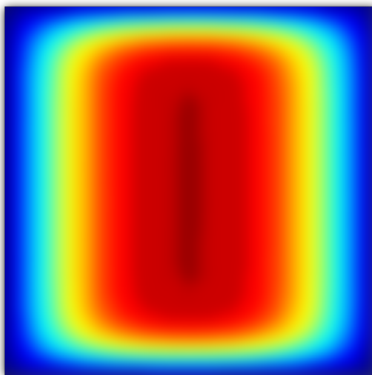


Fick's Law:

$$\nabla \cdot (D \nabla c) = \frac{\partial c}{\partial t}$$

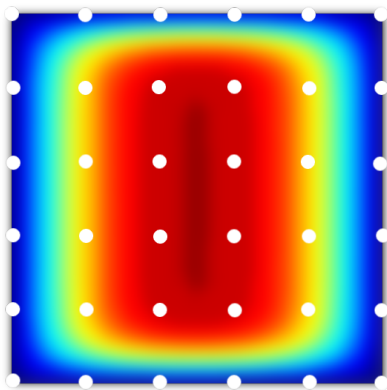
## 2D Domain: Temperature Profile

A hot conductive square is surrounded by cold, well-mixed fluid.



## 2D Domain: Grid Coordinates

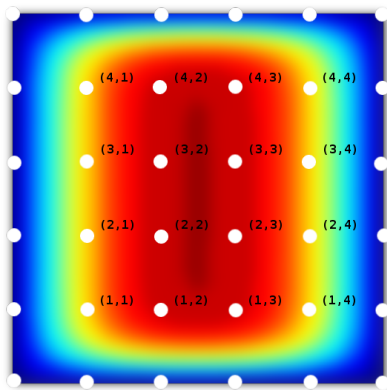
Divide the domain into a discrete grid.





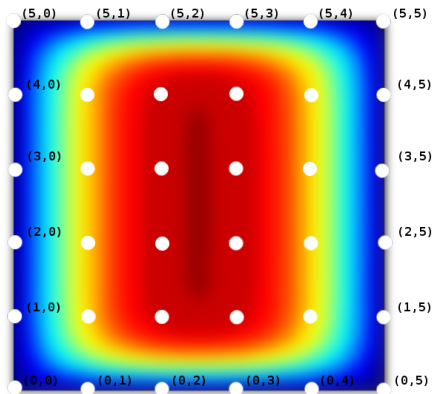
## 2D Domain: Interior

The set of interior points is called  $\Omega$ ...



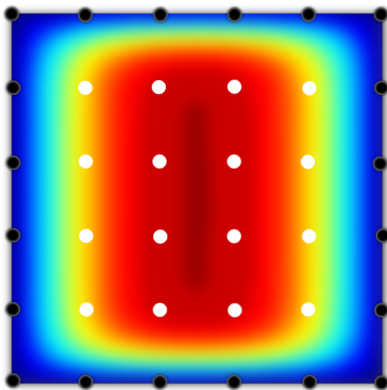
## 2D Domain: Boundary

... and the set of boundary points is called  $\Gamma$ .



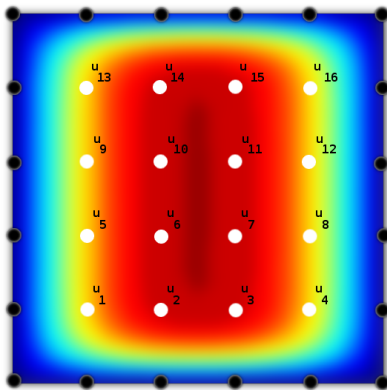
## 2D Domain: Boundary Condition

The temperature on  $\Gamma$  is known to be that of the fluid.



## 2D Domain: Natural Ordering

The vector  $u$  contains all the unknown interior temperatures.



# Discrete Equation: Heat Conduction



$$\nabla^2 u = \frac{1}{\alpha} \frac{\partial u}{\partial t} \quad (1)$$

If there are no heat sources or sinks, the divergence of the temperature is zero, that is,  $\frac{1}{\alpha} \frac{\partial u}{\partial t} \equiv 0$ . In this case, we get the Laplace equation:

$$\nabla^2 u = 0 \quad (2)$$

# Laplace Equation

$$\nabla^2 u = 0 \quad (3)$$

$\nabla^2$  is the Laplacian operator:

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$$

This is in continuous form, but after discretization of the second partial derivatives, we get

$$Au = b \quad (4)$$

So, somehow we have represented  $\nabla^2$  as a matrix  $A$ , and included the boundary conditions in  $b$ .

