## Logic and Computer Design Fundamentals

## Chapter 7 - Registers and Register Transfers

Part 2 - Counters, Register Cells, Buses, \& Serial Operations

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## Overview

- Part 1 - Registers, Microoperations and Implementations
- Part 2 - Counters, register cells, buses, \& serial operations
- Microoperations on single register (continued)
- Counters
- Register cell design
- Multiplexer and bus-based transfers for multiple registers
- Serial transfers and microoperations
- Part 3 - Control of Register Transfers


## Counters

- Counters are sequential circuits which 'count" through a specific state sequence. They can count up, count down, or count through other fixed sequences. Two distinct types are in common usage:


## 1. Ripple Counters

- Clock connected to the flip-flop clock input on the LSB bit flip-flop
- For all other bits, a flip-flop output is connected to the clock input, thus circuit is not truly synchronous!
- Output change is delayed more for each bit toward the MSB.
- Resurgent because of low power consumption

2. Synchronous Counters

- Clock is directly connected to the flip-flop clock inputs
- Logic is used to implement the desired state sequencing


## Ripple Counter

- How does it work?
- When there is a positive edge on the clock input of A, A complements
- The clock input for flipflop $B$ is the complemented output of flip-flop $A$

- When flip A changes from 1 to 0 , there is a positive edge on the clock input of $\mathbf{B}$ causing $B$ to complement


Chapter 7-Part 24

## 4-Bit Ripple Counter



## 4-Bit Ripple Counter



## 4-Bit Ripple Counter



## Ripple Counter (continued)

- The arrows show the cause-effect relation- CP ship from the prior slide =>
- The corresponding sequence of states $=>$
 $(\mathbf{B}, \mathbf{A})=(\mathbf{0 , 0}),(0,1),(\mathbf{1 , 0}),(\mathbf{1}, 1),(0,0),(0,1), \ldots$
- Each additional bit, C, D, ...behaves like bit B, changing half as frequently as the bit before it.
- For 3 bits: $(\mathbf{C}, \mathbf{B}, \mathbf{A})=(\mathbf{0 , 0 , 0}),(\mathbf{0}, \mathbf{0}, \mathbf{1}),(\mathbf{0}, \mathbf{1 , 0}),(\mathbf{0}, 1,1)$, $(\mathbf{1 , 0 , 0}),(1,0,1),(1,1,0),(1,1,1),(0,0,0), \ldots$


## Ripple Counter (continued)

- These circuits are called ripple counters because each edge sensitive transition (positive in the example) causes a change in the next flipflop's state.
- The changes "ripple" upward through the chain of flip-flops, i. e., each transition occurs after a clock-to-output delay from the stage before.


## Ripple Counter (continued)

- Starting with $\mathrm{C}=\mathrm{B}=\mathrm{A}=1$, equivalent to $(C, B, A)=7$ base 10, the next clock increments the count to $(\mathbf{C}, \mathrm{B}, \mathrm{A})=\mathbf{0}$ base 10. In fine timing detail:
- The clock to output delay $\mathrm{t}_{\text {PHL }}$ causes an increasing delay from clock edge for each stage transition.
- Thus, the count "ripples" from least to most significant bit.
- For $n$ bits, total worst case ${ }^{c}$
 delay is $\boldsymbol{n} \mathrm{t}_{\text {PHL }}$.


## Synchronous Counters

- To eliminate the "ripple" effects, use a common clock for each flip-flop and a combinational circuit to generate the next state.
- For an up-counter, use an incrementer.



