

PHY331

Magnetism

Lecture 2

Last week...

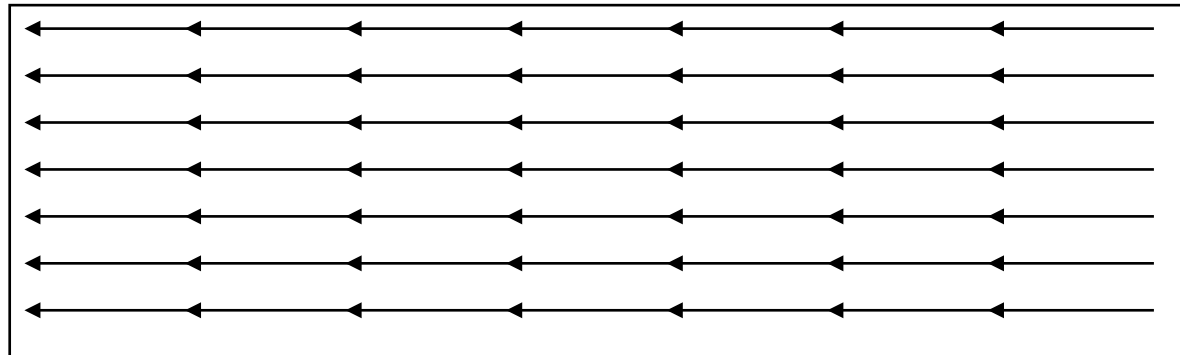
- Revised basic concepts (B and H, energy, torque and force in a magnetic field).
- Talked about different magnetic materials:
 - Diamagnetic
 - Paramagnetic
 - Ferromagnetic

This week...

- Derive magnetic dipole moment of a circulating electron.
- Discuss motion of a magnetic dipole in a constant magnetic field.
- Show that it precesses with a frequency called the Larmor precessional frequency

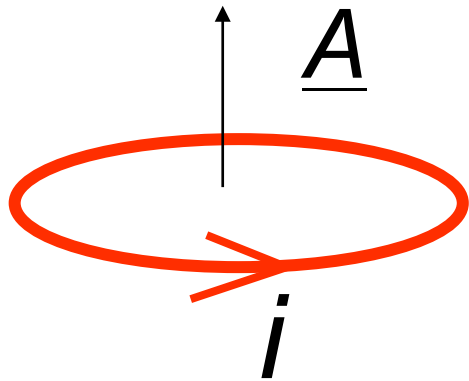
Magnetism on an atomic scale

The old “school picture” of a magnetic material is not so inaccurate if we replace the little arrows by atomic magnetic dipole moments



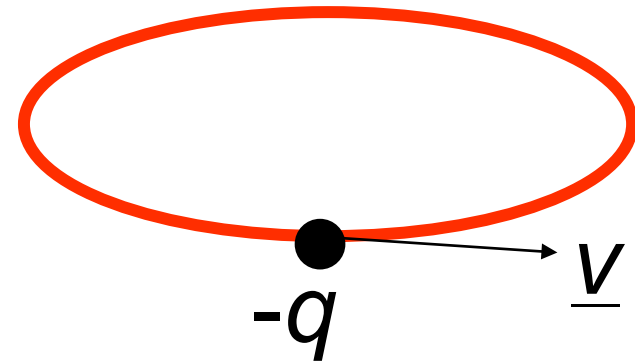
Force on a conductor
in a magnetic field.

