Pathological Gait

Kinesiology RHS 341 Lecture **13** Dr. Einas Al-Eisa

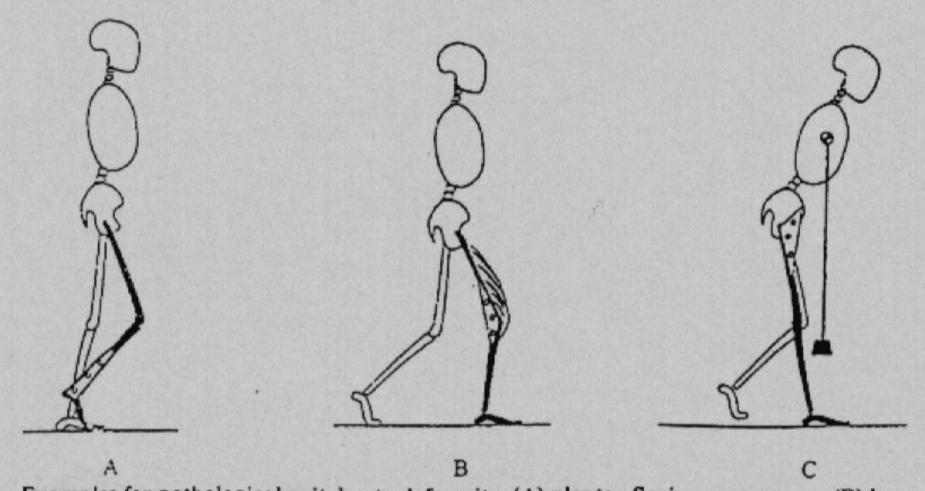
Causes

- 1. Deformity
- 2. Impaired motor control (spasticity)
- 3. Sensory loss
- 4. Pain
- 5. Muscle weakness

Contracture is the most common cause of deformity, such as:

Plantar flexion contracture:

- ➤In stance: blocks progression of the limb over the supporting foot
- ➤ In swing: inhibits floor clearance (increased hip flexion is needed)



Examples for pathological gait due to deformity. (A) plantar flexion contracture, (B) knee flexion contracture, and (C) hip flexion contracture. Contracture is indicated by bolted plate.

Knee flexion contracture:

➤ Blocks progression during stance

Increases the activity in the quadriceps in order to stabilize the knee

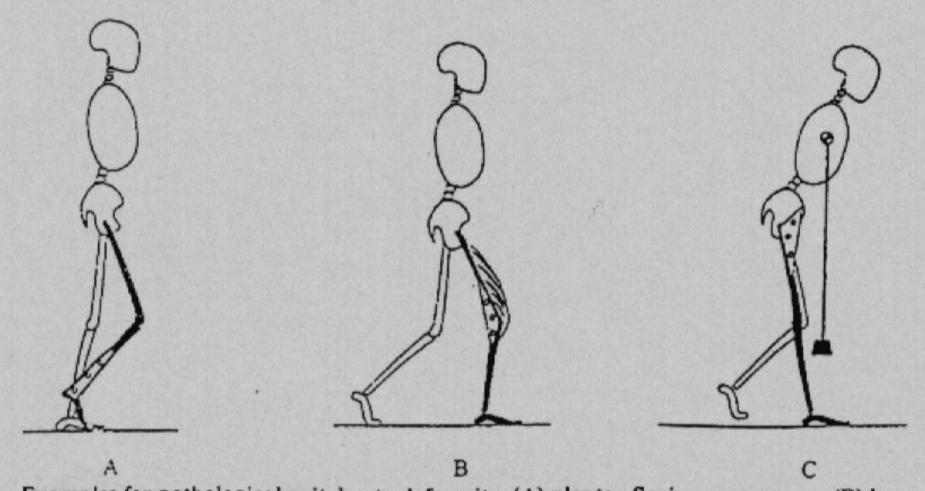
Knee extension contracture:

Increases the energy cost of walking due to the additional body maneuvers required for foot clearance

Hip flexion contracture:

➤To place the body's COG over the supporting foot, the trunk must lean forward

➤introduces strain on the back muscles and hip extensors



Examples for pathological gait due to deformity. (A) plantar flexion contracture, (B) knee flexion contracture, and (C) hip flexion contracture. Contracture is indicated by bolted plate.

