# Engineering Mechanics AGE 2330

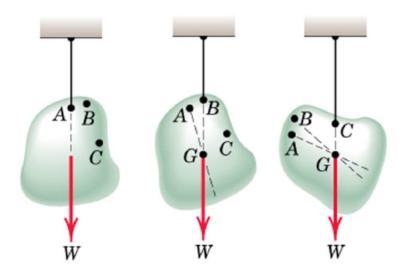
## Lect 7: Center of Mass, Centroid

Dr. Feras Fraige

#### **Center of Mass**

A body of mass *m* in equilibrium under the action of tension in the cord, and resultant *W* of the gravitational forces acting on all particles of the body. -The resultant is collinear with the cord

Suspend the body at different points



-Dotted lines show lines of action of the resultant force in each case.

-These lines of action will be concurrent at a single point G

As long as dimensions of the body are smaller compared with those of the earth.

- we assume uniform and parallel force field due to the gravitational attraction of the earth.

The unique **Point G** is called the Center of Gravity of the body (CG)

#### Determination of CG

- Apply Principle of Moments

Moment of resultant gravitational force W about any axis equals sum of the moments about the same axis of the gravitational forces dW acting on all particles treated as infinitesimal elements. Weight of the body  $W = \int dW$ Moment of weight of an element (dW) @ x-axis = ydWSum of moments for all elements of body =  $\int ydW$ From Principle of Moments:  $\int ydW = \bar{y}W$ 

$$\overline{x} = \frac{\int x dW}{W} \quad \overline{y} = \frac{\int y dW}{W} \quad \overline{z} = \frac{\int z dW}{W}$$

Moment of dW @ z axis??? = 0 or,  $\neq$  0

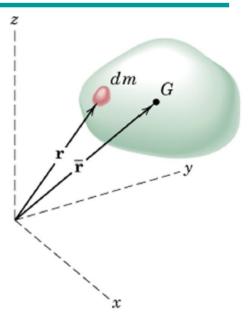
→ Numerator of these expressions represents the sum of the moments; Product of W and corresponding coordinate of G represents the moment of the sum → Moment Principle.

Determination of CG 
$$\bar{x} = \frac{\int x dW}{W}$$
  $\bar{y} = \frac{\int y dW}{W}$   
Substituting  $W = mg$  and  $dW = gdm$   
 $\Rightarrow \quad \bar{x} = \frac{\int x dm}{m}$   $\bar{y} = \frac{\int y dm}{m}$   $\bar{z} = \frac{\int z dm}{m}$ 

In vector notations:

Position vector for elemental mass:  $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ 

Position vector for mass center G:  $\bar{\mathbf{r}} = \bar{x}\mathbf{i} + \bar{y}\mathbf{j} + \bar{z}\mathbf{k}$ 



zdW W

$$\overline{\mathbf{r}} = \frac{\int \mathbf{r} dm}{m}$$

Density  $\rho$  of a body = mass per unit volume

 $\rightarrow$  Mass of a differential element of volume  $dV \rightarrow dm = \rho dV$ 

ightarrow ho may not be constant throughout the body

$$\overline{x} = \frac{\int x\rho dV}{\int \rho dV} \quad \overline{y} = \frac{\int y\rho dV}{\int \rho dV} \quad \overline{z} = \frac{\int z\rho dV}{\int \rho dV}$$

Center of Mass: Following equations independent of g

$$\overline{x} = \frac{\int x dm}{m} \quad \overline{y} = \frac{\int y dm}{m} \quad \overline{z} = \frac{\int z dm}{m}$$
$$\overline{\mathbf{r}} = \frac{\int \mathbf{r} dm}{m} \quad \text{(Vector representation)}$$

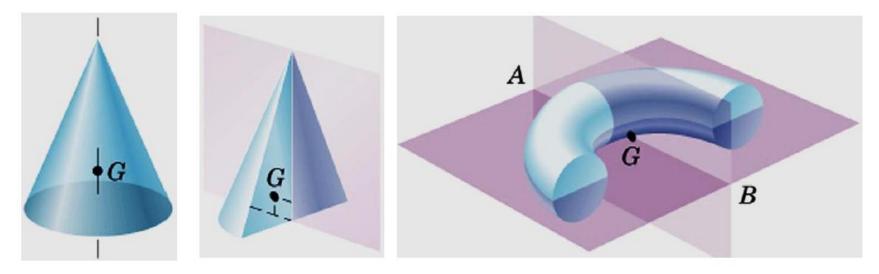
$$\bar{x} = \frac{\int x\rho dV}{\int \rho dV} \quad \bar{y} = \frac{\int y\rho dV}{\int \rho dV} \quad \bar{z} = \frac{\int z\rho dV}{\int \rho dV}$$