## Discrete Equation: Partial Derivatives

$$\begin{array}{cccc} \cdot & \cdot & u_{i+1,j} & \cdot \\ \cdot & u_{i,j-1} & u_{i,j} & u_{i,j+1} \\ \cdot & \cdot & u_{i-1,j} & \cdot \\ \cdot & \cdot & \cdot & \cdot \end{array}$$

## Discrete Equation: Partial Derivatives

$$\begin{array}{cccc}
 \cdot & \cdot & u_{i+1,j} & \cdot \\
 \cdot & u_{i,j-1} & u_{i,j} & u_{i,j+1} \\
 \cdot & \cdot & u_{i-1,j} & \cdot \\
 \cdot & \cdot & \cdot & \cdot
 \end{array}$$

$$\frac{\partial^2 u}{\partial x^2} \approx \frac{\frac{u_{i,j+1} - u_{i,j}}{h} - \frac{u_{i,j} - u_{i,j-1}}{h}}{h} = \left( \frac{1}{h^2} \right) (u_{i,j-1} - 2u_{i,j} + u_{i,j+1})$$



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$$\frac{\partial^2 u}{\partial y^2} \approx \frac{\frac{u_{i+1,j} - u_{i,j}}{h} - \frac{u_{i,j} - u_{i-1,j}}{h}}{h} = \left(\frac{1}{h^2}\right) (u_{i-1,j} - 2u_{i,j} + u_{i+1,j})$$

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$$\frac{\partial^2 u}{\partial y^2} \approx \frac{\frac{u_{i+1,j} - u_{i,j}}{h} - \frac{u_{i,j} - u_{i-1,j}}{h}}{h} = \left(\frac{1}{h^2}\right) (u_{i-1,j} - 2u_{i,j} + u_{i+1,j})$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \approx \left(\frac{1}{h^2}\right) (1u_{i-1,j} + 1u_{i,j-1} - 4u_{i,j} + 1u_{i,j+1} + 1u_{i+1,j})$$

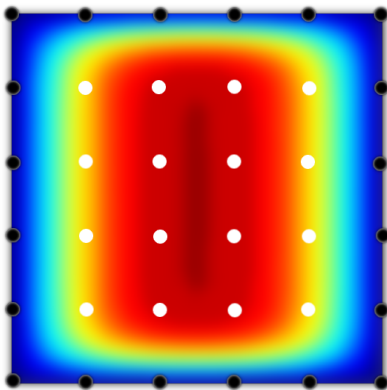


# Numerical Methods

- Direct (Gaussian elimination)
  - Advantages: Accurate, finite number of steps.
  - Disadvantages: Slow, not scalable to large problems.
- Iterative (Gauss-Seidel, Jacobi, SOR, etc.)
  - Advantages: Scalable.
  - Disadvantages: Does not always converge.

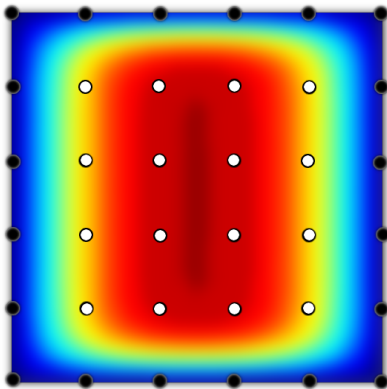
## Multigrid: Given

For a Laplace problem, start knowing only the boundary points.



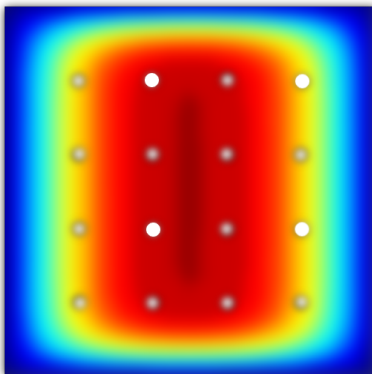
## Multigrid: Iterative Approximation

Find  $u_{approx}$  via quick iterative solver.  
(We now need a correction  $v$  s.t.  $u_{approx} + v = u$ .)



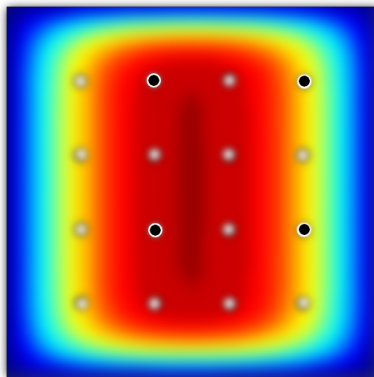
## Multigrid: Coarse Points

Define a coarse set, with only  $1/4^{th}$  the points of the full domain.



