

Chapter 5: Basis of a vector space

Def: Let V be a vector space and

$S = \{v_1, \dots, v_n\}$ be a set of vectors in V . Then S is called a basis of V if and only if

- 1- S spans V , i.e., every vector of V can be written as a linear combination of the vectors in S .
- 2- S is linear independent.

Some properties:

- 1- if $S = \{v_1, \dots, v_n\}$ is a basis of V then every vector of V can be written as a linear combination of the vectors in S in **(unique method)**.

- 2- Let $S = \{e_1, \dots, e_n\}$ be a set of the following vectors in \mathbb{R}^n :

$$e_1 = (1, 0, \dots, 0), \dots, e_k = (0, \dots, 0, 1, 0, \dots, 0), \dots, e_n = (0, \dots, 0, 1).$$

Then S is a basis of \mathbb{R}^n which is called natural basis of \mathbb{R}^n .

Ex: Prove the set of vectors $S = \{1, X, \dots, X^n\}$ is a basis of \mathcal{P}_n ?

Example: Let $v_3 = (1, 1, \lambda)$ and $v_2 = (1, \lambda, 1)$, $v_1 = (\lambda, 1, 1)$ be vectors in \mathbb{R}^3 . Find the value of $\lambda \in \mathbb{R}$ that makes $\{v_1, v_2, v_3\}$ be a basis of \mathbb{R}^3 ?

Solution: The set $\{v_1, v_2, v_3\}$ should be a linear independent, i.e., the equation

$$xv_1 + yv_2 + zv_3 = 0 \quad \text{has a unique solution } x=y=z=0. \text{ So,}$$

$$A = \begin{pmatrix} \lambda & 1 & 1 \\ 1 & \lambda & 1 \\ 1 & 1 & \lambda \end{pmatrix} \quad \text{has an inverse, i.e., } |A| \text{ is not equal to zero.}$$

After calculation, $\lambda \notin \{-2, 1\}$.

As $|A|$ is not equal to zero, the system to prove the linear combination will be with unique solution.

REMARK:

Notice that the basis of a vector space is not necessarily to be unique.

Some properties:

- 1- Let S be a basis of a vector space where $S = \{v_1, \dots, v_n\}$. If $T = \{u_1, \dots, u_m\}$ is a set of vectors in V where $m > n$, i.e., $|T| > |S|$ then T is linear dependent.
- 2- If S and T are two basis of a vector space V then $|S| = |T|$.

Definition: Dimension of a vector space V , $\text{Dim}(V)$, is equal to $|S|$ where S is a basis of V .

For example:

- 1- $\text{Dim}(\mathbb{R}^n) = n$
- 2- $\text{Dim}(\mathcal{P}_n) = n+1$

Remark: if V is a vector space where $\text{Dim}(V) = n$ then to prove the set of vectors $S = \{v_1, \dots, v_n\}$ in V is a basis, it is enough to prove that S is a linear independent or it is a spanning set of V .

** How to find the dimension of a subspace $\text{Span}(S)$ where S is the set of Vectors in a vector space V ?

We will do the following steps:

Step 1: Let A be the matrix where every vector in S is a column in A .

Step 2: Eliminate the matrix A .

Step 3: the vector which meet the columns with the 1 leader will be the basis of $\text{Span}(S)$.

Theorem:

- 1- If V is a vector space and S is a spanning set of V then S contains T where T is a basis of V .
- 2- If S is a linear independent set in a vector space V then there is a basis T of V where T contains S .

Example: Let $W = \text{Span}(S)$ be a subspace of \mathbb{R}^5 , where $S = \{v_1, v_2, v_3, v_4\}$, where

$$v_3 = (1, 2, -1, 2, 0), v_2 = (2, 0, 4, -2, 4), v_1 = (1, 0, 2, -1, 2) \\ v_4 = (1, 4, -4, 5, -2)$$

- a- Find a basis of W ?
- b- Find a basis of V contains $\{v_1, v_3\}$?

Answer:

- a- Firstly, we will construct A as follows:

$$A = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 2 & 4 \\ 2 & 4 & -1 & -4 \\ -1 & -2 & 2 & 5 \\ 2 & 4 & 0 & -2 \end{pmatrix}$$

After elimination, we get

$$\begin{pmatrix} 1 & 2 & 0 & -1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

So, the basis of Span(S) is {V1, V3}

b- The basis T of \mathbb{R}^5 that contains {V1, V3} is $\{v_1, v_3, e_1, e_2, e_3\}$

Where $e_3 = (0, 0, 1, 0, 0)$, $e_2 = (0, 1, 0, 0, 0)$, $e_1 = (1, 0, 0, 0, 0)$

Question from previous exam:

Let $W = \{(x, y, z, t) \in \mathbb{R}^4; 2x + y + z = 0, x - y + z = 0\}$

- 1- Prove that W is a subspace of \mathbb{R}^4 .
- 2- Find a basis of W?