## Synchronous Counters (continued)

- Internal details => Incrementer
- Internal Logic
- XOR complements each bit
- AND chain causes complement of a bit if all bits toward LSB from it equal 1
- Count Enable
- Forces all outputs of AND chain to 0 to "hold" the state
- Carry Out
- Added as part of incrementer
- Connect to Count Enable of additional 4-bit counters to form larger counters

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(a) Loaic Diagram-Serial Gating

Chapter 7 - Part 212

## Synchronous Counters



## Synchronous Counters (continued)

- Carry chain
- series of AND gates through which the carry "ripples"
- Yields long path delays
- Called serial gating
- Replace AND carry chain with ANDs => in parallel
- Reduces path delays
- Called parallel gating
- Like carry lookahead
- Lookahead can be used on COs and ENs to prevent long paths in large counters
- Symbol for Synchronous Counter


Symbol


## Other Counters

- See text for:
- Down Counter - counts downward instead of upward
- Up-Down Counter - counts up or down depending on value a control input such as Up/Down
- Parallel Load Counter - Has parallel load of values available depending on control input such as Load
- Divide-by-n (Modulo n) Counter
- Count is remainder of division by $n$; $n$ may not be a power of 2 or
- Count is arbitrary sequence of $\boldsymbol{n}$ states specifically designed state-by-state
- Includes modulo 10 which is the BCD counter


## Counter with Parallel Load

- Add path for input data
- enabled for Load = 1
- Add logic to:
- disable count logic for Load = 1
- disable feedback from outputs for Load = 1
- enable count logic for Load = 0 and Count = 1
- The resulting function table:

| Load | Count | Action |
| :---: | :---: | :--- |
| 0 | 0 | Hold Stored Value |
| 0 | 1 | Count Up Stored Value |
| 1 | $X$ | Load D |

## Counter with Parallel Load

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| 1 | $X$ | Load D |



## Design Example: Synchronous BCD

- Use the sequential logic model to design a synchronous BCD counter with D flip-flops
- State Table =>
- Input combinations 1010 through 1111 are don't cares

| Current State Q8 Q4 Q2 Q1 |  |  |  | $\begin{gathered} \text { Next State } \\ \text { Q8 Q4 Q2 Q1 } \end{gathered}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 | 1 | 1 |
|  | 0 | 1 | 1 | 0 | 1 | 0 | 0 |
| 0 | 1 | 0 | 0 |  | 1 | 0 | 1 |
|  | 1 | 0 | 1 | 0 | 1 | 1 | 0 |
|  | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
|  | 1 | 1 | 1 | 1 | 0 | 0 | 0 |
| 1 | 0 | 0 |  | 1 | 0 | 0 | 1 |
|  | 0 | 0 |  | 0 | 0 | 0 | 0 |

## Synchronous BCD (continued)

| Current State Q8 Q4 Q2 Q1 | $\begin{aligned} & \text { Next State } \\ & \text { Q8 Q4 Q2 Q1 } \end{aligned}$ |
| :---: | :---: |
| 0 0 0 0 | 0 0 001 |
| $\begin{array}{llll}0 & 0 & 0 & 1\end{array}$ | $0 \begin{array}{llll}0 & 0 & 1 & 0\end{array}$ |
| 0 0 01110 | $\begin{array}{lllll}0 & 0 & 1 & 1\end{array}$ |
| $\begin{array}{lllll}0 & 0 & 1 & 1\end{array}$ | 0 O |
| $\begin{array}{lllll}0 & 1 & 0 & 0\end{array}$ | $\begin{array}{lllll}0 & 1 & 0 & 1\end{array}$ |
| $\begin{array}{lllll}0 & 1 & 0 & 1\end{array}$ | $\begin{array}{lllll}0 & 1 & 1 & 0\end{array}$ |
| $\begin{array}{lllll}0 & 1 & 1 & 0\end{array}$ | $\begin{array}{lllll}0 & 1 & 1 & 1\end{array}$ |
| $\begin{array}{lllll}0 & 1 & 1 & 1\end{array}$ | 10000 |
| 10000 | $\begin{array}{llll}1 & 0 & 0 & 1\end{array}$ |
| $\begin{array}{llll}1 & 0 & 0 & 1\end{array}$ | $\begin{array}{llll}0 & 0 & 0 & 0\end{array}$ |
| Present State | Next State |
| Q8 Q4 Q2 Q1 | Q8 Q4 Q2 Q1 |
| 10010 | $\begin{array}{lllll}1 & 0 & 1 & 1\end{array}$ |
| $\begin{array}{llll}1 & 0 & 1 & 1\end{array}$ | $\begin{array}{lllll}0 & 1 & 1 & 0\end{array}$ |
| $1 \begin{array}{llll}1 & 1 & 0 & 0\end{array}$ | $1 \begin{array}{llll}1 & 1 & 0 & 1\end{array}$ |
| $\begin{array}{llll}1 & 1 & 0 & 1\end{array}$ | $\begin{array}{llll}0 & 1 & 0 & 0\end{array}$ |
| 11110 | $1 \begin{array}{llll}1 & 1 & 1 & 1\end{array}$ |
| $1 \begin{array}{llll}1 & 1 & 1 & 1\end{array}$ | $\begin{array}{llll}0 & 0 & 1 & 0\end{array}$ |

