Vine Cand IIniversity	Mathematics Department	; Math-254
King Saud University: Third Semester	1444 H	Midterm Exam.
Maximum Marks $= 30$		Time: 120 mins.

Question 1: Show that the one of the possible rearrangement of the nonlinear equation $e^x - x^2 = 2 - 3x$, which has a root in the interval [0, 0.6] is

$$x = g(x) = \frac{2 - e^x + x^2}{3}.$$

Show that g(x) has a unique fixed-point in [0, 0.6]. Determine the number of iterations needed to get an approximation with accuracy 10^{-5} to the solution of

$$x_{n+1} = g(x_n) = \frac{2 - e_n^x + x_n^2}{3}; \qquad n \ge 0,$$

lying in the interval [0, 0.6] by using the fixed-point iteration method and $x_0 = 0.5$. [6 Marks]

Question 2: Show that the rate of convergence of Newton's method at the root $\alpha = 1$ of the equation $(x - 1)^2 \sin x = 0$ is linear. Use quadratic convergence method to find x_2 using $x_0 = 1.5$. Compute the relative error. [6 Marks]

Question 3: Find the values of a, b and c such that the iterative scheme

$$x_{n+1} = ax_n + \frac{bN}{x_n^2} + \frac{cN^2}{x_n^5}, \qquad n \ge 0,$$

converges at least cubically to $\alpha = N^{\frac{1}{3}}$. Use this scheme to find second approximation of $(8)^{\frac{1}{3}}$ when $x_0 = 1.8$.

Question 4: Use the simple Gaussian elimination method to find the inverse A^{-1} of the following matrix

$$A = \begin{pmatrix} 1 & -1 & 2\alpha \\ 2 & 2 & 4 \\ 0 & 4 & 8 \end{pmatrix}.$$

Using A^{-1} , find the unique solution of the system $A\mathbf{x} = [-4, 8, 12]^T$ taking α the largest possible negative integer value. [6 Marks]

Question 5: Use LU decomposition by Dollittle's method to find the value(s) of nonzero α for which the linear system $A\mathbf{x} = \mathbf{b}$, where

$$A = \begin{pmatrix} \alpha & 4 & 1 \\ 2\alpha & -1 & 2 \\ 1 & 3 & \alpha \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 6 \\ 3 \\ 5 \end{pmatrix},$$

is inconsistent and consistent. Solve the consistent system.

[6 Marks]

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Show that g(x) has a unique fixed-point in [0, 0.6]. Determine the number of iterations needed to get an approximation with accuracy 10^{-5} to the solution of

$$x_{n+1} = g(x_n) = \frac{2 - e_n^x + x_n^2}{3}; \qquad n \ge 0,$$

lying in the interval [0, 0.6] by using the fixed-point iteration method and $x_0 = 0.5$. [6 Marks]

Solution. Since $f(x) = e^x - x^2 + 3x - 2$, we observe that f(0)f(0.6) = (-1.0000)(1.2621) < 0, then the solution we seek is in the interval [0, 0.6]. Given $g(x) = \frac{2 - e^x + x^2}{3}$ is continuous in [0, 0.6] and

$$g(0) = \frac{2 - e^0 + 0}{3} = 0.3333$$
 and $g(0.6) = \frac{2 - e^{0.6} + (0.6)^2}{3} = 0.1793.$

Also, g is decreasing function of x, and both lie in the interval [0, 0.6]. Thus $g(x) \in [0, 0.6]$, for all $x \in [0, 0.6]$. Also, we have $g'(x) = \frac{-e^x + 2x}{3}$ continuous in (0, 0.6) and

$$g'(0) = \frac{-e^0 + 2(0)}{3} = -0.3333$$
 and $g'(0.6) = \frac{-e^{0.6} + 2(0.6)}{3} = -0.2074.$

Also, g' is decreasing function of x, and both lie in the interval (0, 0.6). Thus |g'(x)| < 1, for all x in the given interval (0, 0.6), so from fixed-point theorem the g(x) has a unique fixed-point. Using the given initial approximation $x_0 = 0.5$, we have the first approximation as

$$x_1 = g(x_0) = \frac{2 - e^{x_0} + x_0^2}{3} = \frac{2 - e^{0.5} + (0.5)^2}{3} = 0.2004.$$