Answer: 1- you can answer by regular method through satisfying the two conditions of subspace. Another method can be done as follows:

W is the set of solutions of the system $2x+y+z=0$ and $x-y+z=0$. The system is homogenous $AX=0$. Therefore, the set of answers is subspace.

2- we have $(x,y,z,t) = (x,y,z,0) + (0, 0, 0, t) \dots \dots (\#)$

$(0,0,0,t) = t(0,0,0,1) \dots \dots \dots (*)$

$(x,y,z,0)$ are solutions to the system $2x+y+z=0$ and $x-y+z=0$

$$\begin{cases} 2x + y + z = 0 \\ x - y + z = 0 \end{cases} \iff \begin{cases} x = -2y \\ z = 3y \end{cases}$$

So, the solution will be written by parameter y

$$y \begin{pmatrix} -2 \\ 1 \\ 3 \\ 0 \end{pmatrix} \dots \dots \dots (**)$$

Hence by (#), (*) and (**), W is generated by

$$\left\{ \begin{pmatrix} -2 \\ 1 \\ 3 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\} \text{ which is the basis of } W.$$

Question :

Let $V = \mathbb{R}^3$. Give example on

1- Linear independent set which is not a basis?

2- Spanning set of V which is not a basis?

Answer:

1- we can take $S = \{(1,0,0)\}$. $|S| = 1$ which is not equal $\text{Dim}(V = \mathbb{R}^3) = 3$. So it is not a basis.

If $a(1,0,0) = (0,0,0)$ then $(a,0,0) = (0,0,0)$. Therefore, $a=0$. Hence S is linear independent.

2- Let $T = \{(1,0,0), (0,1,0), (0,0,1), (1,1,1)\}$

If (a,b,c) is a vector then

$$(a,b,c) = a(1,0,0) + b(0,1,0) + c(0,0,1) + 0(1,1,1)$$

So, T spans $V = \mathbb{R}^3$ but $|T| > \text{Dim}(V = \mathbb{R}^3)$. Hence, T is not a basis.

** Change of a basis:

Definition: Let $S = \{v_1, \dots, v_n\}$ be a basis of a vector space V and $v \in V$, where

$v = x_1 v_1 + \dots + x_n v_n$. Then (x_1, \dots, x_n) is called the coordinate of v related to the basis S .

We write

$$[v]_S = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

to denote the coordinate vector of v related to S .

Theorem:

Let V be a vector space which has two basis

$$C = \{u_1, \dots, u_n\} \text{ and } B = \{v_1, \dots, v_n\}$$

Then the matrix ${}^C P_B$ is a matrix with column

$[v_1]_C, \dots, [v_n]_C$. The matrix ${}^C P_B$ is called the transition matrix from the basis B into the basis C . This matrix has an inverse and for every vector v in V , we have

$$[v]_C = {}^C P_B [v]_B$$

Practise:

Suppose that \mathbb{R}^3 has two basis

$$B = \{v_1 = (0, 1, 1), v_2 = (1, 0, -2), v_3 = (1, 1, 0)\}$$

$$\text{And } C = \{u_1 = (1, 0, 0), u_2 = (0, 1, 0), u_3 = (0, 0, 1)\}$$

1- Find ${}^B P_C$ and ${}^C P_B$.

2- If

$$[v]_C = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \text{ find } [v]_B ?$$

Solution:

$${}_B P_C = \begin{pmatrix} -2 & 2 & -1 \\ -1 & 1 & -1 \\ 2 & -1 & 1 \end{pmatrix} \quad {}_C P_B = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & -2 & 0 \end{pmatrix} \quad \mathbf{1}$$

$$[v]_B = {}_B P_C [v]_C = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad \mathbf{2}$$

(Try to write the full answer for the above answer)

Question from one of previous exams:

In \mathbb{R}^3 , prove that $w = (-2, 1, -2)$, $v = (-1, -1, 2)$, $u = (1, 0, 1)$ is a basis of \mathbb{R}^3 , and then find the coordinate vector of (x,y,z) related to such basis:

Answer:

As $\text{Dim}(\mathbb{R}^3)=3$, it is enough to show that w,v,u spans \mathbb{R}^3 . Suppose for any vector (x,y,z) , the equation

$(x,y,z)= au+bv+cw$. The coefficients matrix of such system is

$$A = \begin{pmatrix} 1 & -1 & -2 \\ 0 & -1 & 1 \\ 1 & 2 & -2 \end{pmatrix}$$

$$|A| = -3$$

So, the system has a unique solution

$$\underline{\underline{\begin{pmatrix} a \\ b \\ c \end{pmatrix} = A^{-1} X = \begin{pmatrix} 2y + z \\ \frac{-x+z}{3} \\ \frac{-x+3y+z}{3} \end{pmatrix}}}$$

EX) Prove that $S = \{(1, 1, 1), (-1, 1, 0), (1, 0, -1)\}$ is a basis of \mathbb{R}^3 and find the coordinate vectors of $(0, 0, 1)$ and $(1, 0, 1), (1, 0, 0)$ which is related to S.