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## Synchronous BCD (continued)

- Use K-Maps to two-level optimize the next state equations and manipulate into forms containing XOR gates:

$$
\begin{aligned}
& \mathrm{D} 1=\overline{\mathrm{Q}_{1}} \\
& \mathrm{D} 2=\mathrm{Q}_{2} \oplus \mathrm{Q}_{1} \overline{\mathrm{Q}_{8}} \\
& \mathrm{D} 4=\mathrm{Q}_{4} \oplus \mathrm{Q}_{1} \mathrm{Q}_{2} \\
& \mathrm{D} 8=\mathrm{Q}_{8} \oplus\left(\mathrm{Q}_{1} \mathrm{Q}_{8}+\mathrm{Q}_{1} \mathrm{Q}_{2} \mathrm{Q}_{4}\right)
\end{aligned}
$$

- The logic diagram can be draw from these equations
- An asynchronous or synchronous reset should be added
- What happens if the counter is perturbed by a power disturbance or other interference and it enters a state other than 0000 through 1001?


## Synchronous BCD (continued)

- Find the actual values of the six next states for the don't care combinations from the equations
- Find the overall state diagram to assess behavior for the don't care states (states in decimal)

| Present State |  |  |  | Next State |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Q8 Q4 Q2 Q1 |  |  |  | Q8 Q4 Q2 Q1 |  |  |  |
| 1 | 0 | 1 |  | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 |  | 0 | 1 | 1 | 0 |
| 1 | 1 | 0 |  | 1 | 1 | 0 | 1 |
| 1 | 1 | 0 |  | 0 | 1 | 0 | 0 |
| 1 | 1 | 1 |  | 1 | 1 | 1 | 1 |
| 1 | 1 | 1 |  | 0 | 0 | 1 |  |

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## Synchronous BCD (Another Solution)



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Chapter 7 -Part 222

## Synchronous BCD (Another Solution)

|  |  |  |  | Next State |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\frac{\text { Present State }}{\text { Q8 Q4 Q2 Q1 }}$ |  |  |  | Q8 Q4 Q2 Q1 |  |  |  |
| 1 | 0 | 1 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 |
| 1 | 1 | 0 | 0 | 1 | 1 | 0 | 1 |
| 1 | 1 | 0 | 1 | 0 | 1 | 0 | 0 |
| 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 |
| 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 |



## Synchronous BCD (continued)

- For the BCD counter design, if an invalid state is entered, return to a valid state occurs within two clock cycles
- Is this adequate? If not:
- Is a signal needed that indicates that an invalid state has been entered? What is the equation for such a signal?
- Does the design need to be modified to return from an invalid state to a valid state in one clock cycle?
- Does the design need to be modified to return from a invalid state to a specific state (such as 0)?
- The action to be taken depends on:
- the application of the circuit
- design group policy


## Counting Modulo N

- The following techniques use an $n$-bit binary counter with asynchronous or synchronous clear and/or parallel load:
- Detect a terminal count of N in a Modulo-N count sequence to asynchronously Clear the count to 0 or asynchronously Load in value 0 (These lead to counts which are present for only a very short time and can fail to work for some timing conditions!)
- Detect a terminal count of $\mathbf{N - 1}$ in a Modulo-N count sequence to Clear the count synchronously to 0
- Detect a terminal count of N-1 in a Modulo-N count sequence to synchronously Load in value 0
- Detect a terminal count and use Load to preset a count of the terminal count value minus ( $\mathbf{N}-1$ )
- Alternatively, custom design a modulo $\mathbf{N}$ counter as done for BCD