 $\rightarrow$  Unique point [=  $f(\rho)$ ] :: Centre of Mass (CM)

- →CM coincides with CG as long as gravity field is treated as uniform and parallel
- $\rightarrow$ CG or CM may lie outside the body

#### Symmetry

 CM always lie on a line or a plane of symmetry in a homogeneous body



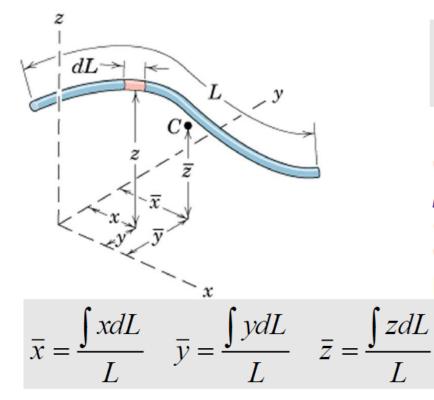
Right CircularHalf Right CircularConeConeCM on centralCM on vertical planeaxisof symmetry

Half Ring CM on intersection of two planes of symmetry (line AB)

#### Centroid

#### - Geometrical property of a body

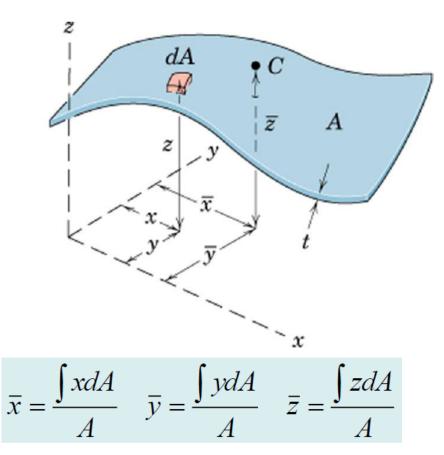
- Body of uniform density :: Centroid and CM coincide



$$\overline{x} = \frac{\int x dm}{m}$$
  $\overline{y} = \frac{\int y dm}{m}$   $\overline{z} = \frac{\int z dm}{m}$ 

Lines: Slender rod, Wire Cross-sectional area = A $\rho$  and A are constant over L $dm = \rho A dL$ Centroid and CM are the same points

Centroid

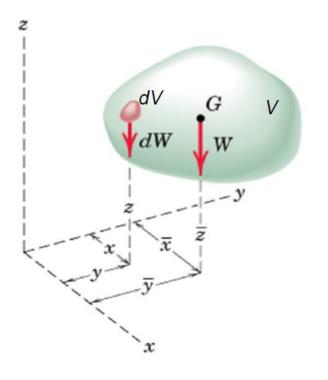


Numerator = First moments of Area

Areas: Body with small but constant thickness t Cross-sectional area = A  $\rho$  and A are constant over A  $dm = \rho t dA$ Centroid and CM are the same points

$$\overline{x} = \frac{\int x dm}{m} \quad \overline{y} = \frac{\int y dm}{m} \quad \overline{z} = \frac{\int z dm}{m}$$

Centroid



Volumes: Body with volume V  $\rho$  constant over V  $dm = \rho dV$ Centroid and CM are the same point

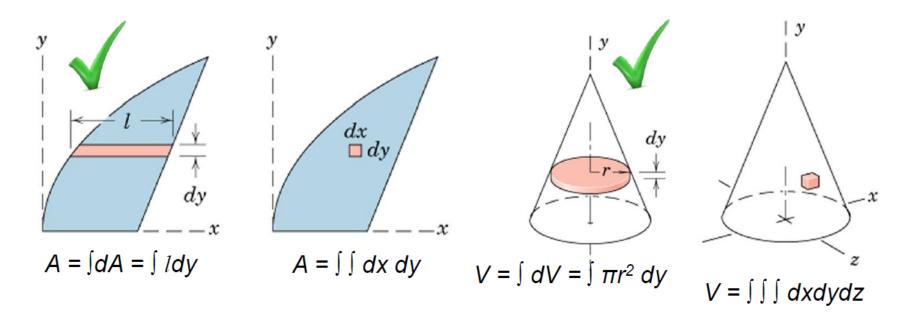
$$\overline{x} = \frac{\int x dm}{m} \quad \overline{y} = \frac{\int y dm}{m} \quad \overline{z} = \frac{\int z dm}{m}$$

$$\overline{x} = \frac{\int x dV}{V} \quad \overline{y} = \frac{\int y dV}{V} \quad \overline{z} = \frac{\int z dV}{V}$$