Answer: As $\text{Dim}(\mathbb{R}^3) = 3$, it is enough to show that w, v, u spans \mathbb{R}^3 . So, it is enough to show that S is a spanning set of \mathbb{R}^3 . After doing the equation of linear combination for any vector in \mathbb{R}^3 , we get

$$\begin{vmatrix} 1 & -1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & -1 \end{vmatrix} = 3 \neq 0$$

So, there is a unique solution to the system that was induced from the equation of linear combination.

To find the coordinate vectors related to S,

It is easy to write $(1, 0, 0) = \frac{1}{3}(1, 1, 1) - \frac{1}{3}(-1, 1, 0) + \frac{1}{3}(1, 0, -1)$

So, the coordinate vector is $(\frac{1}{3}, -\frac{1}{3}, \frac{1}{3})$.

Similarly,

$$(0, 0, 1) = \frac{1}{3}(1, 1, 1) - \frac{1}{3}(-1, 1, 0) - \frac{2}{3}(1, 0, -1)$$

So, the coordinate vector is $(\frac{1}{3}, -\frac{1}{3}, -\frac{2}{3})$.

** Row and Column spaces:

Let A be a matrix of size $n \times m$.

1- Row(A) is the subspace generated by rows of A (notice that every row will be considered a vector)

2- Col(A) is the subspace generated by column of A (notice that every column will be considered a vector)

Properties:

1- Let A be a matrix. If B is a matrix induced from doing some elementary row operations then

$$\text{Row}(A) = \text{Row}(B)$$

2- Let A be a matrix. After elimination, the non-zero rows are linear independent.

(Do not forget that any set of vectors contains zero vector is linear dependent.... Why?)

Definition : Let A be a matrix. The rank of A, $\text{rank}(A) = \text{Dim}(\text{Row}(A))$

Definition: Order of matrix A= the number of non zero rows (After elimination)

Rules: for any matrix A,

1- $\text{Rank}(A) = \text{Dim}(\text{Row}(A)) = \text{Dim}(\text{Col}(A))$.

2- $\text{Rank}(A) = \text{Rank}(\text{transpose}(A))$.

Theorem

Let A be a matrix of size $n \times m$. Then the following are equivalent

1- $AX=0$ has unique solution(zero solution)

2- The columns of A are independent

3- $\text{rank}(A)=n$ (number of rows)

4- $A^T A$ has an inverse.

Theorem

Let A be a matrix of size n X m. Then the following are equivalent

- 1- $AX=B$ is consistent
- 2- The columns of A are spanning set of \mathbb{R}^m
- 3- $\text{rank}(A)=m$ (number of column)
- 4- $A^T A$ has an inverse.

Definition :

Let A be a matrix of size n X m. Then

- 1- The subspace $W = \{X \in \mathbb{R}^n; AX = 0\}$ is called null subspace, $N(A)$, and $\text{Nullity}(A) = \text{Dim}(N(A))$.
- 2- $\text{Im}(A) = \{AX; X \in \mathbb{R}^n\}$.

Rules:

- 1- Let A be a matrix of size n X m. Then $\text{Im}(A)=\text{Col}(A)$
- 2- Let A be a matrix of size n X m. Then $\text{nullity}(A)+ \text{rank}(A)= n$ (number of rows).

Example: Let

$$A = \begin{pmatrix} 1 & 2 & -1 & -1 \\ 0 & -1 & 2 & 3 \\ 2 & 3 & 0 & 1 \\ 1 & 1 & 1 & 2 \end{pmatrix}$$

- 1- Find a basis of the null space, $N(A)$?
- 2- Find a basis of $\text{Col}(A)$?
- 3- find order of A?

Answer:

1- After Elimination, we get

$$\begin{pmatrix} 1 & 0 & 3 & 5 \\ 0 & 1 & -2 & -3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix},$$

So, the basis

$$\begin{pmatrix} -3 \\ -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 5 \\ 3 \\ 0 \\ 1 \end{pmatrix}$$

Non zero rows.

Basis of $N(A)$.

$$\begin{pmatrix} 1 \\ 0 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ -1 \\ 3 \\ 1 \end{pmatrix}$$

2- the basis of $\text{Col}(A)$ (The vectors the meet the column with leaders 1)

3- Order $A=2$