## Counting Modulo 7: Detect 7 and Asynchronously Clear

- A synchronous 4-bit binary counter with an asynchronous Clear is used to make a Modulo 7 counter.
- Use the Clear feature to detect the count 7 and clear the count to 0 . This gives a count of $0,1,2,3,4$, 5, 6, 7 (short) $0,1,2,3,4,5$, 6, 7(short)0, etc.
- DON'T DO THIS! Existence of state 7 may not be long enough to reliably reset all flip-flops to 0 . Referred to as a "suicide" counter! (Count " 7 " is "killed," but the designer's job may be dead as well!)


## Counting Modulo 7: Synchronously Load on Terminal Count of 6

- A synchronous 4-bit binary counter with a synchronous load and an asynchronous clear is used to make a Modulo 7 counter
- Use the Load feature to detect the count " 6 " and load in "zero". This gives a count of $0,1,2,3,4,5,6$, $0,1,2,3,4,5,6,0, \ldots$
- Using don't cares for states above 0110 , detection of 6 can be done with Load = Q4 Q2


## Counting Modulo 7: Synchronously Load on Terminal Count of 6




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## Counting Modulo 9: Synchronously Load on Terminal Count of 8



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## Counting Modulo 6: Synchronously Preset 9 on Reset and Load 9 on Terminal Count 14

- A synchronous, 4-bit binary counter with a synchronous Load is to be used to make a Modulo 6 counter.
- Use the Load feature to preset the count to 9 on Reset and detection of count 14.

- This gives a count of $\mathbf{9}, 10,11,12,13,14,9,10,11,12$, 13, 14, 9, ...
- If the terminal count is $\mathbf{1 5}$ detection is usually built in as Carry Out (CO)


## Register Cell Design

- Assume that a register consists of identical cells
- Then register design can be approached as follows:
- Design representative cell for the register
- Connect copies of the cell together to form the register
- Applying appropriate "boundary conditions" to cells that need to be different and contract if appropriate
- Register cell design is the first step of the above process


## Register Cell Specifications

- A register
- Data inputs to the register
- Control input combinations to the register
- Example 1: Not encoded
- Control inputs: Load, Shift, Add
- At most, one of Load, Shift, Add is $\mathbf{1}$ for any clock cycle $(\mathbf{0}, \mathbf{0}, \mathbf{0}),(\mathbf{1 , 0 , 0}),(\mathbf{0}, 1,0),(\mathbf{0}, 0,1)$
- Example 2: Encoded
- Control inputs: S1, S0
- All possible binary combinations on S1, S0 $(0,0),(0,1),(1,0),(1,1)$


## Register Cell Specifications

- A set of register functions (typically specified as register transfers)
- Example:

$$
\begin{aligned}
& \text { Load: } \mathbf{A} \leftarrow \mathbf{B} \\
& \text { Shift: } \mathbf{A} \leftarrow \mathrm{sr} \mathbf{B} \\
& \text { Add: } \quad \mathbf{A} \leftarrow \mathbf{A}+\mathbf{B}
\end{aligned}
$$

- A hold state specification
- Example:
- Control inputs: Load, Shift, Add
- If all control inputs are $\mathbf{0}$, hold the current register state


## Example 1: Register Cell Design

- Register A (m-bits) Specification:
- Data input: B
- Control inputs (CX, CY)
- Control input combinations (0,0), (0,1) (1,0)
- Register transfers:
- CX: A $\leftarrow \mathbf{B} \vee \mathrm{A}$
- CY:A $\leftarrow \mathbf{B} \oplus \mathbf{A}$
- Hold state: (0,0)