Numerator = First moments of Volume

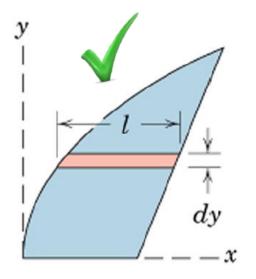
#### (a) Element Selection for Integration

- Order of Element
- First order differential element preferred over higher order element
- only one integration should cover the entire figure



(b) Element Selection for Integration

- Continuity
- Integration of a single element over the entire area
- Continuous function over the entire area



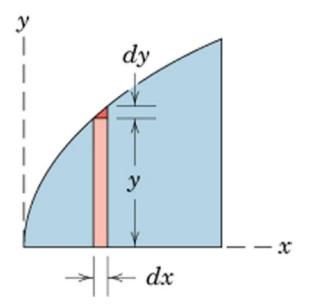
 $x_1$ 

Continuity in the expression for the width of the strip

Discontinuity in the expression for the height of the strip at  $x = x_1$ 

(c) Element Selection for Integration

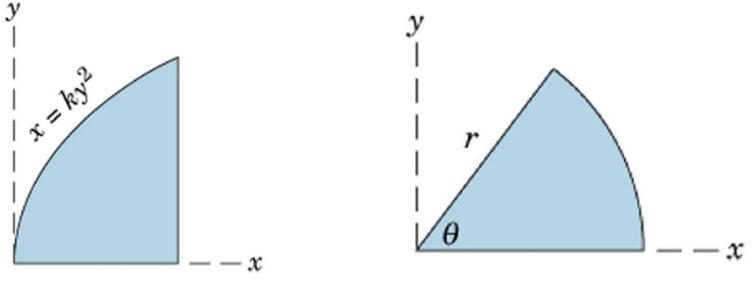
- Discarding higher order terms
- No error in limits



- :: Vertical strip of area under the curve  $\rightarrow dA = ydx$
- :: Ignore 2<sup>nd</sup> order triangular area 0.5*dxdy*

(d) Element Selection for Integration

- Coordinate system
- Convenient to match it with the



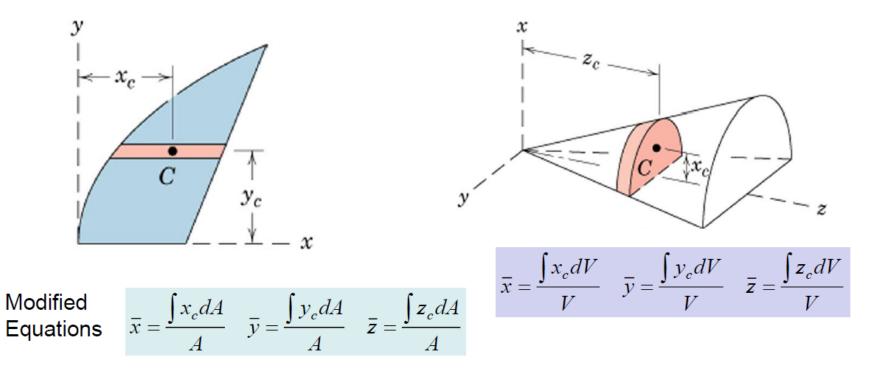
Curvilinear boundary (Rectangular Coordinates)

Circular boundary (Polar coordinates)

(e) Element Selection for Integration

- Centroidal coordinate ( $x_o, y_o, z_c$ ) of element
- $x_{c}, y_{c}, z_{c}$  to be considered for lever arm

:: not the coordinates of the area boundary



#### Centroids of Lines, Areas, and Volumes

- 1.Order of Element Selected for Integration
- 2.Continuity
- **3.Discarding Higher Order Terms**
- 4. Choice of Coordinates

**5.Centroidal Coordinate of Differential Elements** 

$$\overline{x} = \frac{\int x dL}{L}$$
  $\overline{y} = \frac{\int y dL}{L}$   $\overline{z} = \frac{\int z dL}{L}$ 

$$\bar{x} = \frac{\int x_c dA}{A} \quad \bar{y} = \frac{\int y_c dA}{A} \quad \bar{z} = \frac{\int z_c dA}{A}$$