$$\underline{m} = i \underline{A}$$



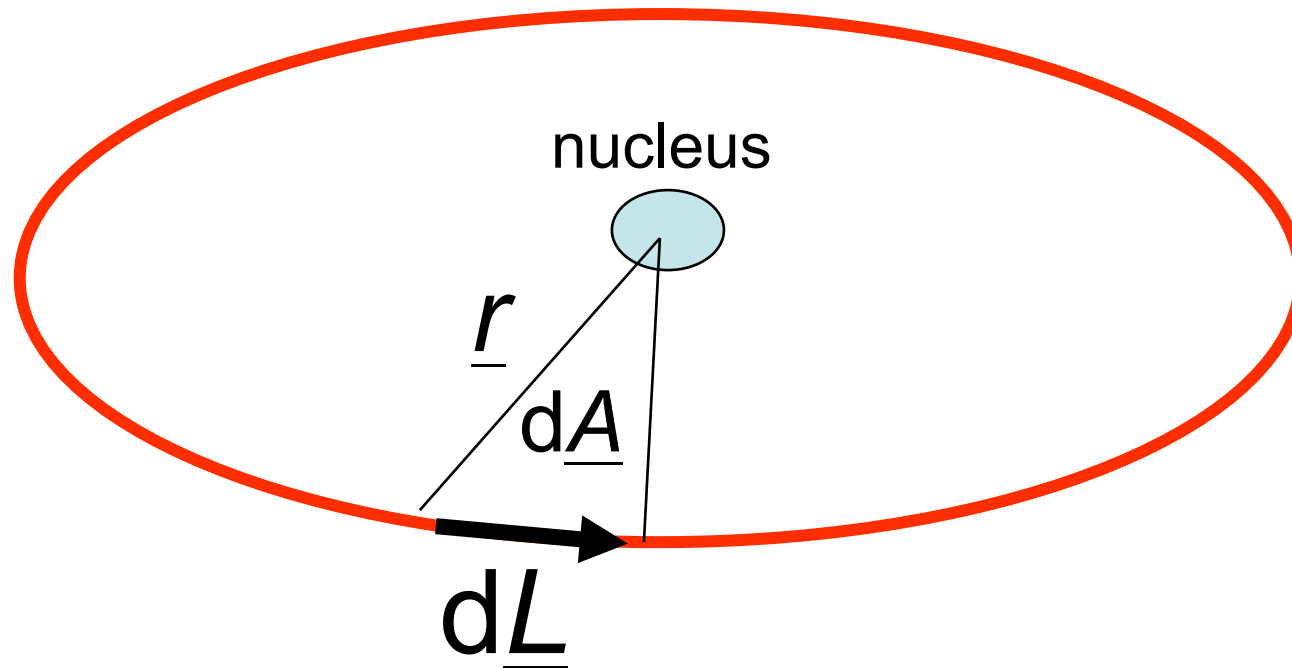
$$\underline{F} = i d\underline{l} \times \underline{B}$$

circulating electron



$$\underline{F} = q \underline{v} \times \underline{B}$$

The magnetic dipole moment of a circulating electron



Triangle area = $1/2 \times \text{base} \times \text{height}$

$$\underline{dA} = \frac{1}{2} \underline{r} \times \underline{dL}$$

- start with $\underline{m} = i \underline{A}$

and re-write as, $\underline{m} = \int i d\underline{A}$

from the diagram, $\underline{m} = \int i \frac{\underline{r} \times d\underline{l}}{2}$

- since $i = -dq/dt$ and $\underline{v} = d\underline{l}/dt$

then $i d\underline{l} = -\underline{v} dq$ so that,

$$\underline{m} = - \int \frac{\underline{r} \times \underline{v} dq}{2} = - \int \frac{\underline{r} \times \underline{v}}{2} dq$$

Remember that the angular momentum L of the circulating electron is

$$\underline{L} = m (\underline{r} \times \underline{v})$$

so that the magnetic dipole moment \underline{m} of the circulating electron is,

$$\underline{m} = -\frac{1}{2} \frac{\underline{L}}{m} \int dq \quad \text{or} \quad \underline{m} = -\frac{\underline{L}}{2m} q \quad (1)$$

where q is the total charge circulating. Note the negative sign.

Magnetic dipole moment (m) dependent on L

- This is a really important result! It demonstrates that an electron in a stable atomic orbital having an angular momentum L has a magnetic dipole moment m .
- This is will be particularly important in the quantum theory of paramagnetism that we will cover later. Here, we will use the fact that both L (and S) are quantised

Atomic theory of Diamagnetism

- Diamagnetic materials have small *negative* values of the susceptibility χ . Magnetisation will oppose an applied magnetic field.
- ***ALL*** materials are diamagnetic.
- The small diamagnetic contribution to the magnetisation M is overwhelmed if the material under investigation is also a **paramagnet** or a **ferromagnet**.
- If all materials are diamagnetic.....it must involve some fundamental mechanism.



Diamagnetic frog

A very simplified picture... (Weber 1854)

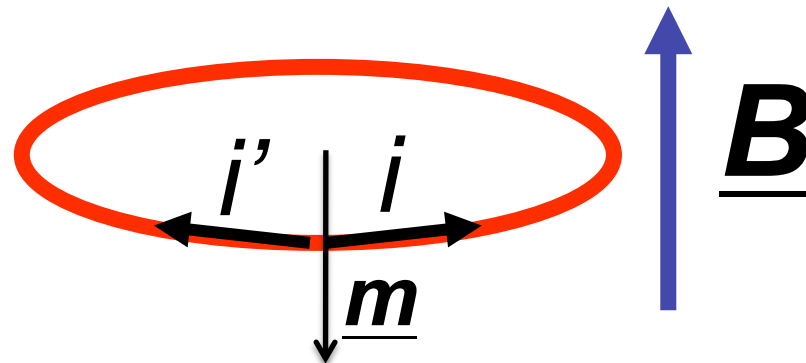
Apply a field B to a current loop.

The flux through the loop changes a *back* E.M.F. is induced.

The *back* E.M.F. and its associated current (i') oppose the applied B field (Lenz's Law).