## Example 1: Register Cell Design (continued)

- Load Control

Load = CX + CY

- All control combinations appear as if encoded (0,0), (0,1), (1,0).
$\mathrm{S}=\mathrm{CX}$
$\mathrm{A}_{\mathrm{i}} \leftarrow \mathrm{B}_{\mathrm{i}} \oplus \mathrm{A}_{\mathrm{i}}$
$\mathrm{CY}=1$
$A_{i} \leftarrow B_{i} \vee A_{i}$
CX $=1$



## Sequential Circuit Design Approach

- Find a state diagram or state table
- Note that there are only two states with the state assignment equal to the register cell output value
- Use the design procedure in Chapter 5 to complete the cell design
- For optimization:
- Use K-maps for up to 4 to 6 variables
- Otherwise, use computer-aided or manual optimization


## Example 1 Again

- State Table:

|  | Hold | Ai v Bi |  | $\mathrm{Ai} \oplus \mathrm{Bi}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | CX $=0$ | CX $=1$ | CX $=1$ | $\mathrm{CY}=1$ | $\mathrm{CY}=1$ |
| $\mathbf{A}_{\mathbf{i}}$ | $\mathbf{C Y}=0$ | $\mathrm{B}_{\mathrm{i}}=0$ | $\mathrm{B}_{\mathrm{i}}=1$ | $B_{i}=0$ | $\mathrm{B}_{\mathrm{i}}=1$ |
| 0 | 0 | 0 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 | 1 | 0 |

- Four variables give a total of 16 state table entries
- By using:
- Combinations of variable names and values
- Don't care conditions (for CX=CY=1)
only 8 entries are required to represent the 16 entries


## Example 1 Again (continued)

- K-map - Use variable ordering CX, CY, $\mathrm{A}_{\mathrm{i}} \mathrm{B}_{\mathrm{i}}$ and assume a D flip-flop

| CX | CY | $\mathrm{A}_{\mathrm{i}}$ | $\mathrm{B}_{\mathrm{i}}$ | $\mathrm{D}_{\mathrm{i}}$ | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | 0 | HOLD |
| 0 | 0 | 0 | 1 | 0 |  |
| 0 | 0 | 1 | 0 | 1 |  |
| 0 | 0 | 1 | 1 | 1 |  |
| 0 | 1 | 0 | 0 | 0 | $\mathbf{C Y}: \mathbf{A} \leftarrow \mathrm{B} \oplus \mathrm{A}$ |
| 0 | 1 | 0 | 1 | 1 |  |
| 0 | 1 | 1 | 0 | 1 |  |
| 0 | 1 | 1 | 1 | 0 |  |
| 1 | 0 | 0 | 0 | 0 | $\mathbf{C X}: \mathbf{A} \leftarrow \mathrm{B}^{\text {v A }}$ |
| 1 | 0 | 0 | 1 | 1 |  |
| 1 | 0 | 1 | 0 | 1 |  |
| 1 | 0 | 1 | 1 | 1 |  |
| 1 | 1 | 0 | 0 | X | No Action |
| 1 | 1 | 0 | 1 | X |  |
| 1 | 1 | 1 | 0 | X |  |
| 1 | 1 | 1 | 1 | X |  |



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## Example 1 Again (continued)

- The resulting SOP equation:

$$
D_{i}=\mathbf{C X} B_{i}+C Y \bar{A}_{i} B_{i}+A_{i} \bar{B}_{i}+\overline{\mathbf{C Y}} A_{i}
$$

- Using factoring and DeMorgan's law:

$$
\begin{aligned}
& \mathbf{D}_{i}=\mathbf{C X} B_{i}+\bar{A}_{i}\left(\mathbf{C Y} B_{i}\right)+A_{i}\left(\overline{C Y B}_{i}\right) \\
& D_{i}=\mathbf{C X B} B_{i}+A_{i} \oplus\left(\mathbf{C Y} B_{i}\right)
\end{aligned}
$$

The gate input cost per cell $=2+8+2+2=14$

- The gate input cost per cell for the previous version is:

Per cell: 19
Shared decoder logic: 8

- Cost gain by sequential design > 5 per cell
- Also, no Enable on the flip-flop makes it cost less


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