Since a = 0 and b = 0.6, then the value of k can be found as follows

$$k_1 = |g'(0)| = 0.3333$$
 and $k_2 = |g'(0.6)| = 0.2074$,

which give $k = \max\{k_1, k_2\} = 0.3333$. Thus using the error bound formula,

$$|\alpha - x_n| \le \frac{k^n}{1-k} |x_1 - x_0|, \quad \text{for all} \quad n \ge 1,$$

and given

$$|\alpha - x_n| \le 10^{-5}$$
, so we have $\frac{k^n}{1-k}|x_1 - x_0| \le 10^{-5}$,

$$\frac{(0.3333)^n}{1 - 0.3333} |0.2004 - 0.5| \le 10^{-5}, \quad n \ln(0.3333) \le \ln(2.2252 \times 10^{-5}), \quad \text{gives}, \quad n \ge 9.7506,$$

So we need ten (10) approximations to get the desired accuracy for the given problem.

Solution. Since

$$f(x) = (x-1)^2 \sin x$$
 and $f'(x) = 2(x-1) \sin x + (x-1)^2 \cos x$

and f'(1) = 0, gives that $\alpha = 1$ is the multiple root. Using Newton's iterative formula, we get

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)} = x_n - \frac{((x_n - 1)^2 \sin x_n)}{(2(x_n - 1)\sin x_n + (x_n - 1)^2 \cos x_n)} = x_n - \frac{((x_n - 1)\sin x_n)}{(2\sin x_n + (x_n - 1)\cos x_n)},$$

for $n \ge 0$. The fixed point form of the developed Newton's formula is

$$x_{n+1} = g(x_n) = x_n - \frac{((x_n - 1)\sin x_n)}{(2\sin x_n + (x_n - 1)\cos x_n)}.$$

Then

$$g(x) = x - \frac{((x-1)\sin x)}{(2\sin x + (x-1)\cos x)},$$

and

$$g'(x) = 1 - \frac{(2\sin x + (x-1)\cos x)(\sin x + (x-1)\cos x) - ((x-1)\sin x)(3\cos x - (x-1)\sin x)}{(2\sin x + (x-1)\cos x)^2}$$

Thus

$$g'(1) = 1 - \frac{2(\sin 1)^2}{4(\sin 1)^2} = \frac{1}{2} \neq 0,$$

and so the Newton's method converges linearly. The quadratic convergent method for multiple root is modified Newton's method

$$x_{n+1} = x_n - m \frac{f(x_n)}{f'(x_n)}, \qquad n \ge 0,$$

where m is the order of multiplicity of the zero of the function. To find m, we check that

$$f''(x) = 2\sin x + 4(x-1)\cos x - (x-1)^2\sin x$$
, and $f''(1) = 2\sin 1 \neq 0$

so m = 2. Thus

$$x_{n+1} = x_n - 2\frac{f(x_n)}{f'(x_n)} = x_n - 2\frac{((x_n - 1)\sin x_n)}{(2\sin x_n + (x_n - 1)\cos x_n)}, \qquad n \ge 0.$$

Now using initial approximation $x_0 = 1.5$, we have the following two approximations

$$x_1 = x_0 - 2\frac{((x_0 - 1)\sin x_0)}{(2\sin x_0 + (x_0 - 1)\cos x_0)} = 1.0087, \quad x_2 = x_1 - 2\frac{((x_1 - 1)\sin x_1)}{(2\sin x_1 + (x_1 - 1)\cos x_1)} = 1.0000,$$

and the relative error is,

$$\frac{|\alpha - x_2|}{|\alpha|} = \frac{|1 - 1.0000|}{1} = 0.0000.$$

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Question 3: Find the values of a, b and c such that the iterative scheme

$$x_{n+1} = ax_n + \frac{bN}{x_n^2} + \frac{cN^2}{x_n^5}, \qquad n \ge 0.$$

converges at least cubically to $\alpha = N^{\frac{1}{3}}$. Use this scheme to find second approximation of $(8)^{\frac{1}{3}}$ when $x_0 = 1.8$.

