



2.2 Evaluating Determinants by Row Reduction

In this section we will show how to evaluate a determinant by reducing the associated matrix to row echelon form. In general, this method requires less computation than cofactor expansion and hence is the method of choice for large matrices.

We begin with a fundamental theorem that will lead us to an efficient procedure for evaluating the determinant of a square matrix of any size.

THEOREM 2.2.1 Let A be a square matrix. If A has a row of zeros or a column of zeros, then $\det(A) = 0$.

Proof Since the determinant of A can be found by a cofactor expansion along any row or column, we can use the row or column of zeros. Thus, if we let C_1, C_2, \dots, C_n denote the cofactors of A along that row or column, then it follows from Formula (7) or (8) in Section 2.1 that

$$\det(A) = 0 \cdot C_1 + 0 \cdot C_2 + \dots + 0 \cdot C_n = 0 \quad \blacktriangleleft$$

The following useful theorem relates the determinant of a matrix and the determinant of its transpose.

THEOREM 2.2.2 Let A be a square matrix. Then $\det(A) = \det(A^T)$.

Proof Since transposing a matrix changes its columns to rows and its rows to columns, the cofactor expansion of A along any row is the same as the cofactor expansion of A^T along the corresponding column. Thus, both have the same determinant. \blacktriangleleft

The next theorem shows how an elementary row operation on a square matrix affects the value of its determinant. In place of a formal proof we have provided a table to illustrate the ideas in the 3×3 case (see Table 1).

Table 1

Relationship	Operation
$\begin{vmatrix} ka_{11} & ka_{12} & ka_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = k \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$ $\det(B) = k \det(A)$	In the matrix B the first row of A was multiplied by k .
$\begin{vmatrix} a_{21} & a_{22} & a_{23} \\ a_{11} & a_{12} & a_{13} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = - \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$ $\det(B) = -\det(A)$	In the matrix B the first and second rows of A were interchanged.
$\begin{vmatrix} a_{11} + ka_{21} & a_{12} + ka_{22} & a_{13} + ka_{23} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$ $\det(B) = \det(A)$	In the matrix B a multiple of the second row of A was added to the first row.

- ① $k \dots$
- ② interchange *A Basic Theorem*
- ③ $kR_i + R_j$

Because transposing a matrix changes its columns to rows and its rows to columns, almost every theorem about the rows of a determinant has a companion version about columns, and vice versa.

Elementary Row Operations

The first panel of Table 1 shows that you can bring a common factor from any row (column) of a determinant through the determinant sign. This is a slightly different way of thinking about part (a) of Theorem 2.2.3.

THEOREM 2.2.3 Let A be an $n \times n$ matrix.

- (a) If B is the matrix that results when a single row or single column of A is multiplied by a scalar k , then $\det(B) = k \det(A)$.
- (b) If B is the matrix that results when two rows or two columns of A are interchanged, then $\det(B) = -\det(A)$.
- (c) If B is the matrix that results when a multiple of one row of A is added to another or when a multiple of one column is added to another, then $\det(B) = \det(A)$.

We will verify the first equation in Table 1 and leave the other two for you. To start, note that the determinants on the two sides of the equation differ only in the first row, so these determinants have the same cofactors, C_{11} , C_{12} , C_{13} , along that row (since those cofactors depend only on the entries in the *second* two rows). Thus, expanding the left side by cofactors along the first row yields

$$\begin{aligned} \begin{vmatrix} ka_{11} & ka_{12} & ka_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} &= ka_{11}C_{11} + ka_{12}C_{12} + ka_{13}C_{13} \\ &= k(a_{11}C_{11} + a_{12}C_{12} + a_{13}C_{13}) \\ &= k \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \end{aligned}$$

Elementary Matrices

It will be useful to consider the special case of Theorem 2.2.3 in which $A = I_n$ is the $n \times n$ identity matrix and E (rather than B) denotes the elementary matrix that results when the row operation is performed on I_n . In this special case Theorem 2.2.3 implies the following result.

THEOREM 2.2.4 Let E be an $n \times n$ elementary matrix.

- (a) If E results from multiplying a row of I_n by a nonzero number k , then $\det(E) = k$.
- (b) If E results from interchanging two rows of I_n , then $\det(E) = -1$.
- (c) If E results from adding a multiple of one row of I_n to another, then $\det(E) = 1$.