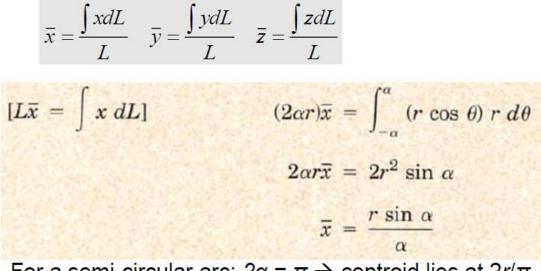
$$\overline{x} = \frac{\int x_c dV}{V} \quad \overline{y} = \frac{\int y_c dV}{V} \quad \overline{z} = \frac{\int z_c dV}{V}$$

## Example on Centroid :: Circular Arc

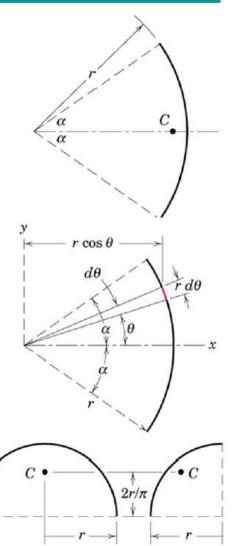
Locate the centroid of the circular arc

Solution: Polar coordinate system is better Since the figure is symmetric: centroid lies on the x axis

Differential element of arc has length  $dL = rd\Theta$ Total length of arc:  $L = 2\alpha r$ *x*-coordinate of the centroid of differential element:  $x=rcos\Theta$ 



For a semi-circular arc:  $2\alpha = \pi \rightarrow$  centroid lies at  $2r/\pi$ 

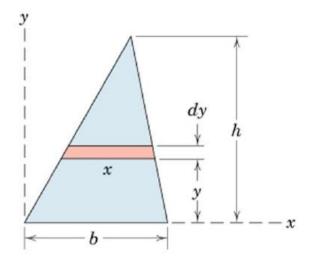


## Example on Centroid :: Triangle

Locate the centroid of the triangle along h from the base

Solution:  

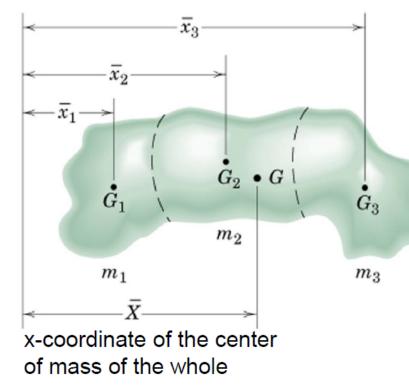
$$dA = xdy$$
;  $x/(h-y) = b/h$   
Total Area,  $A = \frac{1}{2}(bh)$   
 $\bar{x} = \frac{\int x_c dA}{A}$   $\bar{y} = \frac{\int y_c dA}{A}$   $\bar{z} = \frac{\int z_c dA}{A}$   
 $y_c = y$ 



$$[A\overline{y} = \int y_c \, dA] \qquad \qquad \frac{bh}{2} \, \overline{y} = \int_0^h y \, \frac{b(h - y)}{h} \, dy = \frac{bh^2}{6}$$
  
and 
$$\overline{y} = \frac{h}{3}$$

#### **Composite Bodies and Figures**

Divide bodies or figures into several parts such that their mass centers can be conveniently determined → Use Principle of Moment for all finite elements of the body



$$(m_1 + m_2 + m_3)\overline{X} = m_1\overline{x}_1 + m_2\overline{x}_2 + m_3\overline{x}_3$$

Mass Center Coordinates can be written as:

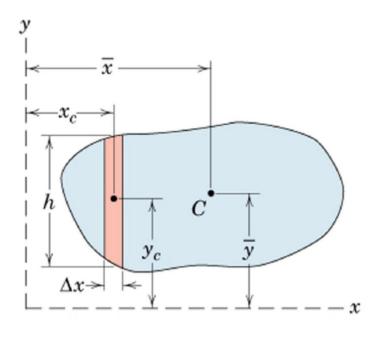
$$\overline{X} = \frac{\sum m\overline{x}}{\sum m} \quad \overline{Y} = \frac{\sum m\overline{y}}{\sum m} \quad \overline{Z} = \frac{\sum m\overline{z}}{\sum m}$$