Solution. Given the iterative scheme converges at least cubically means g' = g'' = 0 at $\alpha = N^{\frac{1}{3}}$. Let

$$g(x) = ax + \frac{bN}{x^2} + \frac{cN}{x^5}, \quad g(N^{\frac{1}{3}}) = 1 = a + b + c,$$

$$g'(x) = a - \frac{2bN}{x^3} - \frac{5cN^2}{x^6}, \quad g'(N^{\frac{1}{3}}) = 0 = a - 2b - 5c,$$

$$g''(x) = 0 + \frac{6bN}{x^4} + \frac{30cN^2}{x^7}, \quad g''(N^{\frac{1}{3}}) = 0 = 3b + 15c,$$

Solving these three equations for unknowns a, b and c, we obtain $a = b = \frac{5}{9}$ and $c = -\frac{1}{9}$. Thus

$$x_{n+1} = \frac{5x_n}{9} + \frac{5N}{9x_n^2} - \frac{N^2}{9x_n^5}, \qquad n \ge 0.$$

Using $x_0 = 1.8$, N = 8, we obtain

$$x_1 = \frac{5x_0}{9} + \frac{5N}{9x_0^2} - \frac{N^2}{9x_0^5} = 1.9954,$$

and

$$x_2 = \frac{5x_1}{9} + \frac{5N}{9x_1^2} - \frac{N^2}{9x_1^5} = 2.0000,$$

the required second approximation. The absolute error can be obtained as

$$|(8)^{1/3} - 2.0000| = |2.0000 - 2.0000| = 0.0000$$
 up to 4 dp

Question 4: Use the simple Gaussian elimination method to find the inverse A^{-1} of the following matrix

$$A = \left(\begin{array}{rrr} 1 & -1 & 2\alpha \\ 2 & 2 & 4 \\ 0 & 4 & 8 \end{array} \right).$$

Using A^{-1} , find the unique solution of the system $A\mathbf{x} = [-4, 8, 12]^T$ taking α the largest possible negative integer value. [6 Marks]

Solution. Suppose that the inverse $A^{-1} = B$ of the given matrix exists and let

$$AB = \begin{pmatrix} 1 & -1 & 2\alpha \\ 2 & 2 & 4 \\ 0 & 4 & 8 \end{pmatrix} \begin{pmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \mathbf{I}.$$

Now to find the elements of the matrix B, we apply the simple Gaussian elimination on the augmented matrix

$$[A|\mathbf{I}] = \begin{pmatrix} 1 & -1 & 2\alpha & \vdots & 1 & 0 & 0 \\ 2 & 2 & 4 & \vdots & 0 & 1 & 0 \\ 0 & 4 & 8 & \vdots & 0 & 0 & 1 \end{pmatrix}.$$

Using $m_{21} = \frac{2}{1} = 2$ and $m_{31} = 0$, gives

$$[A|\mathbf{I}] \equiv \begin{pmatrix} 1 & -1 & 2\alpha & \vdots & 1 & 0 & 0 \\ 0 & 4 & 4 - 4\alpha & \vdots & -2 & 1 & 0 \\ 0 & 4 & 8 & \vdots & 0 & 0 & 1 \end{pmatrix}.$$

Using $m_{32} = \frac{4}{4} = 1$, gives

$$[A|\mathbf{I}] \equiv \begin{pmatrix} 1 & -1 & 2\alpha & \vdots & 1 & 0 & 0 \\ 0 & 4 & 4 - 4\alpha & \vdots & -2 & 1 & 0 \\ 0 & 0 & 4 + 4\alpha & \vdots & 2 & -1 & 1 \end{pmatrix}$$

Solve the first upper system

$$\begin{pmatrix} 1 & -1 & 2\alpha \\ 0 & 4 & 4-4\alpha \\ 0 & 0 & 4+4\alpha \end{pmatrix} \begin{pmatrix} b_{11} \\ b_{21} \\ b_{31} \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix},$$

by using backward substitution, we get

$$b_{11} - b_{21} + 2\alpha b_{31} = 1$$

$$4b_{21} + (4 - 4\alpha)b_{31} = -2$$

$$+ (4 + 4\alpha)b_{31} = 2$$

which gives $b_{11} = 0$, $b_{21} = -\frac{1}{1+\alpha}$, $b_{31} = \frac{1}{2(1+\alpha)}$. Similarly, the solution of the second upper system

$$\begin{pmatrix} 1 & -1 & 2\alpha \\ 0 & 4 & 4-4\alpha \\ 0 & 0 & 4+4\alpha \end{pmatrix} \begin{pmatrix} b_{12} \\ b_{22} \\ b_{32} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix},$$

can be obtained as follows:

$$b_{12} - b_{22} + 2\alpha b_{32} = 0$$

$$4b_{22} + (4 - 4\alpha)b_{32} = 1$$

$$+ (4 + 4\alpha)b_{32} = -1$$

which gives $b_{12} = \frac{1+\alpha}{2(\alpha+1)}$, $b_{22} = \frac{1}{2(\alpha+1)}$, $b_{32} = -\frac{1}{4(\alpha+1)}$. Finally, the solution of the third upper system