EXAMPLE 1 Determinants of Elementary Matrices

The following determinants of elementary matrices, which are evaluated by inspection, illustrate Theorem 2.2.4.

E_1

$$\begin{vmatrix} 1 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} = 3$$

The second row of I_4 was multiplied by 3.

E_2

$$\begin{vmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{vmatrix} = -1$$

The first and last rows of I_4 were interchanged.

E_3

$$\begin{vmatrix} 1 & 0 & 0 & 7 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} = 1$$

7 times the last row of I_4 was added to the first row.

Observe that the determinant of an elementary matrix cannot be zero.

Matrices with Proportional Rows or Columns

Handwritten notes: $3R_2$, $R_1 \leftrightarrow R_4$, $7R_4 + R_1$

If a square matrix A has two proportional rows, then a row of zeros can be introduced by adding a suitable multiple of one of the rows to the other. Similarly for columns. But adding a multiple of one row or column to another does not change the determinant, so from Theorem 2.2.1, we must have $\det(A) = 0$. This proves the following theorem.

THEOREM 2.2.5 If A is a square matrix with two proportional rows or two proportional columns, then $\det(A) = 0$.

EXAMPLE 2 Proportional Rows or Columns

Each of the following matrices has two proportional rows or columns; thus, each has a determinant of zero.

Evaluating Determinants by Row Reduction

We will now give a method for evaluating determinants that involves substantially less computation than cofactor expansion. The idea of the method is to reduce the given matrix to upper triangular form by elementary row operations, then compute the determinant of the upper triangular matrix (an easy computation), and then relate that determinant to that of the original matrix. Here is an example.

EXAMPLE 3 Using Row Reduction to Evaluate a Determinant

Evaluate $\det(A)$ where

$$A = \begin{bmatrix} 0 & 1 & 5 \\ 3 & -6 & 9 \\ 2 & 6 & 1 \end{bmatrix}$$

Solution We will reduce A to row echelon form (which is upper triangular) and then apply Theorem 2.1.2.

$$\begin{aligned} \det(A) &= \begin{vmatrix} 0 & 1 & 5 \\ 3 & -6 & 9 \\ 2 & 6 & 1 \end{vmatrix} = - \begin{vmatrix} 3 & -6 & 9 \\ 0 & 1 & 5 \\ 2 & 6 & 1 \end{vmatrix} && \leftarrow \text{The first and second rows of } A \text{ were interchanged.} \\ &= -3 \begin{vmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 2 & 6 & 1 \end{vmatrix} && \leftarrow \text{A common factor of 3 from the first row was taken through the determinant sign.} \\ &= -3 \begin{vmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 0 & 10 & -5 \end{vmatrix} && \leftarrow -2 \text{ times the first row was added to the third row.} \\ &= -3 \begin{vmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 0 & 0 & -55 \end{vmatrix} && \leftarrow -10 \text{ times the second row was added to the third row.} \\ &= (-3)(-55) \begin{vmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{vmatrix} && \leftarrow \text{A common factor of } -55 \text{ from the last row was taken through the determinant sign.} \\ &= (-3)(-55)(1) = 165 \end{aligned}$$

Even with today's fastest computers it would take millions of years to calculate a 25×25 determinant by cofactor expansion, so methods based on row reduction are often used for large determinants. For determinants of small size (such as those in this text), cofactor expansion is often a reasonable choice.



Example 3

$$A = \begin{bmatrix} 0 & 1 & 5 \\ 3 & -6 & 9 \\ 2 & 6 & 1 \end{bmatrix}$$

Row reduction

$R_1 \rightarrow$

$$\left| \begin{array}{ccc|c} 0 & 1 & 5 & \\ 3 & -6 & 9 & \\ 2 & 6 & 1 & \end{array} \right| \xrightarrow{R_1 \leftrightarrow R_2} \left| \begin{array}{ccc|c} 3 & -6 & 9 & \\ 0 & 1 & 5 & \\ 2 & 6 & 1 & \end{array} \right| = -3 \left| \begin{array}{ccc|c} 1 & -2 & 3 & \\ 0 & 1 & 5 & \\ 2 & 6 & 1 & \end{array} \right|$$