*m*'s can be replaced by *L*'s, *A*'s, and *V*'s for lines, areas, and volumes

### Centroid of Composite Body/Figure

#### Irregular area :: Integration vs Approximate Summation

- Area/volume boundary cannot be expressed analytically
- Approximate summation instead of integration



Divide the area into several strips Area of each strip =  $h\Delta x$ Moment of this area about x- and y-axis =  $(h\Delta x)y_c$  and  $(h\Delta x)x_c$   $\rightarrow$  Sum of moments for all strips divided by the total area will give corresponding coordinate of the centroid

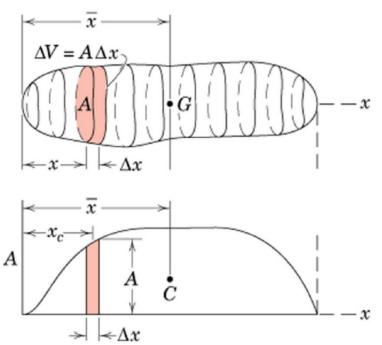
$$\bar{x} = \frac{\sum A x_c}{\sum A} \quad \bar{y} = \frac{\sum A y_c}{\sum A}$$

Accuracy may be improved by reducing the thickness of the strip

### Centroid of Composite Body/Figure

Irregular volume :: Integration vs Approximate Summation

- Reduce the problem to one of locating the centroid of area
- Approximate summation instead of integration



Divide the area into several strips Volume of each strip =  $A\Delta x$ Plot all such A against x.

 x → Area under the plotted curve represents volume of whole body and the x-coordinate of the centroid of the area under the curve is given by:

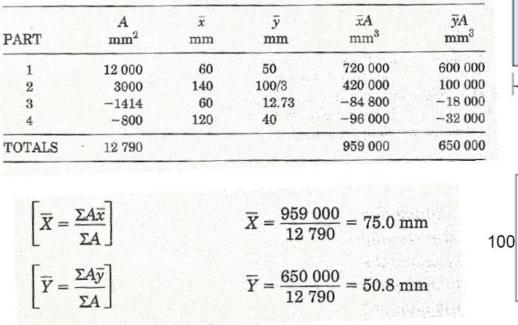
$$\bar{x} = \frac{\sum (A\Delta x) x_c}{\sum A\Delta x} \Longrightarrow \bar{x} = \frac{\sum V x_c}{\sum V}$$

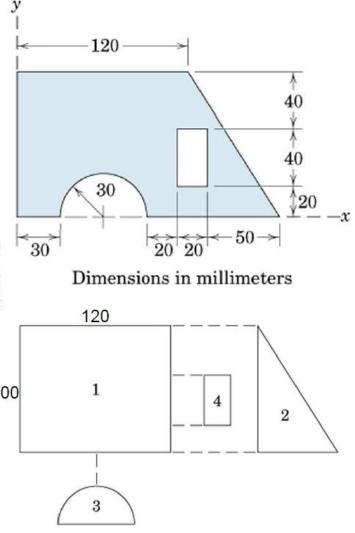
Accuracy may be improved by reducing the width of the strip

#### Example on Centroid of Composite Figure

Locate the centroid of the shaded area

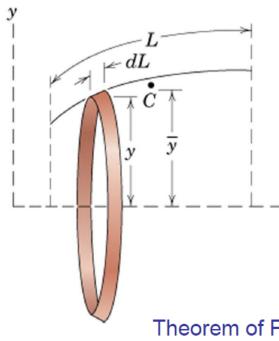
Solution: Divide the area into four elementary shapes: Total Area =  $A_1 + A_2 - A_3 - A_4$ 





#### Theorem of Pappus: Area of Revolution

- method for calculating surface area generated by revolving a plane curve about a non-intersecting axis in the plane of the curve



#### Surface Area

Area of the ring element: circumference times dL $dA = 2\pi y dL$ 

Total area,  $A = 2\pi \int y dL$ 

If area is revolved through an angle  $\theta < 2\pi$  $\theta$  in radians

$$\because \bar{y}L = \int y \, dL \quad \Rightarrow \quad A = 2\pi \, \bar{y}L$$

or  $A = \theta \bar{y}L$ 

 $\overline{y}$  is the y-coordinate of the centroid C for the line of length L

Generated area is the same as the lateral area of a right circular cylinder of length L and radius  $\overline{y}$ 

Theorem of Pappus can also be used to determine centroid of plane curves if area created by revolving these figures @ a non-intersecting axis is known