$$\begin{pmatrix} 1 & -1 & 2\alpha \\ 0 & 4 & 4-4\alpha \\ 0 & 0 & 4+4\alpha \end{pmatrix} \begin{pmatrix} b_{13} \\ b_{23} \\ b_{33} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix},$$

can be obtained as follows:

$$b_{13} - b_{23} + 2\alpha b_{33} = 0$$

$$4b_{23} + (4 - 4\alpha)b_{33} = 0$$

$$+ (4 + 4\alpha)b_{33} = 1$$

and it gives $b_{13} = -\frac{1}{4}$, $b_{23} = \frac{\alpha - 1}{4(\alpha + 1)}$, $b_{33} = \frac{1}{4(\alpha + 1)}$. Hence the elements of the inverse matrix B are Thus

$$B = A^{-1} = \begin{pmatrix} 0 & \frac{1+\alpha}{2(\alpha+1)} & -\frac{1}{4} \\ -\frac{1}{1+\alpha} & \frac{1}{2(\alpha+1)} & \frac{\alpha-1}{4(\alpha+1)} \\ \frac{1}{2(1+\alpha)} & -\frac{1}{4(\alpha+1)} & \frac{1}{4(\alpha+1)} \end{pmatrix},$$

which is the required inverse of the given matrix A for any α . The inverse does not exist at $\alpha = -1$, so take $\alpha = -2$, we get

$$B = A^{-1} = \begin{pmatrix} 0 & 0.5 & -0.25 \\ 1 & -0.5 & 0.75 \\ -0.5 & 0.25 & -0.25 \end{pmatrix},$$

which is the required inverse of the given matrix A. Now to find the solution of the system, we do as

$$\mathbf{x} = A^{-1}\mathbf{b} = \begin{pmatrix} 0 & 0.5 & -0.25 \\ 1 & -0.5 & 0.75 \\ -0.5 & 0.25 & -0.25 \end{pmatrix} \begin{pmatrix} -4 \\ 8 \\ 12 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix},$$

the required solution.

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Question 5: Use LU decomposition by Dollittle's method to find the value(s) of nonzero α for which the linear system $A\mathbf{x} = \mathbf{b}$, where

$$A = \begin{pmatrix} \alpha & 4 & 1 \\ 2\alpha & -1 & 2 \\ 1 & 3 & \alpha \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 6 \\ 3 \\ 5 \end{pmatrix},$$

is inconsistent and consistent. Solve the consistent system.

Solution. Since we know that

$$A = \begin{pmatrix} \alpha & 4 & 1 \\ 2\alpha & -1 & 2 \\ 1 & 3 & \alpha \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{pmatrix} \begin{pmatrix} u_{11} & u_{12} & u_{13} \\ 0 & u_{22} & u_{23} \\ 0 & 0 & u_{33} \end{pmatrix} = LU.$$

Using $m_{21} = \frac{2\alpha}{\alpha} = 2 = l_{21}, m_{31} = \frac{1}{\alpha} = l_{31}$, and $m_{32} = \frac{(3\alpha - 4)}{(-9\alpha)} = l_{32} (\alpha \neq 0)$, gives

$$\begin{pmatrix} \alpha & 4 & 1\\ 0 & -9 & 0\\ 0 & \frac{(3\alpha-4)}{\alpha} & \frac{(\alpha^2-1)}{\alpha} \end{pmatrix} \equiv \begin{pmatrix} \alpha & 4 & 1\\ 0 & -9 & 0\\ 0 & 0 & \frac{(\alpha^2-1)}{\alpha} \end{pmatrix}.$$

Obviously, the original set of equations has been transformed to an upper-triangular form. Thus

$$A = \begin{pmatrix} \alpha & 4 & 1\\ 2\alpha & -1 & 2\\ 1 & 3 & \alpha \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0\\ 2 & 1 & 0\\ \frac{1}{\alpha} & \frac{(3\alpha - 4)}{(-9\alpha)} & 1 \end{pmatrix} \begin{pmatrix} \alpha & 4 & 1\\ 0 & -9 & 0\\ 0 & 0 & \frac{(\alpha^2 - 1)}{\alpha} \end{pmatrix},$$

which is the required decomposition of A. The given linear system has no solution or infinitely many solution if

$$det(A) = det(U) = \frac{-9\alpha(\alpha^2 - 1)}{\alpha} = -9(\alpha^2 - 1) = (\alpha^2 - 1) = 0,$$

which gives, $\alpha = -1$ or $\alpha = 1$.