$$= -3 \left| \begin{array}{ccc|c} 1 & -2 & 3 & \\ 0 & 1 & 5 & \\ 0 & 10 & -5 & \end{array} \right| = -3 \left| \begin{array}{ccc|c} 1 & -2 & 3 & \\ 0 & 1 & 5 & \\ 0 & 0 & -55 & \end{array} \right|$$

$$= -3 \underline{(-55)} \left| \begin{array}{ccc|c} 1 & -2 & 3 & \\ 0 & 1 & 5 & \\ 0 & 0 & 1 & \end{array} \right|$$

$$= (-3)(-55)(1)(1)(1)$$

$$= \boxed{165}$$

EXAMPLE 4 Using Column Operations to Evaluate a Determinant

Compute the determinant of

$$A = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 2 & 7 & 0 & 6 \\ 0 & 6 & 3 & 0 \\ 7 & 3 & 1 & -5 \end{bmatrix}$$

Solution This determinant could be computed as above by using elementary row operations to reduce A to row echelon form, but we can put A in lower triangular form in one step by adding -3 times the first column to the fourth to obtain

$$\det(A) = \det \begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 7 & 0 & 0 \\ 0 & 6 & 3 & 0 \\ 7 & 3 & 1 & -26 \end{bmatrix} = (1)(7)(3)(-26) = -546$$

Example 4 points out that it is always wise to keep an eye open for column operations that can shorten computations.

Cofactor expansion and row or column operations can sometimes be used in combination to provide an effective method for evaluating determinants. The following example illustrates this idea.

EXAMPLE 5 Row Operations and Cofactor Expansion

Evaluate $\det(A)$ where

$$A = \begin{bmatrix} 3 & 5 & -2 & 6 \\ 1 & 2 & -1 & 1 \\ 2 & 4 & 1 & 5 \\ 3 & 7 & 5 & 3 \end{bmatrix}$$

Solution By adding suitable multiples of the second row to the remaining rows, we

obtain

$$\det A = - \begin{vmatrix} 1 & 2 & -1 & 1 \\ 3 & 5 & -2 & 6 \\ 2 & 4 & 1 & 5 \\ 3 & 7 & 5 & 3 \end{vmatrix}$$

$$= - \begin{vmatrix} 1 & 2 & -1 & 1 \\ 0 & -1 & 1 & 3 \\ 0 & 0 & 3 & 3 \\ 0 & 1 & 8 & 0 \end{vmatrix}$$

$$= -1 \begin{vmatrix} -1 & 1 & 3 \\ 0 & 3 & 3 \\ 1 & 8 & 0 \end{vmatrix}$$

$$= -1 \begin{vmatrix} -1 & 1 & 3 \\ 0 & 3 & 3 \\ 0 & 9 & 3 \end{vmatrix}$$

$$= -(-1) \begin{vmatrix} 3 & 3 \\ 9 & 3 \end{vmatrix} = -(-1)(9 - 27) = -(-1)(-18) = -18$$

Handwritten notes and diagrams: The first determinant has the first row circled in blue. The second determinant has the first column circled in blue. The third determinant has the first row circled in blue. The fourth determinant has the first row circled in blue. The final result -18 is circled in blue.

Example 4

$$A = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 2 & 7 & 0 & 6 \\ 0 & 6 & 3 & 0 \\ 7 & 3 & 1 & -5 \end{bmatrix}$$

could be computed as above by using

$$-3C_1 + C_4$$

$$\begin{aligned} (-3)(7) &= -21 \\ -21 - 5 &= -26 \end{aligned}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 7 & 0 & 0 \\ 0 & 6 & 3 & 0 \\ 7 & 3 & 1 & -26 \end{bmatrix}$$

$$\det(A) = (1)(7)(3)(-26) = -546$$

=



Exercise Set 2.2

► In Exercises 1–4, verify that $\det(A) = \det(A^T)$. ◀

1. $A = \begin{bmatrix} -2 & 3 \\ 1 & 4 \end{bmatrix}$

2. $A = \begin{bmatrix} -6 & 1 \\ 2 & -2 \end{bmatrix}$

3. $A = \begin{bmatrix} 2 & -1 & 3 \\ 1 & 2 & 4 \\ 5 & -3 & 6 \end{bmatrix}$

4. $A = \begin{bmatrix} 4 & 2 & -1 \\ 0 & 2 & -3 \\ -1 & 1 & 5 \end{bmatrix}$

► In Exercises 5–8, find the determinant of the given elementary matrix by inspection. ◀

5. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -5 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

6. $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -5 & 0 & 1 \end{bmatrix}$

7. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

8. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -\frac{1}{3} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

► In Exercises 9–14, evaluate the determinant of the matrix by first reducing the matrix to row echelon form and then using some combination of row operations and cofactor expansion. ◀

9. $\begin{bmatrix} 3 & -6 & 9 \\ -2 & 7 & -2 \\ 0 & 1 & 5 \end{bmatrix}$

10. $\begin{bmatrix} 3 & 6 & -9 \\ 0 & 0 & -2 \\ -2 & 1 & 5 \end{bmatrix}$

11. $\begin{bmatrix} 2 & 1 & 3 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 2 & 1 & 0 \\ 0 & 1 & 2 & 3 \end{bmatrix}$

12. $\begin{bmatrix} 1 & -3 & 0 \\ -2 & 4 & 1 \\ 5 & -2 & 2 \end{bmatrix}$

13. $\begin{bmatrix} 1 & 3 & 1 & 5 & 3 \\ -2 & -7 & 0 & -4 & 2 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}$

14. $\begin{bmatrix} 1 & -2 & 3 & 1 \\ 5 & -9 & 6 & 3 \\ -1 & 2 & -6 & -2 \\ 2 & 8 & 6 & 1 \end{bmatrix}$

► In Exercises 15–22, evaluate the determinant, given that

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = -6 \quad \blacktriangleleft$$

15. $\begin{vmatrix} d & e & f \\ g & h & i \\ a & b & c \end{vmatrix}$

16. $\begin{vmatrix} g & h & i \\ d & e & f \\ a & b & c \end{vmatrix}$

17. $\begin{vmatrix} 3a & 3b & 3c \\ -d & -e & -f \\ 4g & 4h & 4i \end{vmatrix}$

18. $\begin{vmatrix} a+d & b+e & c+f \\ -d & -e & -f \\ g & h & i \end{vmatrix}$

19. $\begin{vmatrix} a+g & b+h & c+i \\ d & e & f \\ g & h & i \end{vmatrix}$

20. $\begin{vmatrix} a & b & c \\ 2d & 2e & 2f \\ g+3a & h+3b & i+3c \end{vmatrix}$

21. $\begin{vmatrix} -3a & -3b & -3c \\ d & e & f \\ g-4d & h-4e & i-4f \end{vmatrix}$

22. $\begin{vmatrix} a & b & c \\ d & e & f \\ 2a & 2b & 2c \end{vmatrix}$

23. Use row reduction to show that

$$\begin{vmatrix} 1 & 1 & 1 \\ a & b & c \\ a^2 & b^2 & c^2 \end{vmatrix} = (b-a)(c-a)(c-b)$$

24. Verify the formulas in parts (a) and (b) and then make a conjecture about a general result of which these results are special cases.

(a) $\det \begin{bmatrix} 0 & 0 & a_{13} \\ 0 & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = -a_{13}a_{22}a_{31}$

(b) $\det \begin{bmatrix} 0 & 0 & 0 & a_{14} \\ 0 & 0 & a_{23} & a_{24} \\ 0 & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{bmatrix} = a_{14}a_{23}a_{32}a_{41}$

► In Exercises 25–28, confirm the identities without evaluating the determinants directly. ◀

25. $\begin{vmatrix} a_1 & b_1 & a_1 + b_1 + c_1 \\ a_2 & b_2 & a_2 + b_2 + c_2 \\ a_3 & b_3 & a_3 + b_3 + c_3 \end{vmatrix} = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$

26. $\begin{vmatrix} a_1 + b_1t & a_2 + b_2t & a_3 + b_3t \\ a_1t + b_1 & a_2t + b_2 & a_3t + b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = (1-t^2) \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$

27. $\begin{vmatrix} a_1 + b_1 & a_1 - b_1 & c_1 \\ a_2 + b_2 & a_2 - b_2 & c_2 \\ a_3 + b_3 & a_3 - b_3 & c_3 \end{vmatrix} = -2 \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$

28. $\begin{vmatrix} a_1 & b_1 + ta_1 & c_1 + rb_1 + sa_1 \\ a_2 & b_2 + ta_2 & c_2 + rb_2 + sa_2 \\ a_3 & b_3 + ta_3 & c_3 + rb_3 + sa_3 \end{vmatrix} = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$