## Multigrid: Coarse Correction

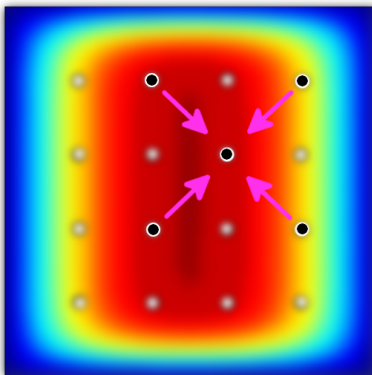
Solve for  $v_{coarse}$  via accurate direct solver at the coarse resolution.





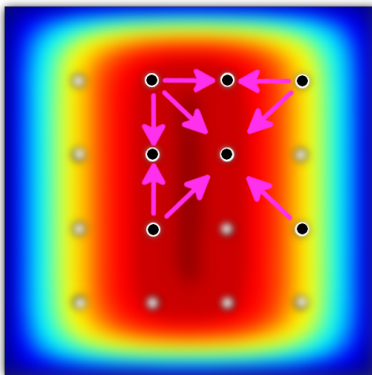
## Multigrid: Interpolation to $v_{fine}$

Interpolate  $v_{coarse}$  to  $v_{fine}$ .



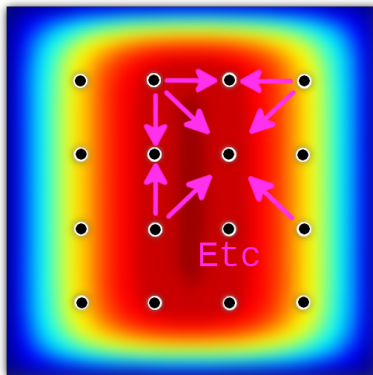
## Multigrid: Interpolation to $v_{fine}$

Interpolate  $v_{coarse}$  to  $v_{fine}$ .

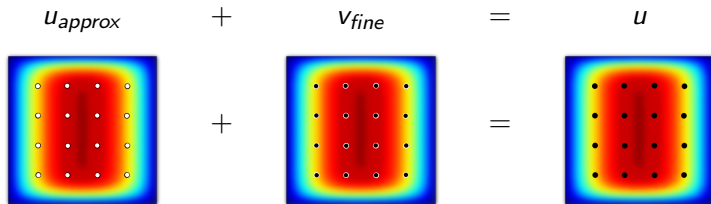


## Multigrid: Interpolation to $v_{fine}$

Interpolate  $v_{coarse}$  to  $v_{fine}$ .

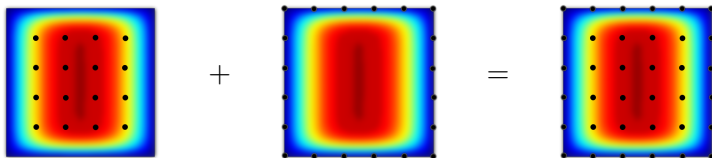


# Multigrid: Correction

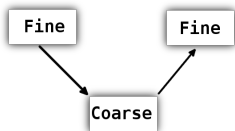


# Multigrid: Solution

The full-domain solution is the combination of  $\Omega$  and  $\Gamma$  points.

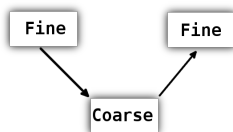


## Multigrid: “Multi”

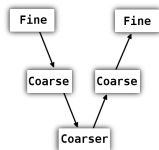


This is a two-grid pattern, with only  $N/4$  coarse points for the direct solver.

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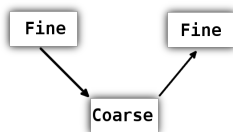


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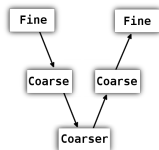


However, we can also extend to a three-grid pattern, with  $N/16$  points in the coarsest set.

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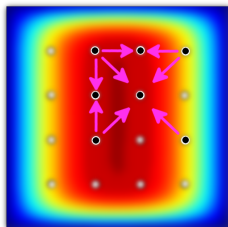
However, we can also extend to a three-grid pattern, with  $N/16$  points in the coarsest set.

By allowing the multigrid cycle function to call itself, recursively, we can extend to arbitrary  $N$ -grids.



## Future Work: Parallelization

Interpolation, for example, can be parallelized.



## Future Work: Parallelization Methods

<b>CPU</b>	(Central Processing Unit)	OpenMP
<b>GPU</b>	(Graphics Processing Unit)	PyCUDA
<b>MPI</b>	Message Passing Interface	OpenMPI
<b>Grid</b>		BOINC; Esimcluster

# Acknowledgements

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Mathematics

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Chemical and Biological Engineering