If the resistance of the loop is *small**, the new induced current continues for as long as the B field is applied (*e.g. like a circulating electron?).

This circulating current results causes a magnetic dipole which opposes applied magnetic field.



‘Atomic version’ of Lenz’s law

Can very simplistically think of diamagnetism as ‘atomic-version’ of Lenz’s law (i.e. a response to a magnetic field that creates a current that ‘flows’ around each atom).

DO NOT consider this as a bulk phenomena - diamagnetism **ONLY** works at the scale of an individual atom!

Actually, the ‘best’ way to think of diamagnetism is a magnetic field caused by the precession of electrons in an applied magnetic field.

Precession: the motion of a magnetic dipole in a constant magnetic field

- Every circulating electron on every atom has a *magnetic dipole moment*
- The magnetic field \underline{B} produces a torque $\underline{\Gamma}$ on each dipole
- by Newton's Law,
$$\frac{d\underline{L}}{dt} = \underline{\Gamma} = \underline{m} \times \underline{B} \quad (2)$$

rate of change of (angular) momentum = applied torque

we already know $\underline{m} = \underline{m}(\underline{L})$ so that,

$$\frac{d\underline{L}}{dt} = - \frac{q}{2m} \underline{L} \times \underline{B}$$

(substitute (1) into (2))

must be the vector equation of motion (*it will be precessional motion*)

so for a B field in the vertical z direction only,

$$\frac{dL_x}{dt} \hat{i} + \frac{dL_y}{dt} \hat{j} + \frac{dL_z}{dt} \hat{k} = - \frac{q}{2m} \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ L_x & L_y & L_z \\ 0 & 0 & B \end{vmatrix}$$

this gives,

$$\frac{dL_x}{dt} = -\frac{q}{2m} L_y B \quad \frac{dL_y}{dt} = +\frac{q}{2m} L_x B \quad \frac{dL_z}{dt} = 0$$

the component of L along z is constant,

say
$$L_z = L \cos \alpha$$

so solving the x and y components gives,

$$\frac{d^2 L_x}{dt^2} = -\frac{qB}{2m} \frac{dL_y}{dt} = -\left(\frac{qB}{2m}\right)^2 L_x$$

and a similar equation for L_y ,

$$\frac{d^2 L_y}{dt^2} = - \left(\frac{qB}{2m} \right)^2 L_y$$

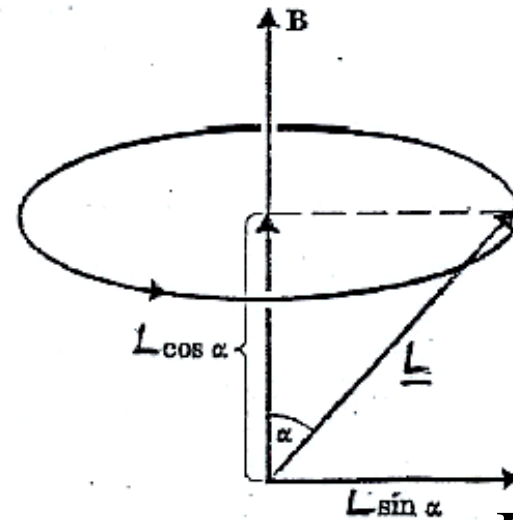
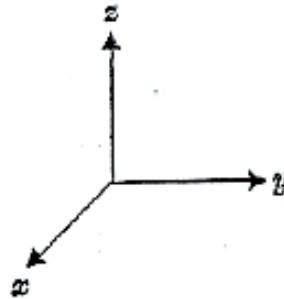
(recall $\ddot{x} + \omega^2 x = 0$ for SHM)

i.e. the equations of two simple harmonic motions at 90° , so we have circular motion with a constant L_z component.

$$L_x = L \sin(\alpha) \cos(\omega t)$$

$$L_y = L \sin(\alpha) \sin(\omega t)$$

$$L_z = L \cos(\alpha)$$



This is precessional motion with

$$\omega_L = \frac{qB}{2m}$$

where ω_L is known as the Larmor precessional frequency when $q = e$.

Summary

Saw that the magnetic dipole moment \underline{m} of the circulating electron in a loop is

$$\underline{m} = -\frac{\underline{L}}{2m} q$$

Applied Newton's Law,
to get SHM solutions of form

$$\frac{d\underline{L}}{dt} = \underline{\Gamma} = \underline{m} \times \underline{B}$$

$$\frac{d^2 L_x}{dt^2} = -\left(\frac{qB}{2m}\right)^2 L_x \quad \frac{d^2 L_y}{dt^2} = -\left(\frac{qB}{2m}\right)^2 L_y$$

where $L_y = L \sin(\alpha) \sin(\omega t)$ etc.. *Precession in a field with a frequency $\omega = qB / 2m$*