Soleus and gastrocnemius spasticity:

>Lead to persistent ankle plantar flexion

Hamstring spasticity:

- > leads to persistent knee flexion
- > limits the effectiveness of terminal swing
- >restricts thigh advancement in stance

Hip flexor spasticity:

Restricts progression in mid and terminal stance

Sustained quadriceps action:

➤ Inhibits pre-swing preparation for limb advancement

3. Sensory loss

 Prevents the patient from knowing the position of the hip, knee, ankle, or foot

3. Sensory loss

Moderate sensory loss causes slow walking

 Greater sensory loss may obstruct walking as it causes the patient to be unable to use his available motor control because he/she can not trust the motions that occurs

4. Pain

Major causes of musculoskeletal pain are:

>Excessive tissue tension

>Joint distension related to trauma or arthritis

Pain in the limbs:

May be classified under 4 headings:

- 1. Joint pain
- 2. Soft tissue pain
- 3. Neurogenic pain
- 4. Orthopaedic causes (fractures, dislocations, tumors, infections)

4. Pain

Physiological reactions to pain are:

> Deformity

>Muscular weakness

5. Muscle weakness

 When the patient's muscle strength is insufficient to meet the demands of walking

 Can be caused by disuse muscular atrophy or neurological impairment

Normal function:

➤ During <u>initial contact</u> and loading response, the GRFV lies <u>anterior</u> to the hip joint creating <u>flexion moment</u> which is compensated by the action of the gluteus maximus of the supporting leg

Effect of weakness on gait:

➤ Inability to counteract the <u>flexion</u> moment

Tendency for excessive hip flexion and anterior pelvic tilt

Possible compensation:

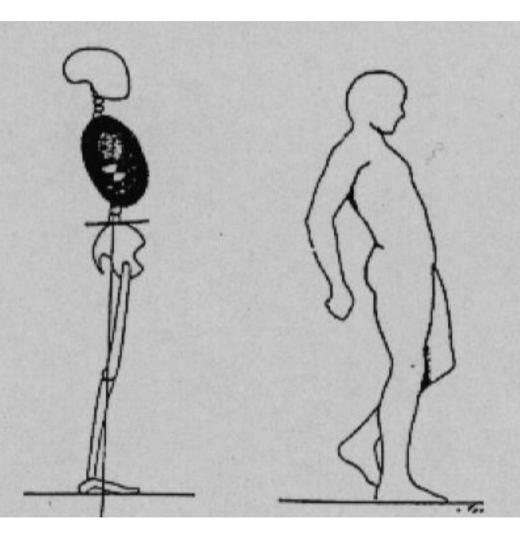
The patient will lean the trunk backward to shift the GRFV behind the axis of the hip joint and to prevent the trunk from falling forward (gluteus maximus gait)

Possible compensation:

➤ Note: the trunk will lean backward during the entire stride whether the weakness is unilateral or bilateral

Long term effects of compensation:

>Excessive lumbar lordosis



Shifting the GRFV behind the hip joint to compensate for hip extensor muscle weakness.

Normal function:

➤ During single limb support, the GRFV lies medial to the hip joint creating adduction moment

Normal function:

There is tendency of the pelvis and trunk to drop laterally to the opposite side (toward the swing limb) by the effect of the adduction moment

Normal function:

Adduction moment is counterbalanced by the action of the abductor muscles on the stance limb to prevent the trunk and pelvis from dropping to the unsupported side

Effect of weakness on gait:

Inability to counteract the <u>adduction</u> moment, so the pelvis will drop towards the swing side (positive **Trendlenburg sign**)

Possible compensation:

If the weakness is <u>unilateral</u>: the patient will lean the trunk laterally toward the weak limb every time it contacts the ground and throughout the stance phase (gluteus medius gait)

Possible compensation:

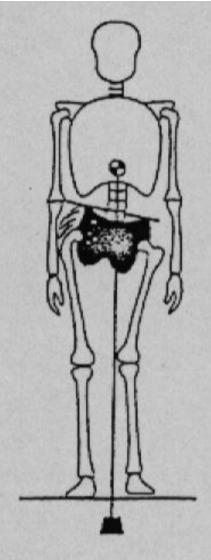
➤If the weakness is <u>bilateral</u>: (waddling gait)

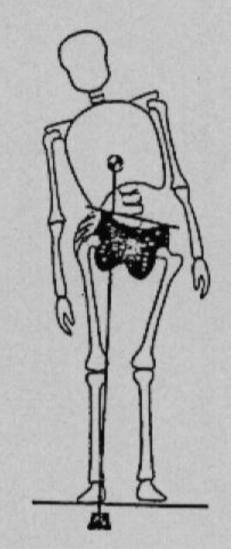
Possible compensation:

Note: lateral leaning of the trunk shifts the GRFV to pass either through the hip joint (where no moment is created), or lateral to the hip joint (creating abduction moment to be compensated by the adductors)

Long term effects of compensation:

➤ Lateral spinal curve (functional scoliosis)





(A)

Contralateral pelvic drop resulting from weak ipsilateral hip abductors. (A) the body COG is displaced away from stance limb, (B) compensating trunk lean and COG moves toward stance limb.

Weakness of knee extensors (Quadriceps)

Normal function:

During <u>loading responses</u>, the GRFV lies <u>posterior</u> to the knee joint creating <u>flexion</u> <u>moment</u> which is compensated by the eccentric action of the quadriceps muscle

Weakness of knee extensors (Quadriceps)

Effect of weakness on gait:

➤ Inability to counteract the <u>flexion</u> moment

➤ Tendency for excessive knee flexion during loading response and instability at heel strike

Weakness of knee extensors (Quadriceps)

Possible compensation:

The hip extensors (gluteus maximus) and plantar flexors (soleus) will tend to pull the femur & tibia posteriorly resulting in knee extension

Possible compensation:

➤ The trunk will lean <u>forward</u> to shift the GRFV anterior to the knee joint creating an extension moment and placing the knee in hyperextension (which eliminates the need for the quadriceps action)

Possible compensation:

If both the quadriceps and gluteus maximus are paralyzed, the patient may compensate by **pushing the femur posteriorly with his hand** at initial contact and loading response (to prevent hip flexion and put the knee into extension)

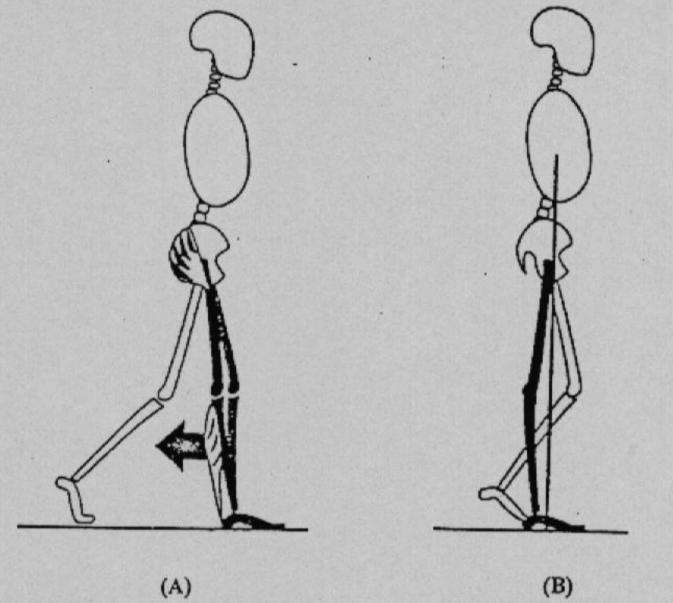
Possible compensation:

The patient may turn the limb outward to lock the knee joint in extension (eliminating the need for quadriceps activity)

Long term effects of compensation:

Disabling fatigue

➤ Degeneration of the ligaments supporting the hyper-extended knee (due to chronic strain)



Substitution for weak quadriceps. (A) is the action of the soleus and gluteus maximus to retract the tibia and the femur. (B) is the shifting of the GRFV anterior to the knee joint.

