

FINAL EXAMINATION, SEMESTER I, 2022
DEPT. MATH., COLLEGE OF SCIENCE, KSU
MATH: 107 FULL MARK: 40 TIME: 3 HOURS

Q1. [Marks: 3+3+3=9]

(a) Find the values of λ for which the following system of equations has a unique solution:

$$2x_1 + 3x_2 + x_3 = -1$$

$$x_1 + 2x_2 + x_3 = 0$$

$$3x_1 + x_2 + (\lambda^2 - 6)x_3 = \lambda - 3.$$

(b) Let A be a square matrix with $\det(A) = 1$ and

$$\text{adj}(A) = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Compute A^{-1} and deduce A .

(c) By using Cramer's Rule solve the system of equations:

$$-p + q - 2r = 1$$

$$p - q + 9r = -2$$

$$5q + r = 4.$$

Q2. [Marks: 3+3+3=9]

(a) Let $\mathbf{u} = \langle 1, 2, -1 \rangle$, $\mathbf{v} = \langle 0, 1, -1 \rangle$ and $\mathbf{w} = \langle 2, 3, 1 \rangle$. (i) Find the angle between \mathbf{u} and \mathbf{v} .

(ii) Find the component of $\mathbf{u} + 2\mathbf{v}$ along \mathbf{w} .

(b) Find an equation of the plane that contains the point $P(4, -3, 0)$ and the line: $x = t + 5$, $y = 2t - 1$, $z = -t + 7$.

(c) Identify the surface $x - y^2 - z^2 = 0$, give traces, and sketch.

Q3. [Mark: 6+3+3=12]

(a) The position vector of a moving point at time t is $\mathbf{r}(t) = \langle 4 \cos t, 9 \sin t, t \rangle$. Find the tangential and normal components of acceleration, and curvature at time t .

(b) Show that $\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 + 3y^2}{x^2 + y^2}$ does not exist.

(c) The temperature T at (x, y) is given by $T = 5(x^2 + y^2)^2$, where T is in degrees and x and y are in centimeters. Use differential to approximate the temperature difference between points $(1, 1)$ and $(1.01, 0.98)$.

Q4. [Marks: 3+3+4=10]

(a) Use partial derivative to find $\frac{\partial z}{\partial x}$ if $(x^2 + 1)z^3 - y^2z^2 + xyz = 3$.

(b) Let $f(x, y, z) = xyz$. Find the directional derivative of f at the point $A(1, 1, 1)$ in the direction of the vector $\mathbf{a} = \mathbf{i} + \mathbf{j} + \mathbf{k}$.

(c) Let $g(x, y) = x^2 + y^2 + xy^2 + 9$. Find the local extrema and saddle point if any.

Solution M107 Final Exam

(P-1)

$$Q_1 (a) \left(\begin{array}{ccc|c} 2 & 3 & 1 & -1 \\ 1 & 2 & 1 & 0 \\ 3 & 1 & \lambda^2 - 6 & \lambda - 3 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & \lambda - 4 & \lambda - 2 \end{array} \right)$$

Hence the system has a unique solution for all $\lambda \in \mathbb{R} \setminus \{-2, 2\}$. Mark 3

$$(b) \det(A) = 1 \text{ and } \text{adj}(A) = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}. \text{ so,}$$

$$A^{-1} = \frac{1}{\det(A)} \cdot \text{adj}(A) = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}. \text{ Hence,}$$

$$A = (A^{-1})^{-1} = (\text{adj}(A))^{-1} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Mark: 1.5 + 1.5 = 3

$$(c) \det(A) = \begin{vmatrix} -1 & 1 & -2 \\ 1 & -1 & 9 \\ 0 & 5 & 1 \end{vmatrix} = 35$$

$$\cdot \det(A_1) = \begin{vmatrix} 1 & 1 & -2 \\ -2 & -1 & 9 \\ 4 & 5 & 1 \end{vmatrix} = 4$$

Mark 1

$$\cdot \det(A_2) = \begin{vmatrix} -1 & 1 & -2 \\ 1 & -2 & 9 \\ 0 & 4 & 1 \end{vmatrix} = 29$$

Mark 1

$$\cdot \det(A_3) = \begin{vmatrix} -1 & 1 & 1 \\ 1 & -1 & -2 \\ 0 & 5 & 4 \end{vmatrix} = -5$$

Mark 1

Thus, $p = \frac{4}{35}$, $q = \frac{29}{35}$, and $r = \frac{-5}{35} = -\frac{1}{7}$

Q₂ (a) $\|\underline{u}\| = \sqrt{6}$, $\|\underline{v}\| = \sqrt{2}$

(Mark 1.5)

$$\underline{u} \cdot \underline{v} = 3 \quad \cos \theta = \frac{\underline{u} \cdot \underline{v}}{\|\underline{u}\| \|\underline{v}\|} = \frac{3}{\sqrt{6} \sqrt{2}} = \frac{3}{\sqrt{12}} = \frac{3}{2\sqrt{3}}$$

(ii) $\underline{u} + 2\underline{v} = \langle 1, 4, -3 \rangle$

(Mark 1.5)

$$\text{Comp}_{\underline{w}} \underline{u} + 2\underline{v} = \frac{\langle 1, 4, -3 \rangle \cdot \langle 2, 3, 1 \rangle}{\sqrt{14}} = \frac{11}{\sqrt{14}}$$

(b) The point $Q(5, -1, 7)$ with $t=0$ and $R(6, 1, 6)$ with $t=1$ lie on the line and in the plane. As $P(4, -3, 0)$ we get $\overrightarrow{QP} = \langle -1, -2, -7 \rangle$ and $\overrightarrow{QR} = \langle 1, 2, -1 \rangle$.