To find the solution of the given system when $\alpha = -1$ and it gives

$$\begin{pmatrix} -1 & 4 & 1 \\ -2 & -1 & 2 \\ 1 & 3 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & -\frac{7}{9} & 1 \end{pmatrix} \begin{pmatrix} -1 & 4 & 1 \\ 0 & -9 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

Now solving the lower-triangular system $L\mathbf{y} = \mathbf{b}$ for unknown vector \mathbf{y} , that is

$$\left(\begin{array}{rrrr} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & -\frac{7}{9} & 1 \end{array}\right) \left(\begin{array}{r} y_1 \\ y_2 \\ y_3 \end{array}\right) = \left(\begin{array}{r} 6 \\ 3 \\ 5 \end{array}\right).$$

Performing forward substitution yields, $[y_1, y_2, y_3]^T = [6, -9, 4]^T$.

Then solving the upper-triangular system $U\mathbf{x} = \mathbf{y}$ for unknown vector \mathbf{x} , that is

$$\left(\begin{array}{rrrr} -1 & 4 & 1 \\ 0 & -9 & 0 \\ 0 & 0 & 0 \end{array}\right) \left(\begin{array}{r} x_1 \\ x_2 \\ x_3 \end{array}\right) = \left(\begin{array}{r} 6 \\ -9 \\ 4 \end{array}\right).$$

[6 Marks]

Last row gives, $0x_1 + 0x_2 + 0x_3 = 4$, which is not possible, and so no solution. To find the solution of the given system when $\alpha = 1$ and it gives

$$\begin{pmatrix} 1 & 4 & 1 \\ 2 & -1 & 2 \\ 1 & 3 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & \frac{1}{9} & 1 \end{pmatrix} \begin{pmatrix} 1 & 4 & 1 \\ 0 & -9 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

Now solving the lower-triangular system $L\mathbf{y} = \mathbf{b}$ for unknown vector \mathbf{y} , that is

$$\begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & \frac{1}{9} & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} 6 \\ 3 \\ 5 \end{pmatrix}.$$

Performing forward substitution yields, $[y_1, y_2, y_3]^T = [6, -9, 0]^T$. Then solving the upper-triangular system $U\mathbf{x} = \mathbf{y}$ for unknown vector \mathbf{x} , that is

$$\left(\begin{array}{rrrr} 1 & 4 & 1 \\ 0 & -9 & 0 \\ 0 & 0 & 0 \end{array}\right) \left(\begin{array}{r} x_1 \\ x_2 \\ x_3 \end{array}\right) = \left(\begin{array}{r} 6 \\ -9 \\ 0 \end{array}\right).$$

Last row gives, $0x_1+0x_2+0x_3=0$, which means we have many solutions. Performing backward substitution and using $x_3 = t$, yields

and it gives, $[x_1, x_2, x_3]^T = [2 - t, 1, t]^T$, for any nonzero t.

To find the unique solution for system for nonzero $\alpha \ (\neq \pm 1)$ we do as follows:

$$L\mathbf{y} = \begin{pmatrix} 1 & 0 & 0\\ 2 & 1 & 0\\ \frac{1}{\alpha} & \frac{(3\alpha - 4)}{(-9\alpha)} & 1 \end{pmatrix} \begin{pmatrix} y_1\\ y_2\\ y_3 \end{pmatrix} = \begin{pmatrix} 6\\ 3\\ 5 \end{pmatrix} = \mathbf{b}.$$

Performing forward substitution yields, $[y_1, y_2, y_3]^T = [6, -9, \frac{2\alpha - 2}{\alpha}]^T$. Then solving the upper-triangular system $U\mathbf{x} = \mathbf{y}$ for unknown vector \mathbf{x} , that is

$$\begin{pmatrix} \alpha & 4 & 1\\ 0 & -9 & 0\\ 0 & 0 & \frac{(\alpha^2 - 1)}{\alpha} \end{pmatrix} \begin{pmatrix} x_1\\ x_2\\ x_3 \end{pmatrix} = \begin{pmatrix} 6\\ -9\\ \frac{2\alpha - 2}{\alpha} \end{pmatrix},$$

and performing backward substitution yields, $[x_1, x_2, x_3]^T = [\frac{2\alpha - 2}{\alpha^2 - 1}, 1, \frac{2\alpha - 2}{\alpha^2 - 1}]^T$.