Normal function:

➤ During <u>initial contact</u> and loading response, the GRFV lies <u>posterior</u> to the ankle joint creating <u>plantar flexion</u> moment which is compensated by the action of the tibialis anterior

Normal function:

Note: the action of the tibialis anterior is concentric during initial contact, then the action changes to eccentric during loading response (to prevent foot slap)

Effect of weakness on gait:

➤ Inability to counteract the <u>plantar flexion</u> moment

>Excessive plantar flexion

Effect of weakness on gait:

The entire foot and toes would strike the floor at initial contact (lack of normal heel strike)

➤ Toe drag during swing phase

Possible compensation:

Increased hip and knee flexion to lift the limb and foot in swing phase (high steppage gait)

➤Or: hip hiking of the affected side

Possible compensation:

➤If knee flexion is impaired: the limb can be lifted by cricumduction of the leg

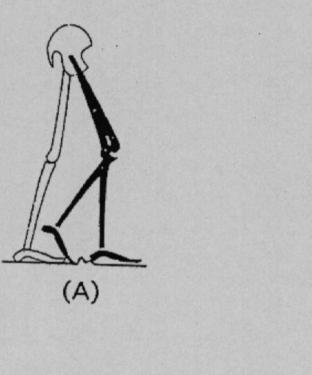
Long term effects of compensation:

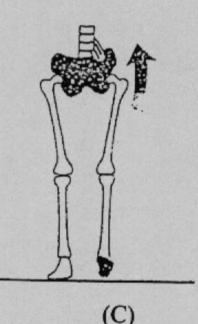
Easy fatigue due to increased energy expenditure as a result of the compensation A: toe drag

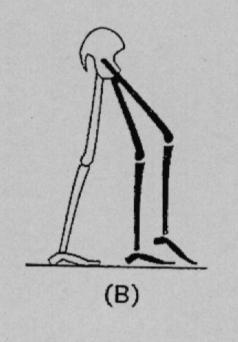
B: high steppage gait

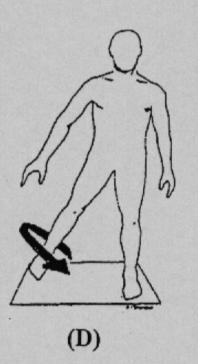
C: hip hiking

D: circumduction









Normal function:

➤ During mid-stance, terminal stance and pre-swing, the GRFV lies anterior to the ankle joint creating dorsiflexion moment which is compensated by the action of the plantar flexors

Normal function:

➤ Note: the calf muscles contract eccentrically 1st to oppose the dorsiflexion moment and control tibial advance, then contract concentrically to plantar flex the ankle in the later part of stance phase

Effect of weakness on gait:

➤ Inability to counteract the <u>dorsiflexion</u> moment

Effect of weakness on gait:

Excessive ankle dorsiflexion and uncontrolled tibial advancement leading to loss of tibial stability during the weight bearing period (at the onset of single limb support)

Possible compensation:

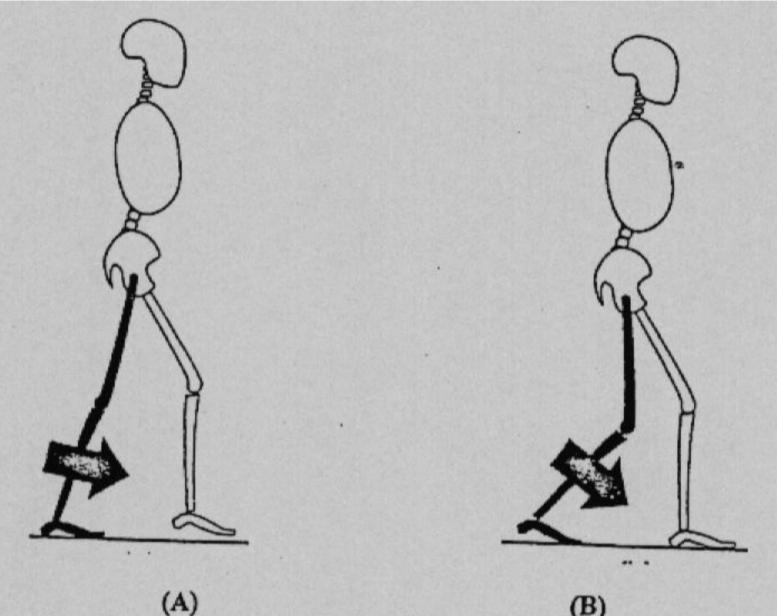
Increased demand on quadriceps to counteract tibial instability

Terminal stance knee extension is lost and replaced with flexion

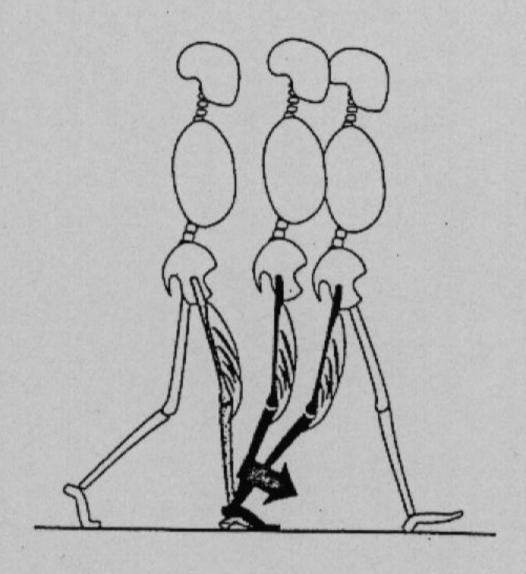
Possible compensation:

Delayed heel rise (prolonged heel contact) during stance phase (terminal stance and pre-swing)

➤ Shorter steps and slower walking speed



Excessive ankle dorsiflexion is represented by (A) prolonged heel contact and (B) excessive knee flexion.



(C)
Action of quadriceps muscle to counteract tibial instability leading to sustained knee flexion.

Correction of gait

 Exercise program geared for correction of, or compensation for, the disability or weakness:

- >Strengthening & mobilizing exercises
- Balance training
- ➤ Encouragement of rhythmic rotatory trunk movements

Correction of gait

 The patient must gain the knowledge, the image and the feeling of a correct posture and walking pattern

 The patient should stand upright looking straight ahead and not down at his feet (using a mirror)

Aids to walking

May be temporary or permanent

- The choice depends on the patient's disability, general condition, and age:
 - ➤ Adjustable parallel bars
 - ➤ Sticks (canes)
 - ➤ Crutches

1. Four-point alternate crutch gait

- Crutch-leg sequence:
 - Right crutch
 - Left leg
 - Left crutch
 - Right leg
- Safe, but slow gait

2. Two-point alternate crutch gait

- Crutch-leg sequence:
 - Right crutch and left leg together
 - Left crutch and right leg together

 Faster than the four-point gait, and demands greater balance

3. Three-point crutch gait

- Crutch-leg sequence:
 - Both crutches and the weaker leg
 - The stronger leg

 Used when one limb is unable to take any weight or only partial weight

4. Swing-to crutch gait

- Crutch-body sequence:
 - Both crutches are lifted and placed on the ground in front of the body
 - The body swings forward to the crutches

5. Swing-through crutch gait

- Crutch-body sequence:
 - Both crutches are lifted and placed on the ground in front of the body
 - The body swings through past the crutches, so the feet are ahead of the crutches