Thus, $\overrightarrow{QP} \times \overrightarrow{QR} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ -1 & -2 & -7 \\ 1 & 2 & -1 \end{vmatrix} = \langle 16, -8, 0 \rangle$

(Mark 2)

Therefore, the equation of the plane is

$$16(x-4) - 8(y+3) + 0(z-0) = 0$$

or, $16x - 8y - 64 - 24 = 0$

i.e. $2x - y = 11$

(Mark 1)

(c) xy -trace: $x = y^2$ parabola

xz -trace: $x = z^2$ parabola

parallel to xy -Plane ($x=1$): $y^2 + z^2 = 1$ circle.

The surface $x = y^2 + z^2$ is a paraboloid.

(Marks: 1+1+1=3)

Q3 (a) $\underline{r}(t) = \langle 4\cos t, 9\sin t, t \rangle$
 $\underline{r}'(t) = \langle -4\sin t, 9\cos t, 1 \rangle$
 $\underline{r}''(t) = \langle -4\cos t, -9\sin t, 0 \rangle$

$$\underline{r}'(t) \cdot \underline{r}''(t) = 16\sin t \cos t - 81\sin t \cos t$$

$$= -65\sin t \cos t$$

$$\|\underline{r}'(t)\| = \sqrt{16\sin^2 t + 81\cos^2 t + 1}$$

$$a_T = \frac{-65\sin t \cos t}{(16\sin^2 t + 81\cos^2 t + 1)^{\frac{1}{2}}}$$

(Mark 2)

$$a_N = \frac{(81\sin^2 t + 16\cos^2 t + 1296)^{\frac{1}{2}}}{(16\sin^2 t + 81\cos^2 t + 1)^{\frac{1}{2}}}$$

(Mark 3)

$$k = a_N \cdot \frac{1}{16\sin^2 t + 81\cos^2 t + 1}$$

$$= \frac{(81\sin^2 t + 16\cos^2 t + 1296)^{\frac{1}{2}}}{(16\sin^2 t + 81\cos^2 t + 1)^{\frac{3}{2}}}$$

(Mark 1)

(b) $x \neq 0, f(x, 0) = 1, \lim_{x \rightarrow 0} \frac{x^2}{x^2} = 1$

$y \neq 0, f(0, y) = 3, \lim_{y \rightarrow 0} \frac{3y^2}{y^2} = 3$

By Two-path rule $\lim_{(x,y) \rightarrow (0,0)} f(x,y)$ DNE

(Mark 1 + 1 + 1 = 3)

Q₃ (c) $T(x, y) = 5(x^2 + y^2)^2$,
 $dx = 0.01$, $dy = -0.02$.

Mark 1

$$dT = 10(x^2 + y^2)(2x)dx + 10(x^2 + y^2)(2y)dy$$

$$= 20x(x^2 + y^2)dx + 20y(x^2 + y^2)dy$$

$(x, y) = (1, 1)$,

Mark 1

$$dT = 40(0.01 - 0.02) = -0.4$$

Mark 1

Q₄ (a) $F(x, y, z) = (x^2 + 1)z^3 - y^2z^2 + xyz - 3$

$$\frac{\partial z}{\partial x} = - \frac{(2xz^3 + yz)}{3(x^2 + 1)z^2 - 2y^2z + xy}$$

Mark 1.5 + 1.5 = 3

(b) $f(x, y, z) = xyz$

Mark 1

$$\underline{u} = \frac{\langle 1, 1, 1 \rangle}{\sqrt{3}} = \left\langle \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right\rangle$$

$$\nabla f = \langle yz, xz, xy \rangle$$

Mark 1

$$D_{\underline{u}} f(x, y, z) = \nabla f \cdot \underline{u}(x, y, z)$$

$$= \langle 1, 1, 1 \rangle \cdot \left\langle \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right\rangle$$

$$= \frac{3}{\sqrt{3}} = \sqrt{3}$$

Mark 1

Q4 (c) $g(x, y) = x^2 + y^2 + xy^2 + 9$

$$\Rightarrow \begin{cases} g_x = 2x + y^2 = 0 \\ g_y = 2y + 2xy = 0 \end{cases} \Rightarrow$$

$$2y - 2 \cdot \frac{1}{2} y^2 y = 0 \Rightarrow 2y - y^3 = 0 \Rightarrow y = 0, y = \pm\sqrt{2}$$

so, $\begin{cases} x = 0, y = 0 \\ x = -1, y = \sqrt{2} \\ x = -1, y = -\sqrt{2} \end{cases}$

(Mark 1)

Critical points are: $(0, 0)$, $(-1, \sqrt{2})$ and $(-1, -\sqrt{2})$.

$$D(x, y) = \begin{vmatrix} 2 & 2y \\ 2y & 2 + 2x \end{vmatrix}$$

(Mark 1)

$\cdot D(0, 0) = \begin{vmatrix} 2 & 0 \\ 0 & 2 \end{vmatrix} = 4 > 0, g_{xx} > 0 \Rightarrow \text{local min}$

$\cdot D(-1, \sqrt{2}) = \begin{vmatrix} 2 & 2\sqrt{2} \\ 2\sqrt{2} & 0 \end{vmatrix} = -8 < 0 \Rightarrow \text{saddle point}$

$\cdot D(-1, -\sqrt{2}) = \begin{vmatrix} 2 & -2\sqrt{2} \\ -2\sqrt{2} & 0 \end{vmatrix} = -8 < 0 \Rightarrow \text{saddle point}$

(Mark 2)