► In Exercises 29–30, show that $\det(A) = 0$ without directly evaluating the determinant. ◀

$$29. A = \begin{bmatrix} -2 & 8 & 1 & 4 \\ 3 & 2 & 5 & 1 \\ 1 & 10 & 6 & 5 \\ 4 & -6 & 4 & -3 \end{bmatrix}$$

$$30. A = \begin{bmatrix} -4 & 1 & 1 & 1 & 1 \\ 1 & -4 & 1 & 1 & 1 \\ 1 & 1 & -4 & 1 & 1 \\ 1 & 1 & 1 & -4 & 1 \\ 1 & 1 & 1 & 1 & -4 \end{bmatrix}$$

► It can be proved that if a square matrix M is partitioned into **block triangular form** as

$$M = \begin{bmatrix} A & 0 \\ C & B \end{bmatrix} \quad \text{or} \quad M = \begin{bmatrix} A & C \\ 0 & B \end{bmatrix}$$

in which A and B are square, then $\det(M) = \det(A)\det(B)$. Use this result to compute the determinants of the matrices in Exercises 31 and 32. ◀

$$31. M = \left[\begin{array}{ccc|ccc} 1 & 2 & 0 & 8 & 6 & -9 \\ 2 & 5 & 0 & 4 & 7 & 5 \\ -1 & 3 & 2 & 6 & 9 & -2 \\ \hline 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & -3 & 8 & -4 \end{array} \right]$$

$$32. M = \left[\begin{array}{ccc|cc} 1 & 2 & 0 & 0 & 0 \\ 0 & 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ \hline 0 & 0 & 0 & 1 & 2 \\ 2 & 0 & 0 & 0 & 1 \end{array} \right]$$

33. Let A be an $n \times n$ matrix, and let B be the matrix that results when the rows of A are written in reverse order. State a theorem that describes how $\det(A)$ and $\det(B)$ are related.

34. Find the determinant of the following matrix.

$$\begin{bmatrix} a & b & b & b \\ b & a & b & b \\ b & b & a & b \\ b & b & b & a \end{bmatrix}$$

True-False Exercises

TF. In parts (a)–(f) determine whether the statement is true or false, and justify your answer.

- (a) If A is a 4×4 matrix and B is obtained from A by interchanging the first two rows and then interchanging the last two rows, then $\det(B) = \det(A)$.
- (b) If A is a 3×3 matrix and B is obtained from A by multiplying the first column by 4 and multiplying the third column by $\frac{3}{4}$, then $\det(B) = 3\det(A)$.
- (c) If A is a 3×3 matrix and B is obtained from A by adding 5 times the first row to each of the second and third rows, then $\det(B) = 25\det(A)$.
- (d) If A is an $n \times n$ matrix and B is obtained from A by multiplying each row of A by its row number, then

$$\det(B) = \frac{n(n+1)}{2} \det(A)$$

- (e) If A is a square matrix with two identical columns, then $\det(A) = 0$.
- (f) If the sum of the second and fourth row vectors of a 6×6 matrix A is equal to the last row vector, then $\det(A) = 0$.

Working with Technology

T1. Find the determinant of

$$A = \begin{bmatrix} 4.2 & -1.3 & 1.1 & 6.0 \\ 0.0 & 0.0 & -3.2 & 3.4 \\ 4.5 & 1.3 & 0.0 & 14.8 \\ 4.7 & 1.0 & 3.4 & 2.3 \end{bmatrix}$$

by reducing the matrix to reduced row echelon form, and compare the result obtained in this way to that obtained in Exercise T1 of Section 2.1.

2.3 Properties of Determinants; Cramer's Rule

In this section we will develop some fundamental properties of matrices, and we will use these results to derive a formula for the inverse of an invertible matrix and formulas for the solutions of certain kinds of linear systems.

Basic Properties of Determinants

Suppose that A and B are $n \times n$ matrices and k is any scalar. We begin by considering possible relationships among $\det(A)$, $\det(B)$, and

$$\det(kA), \quad \det(A+B), \quad \text{and} \quad \det(AB)$$

Since a common factor of any row of a matrix can be moved through the determinant sign, and since each of the n rows in kA has a common factor of k , it follows that