King Saud University

College of Engineering

IE – 341: “Human Factors Engineering”

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Chapter 10. Human Control of Systems Compatibility – Part II (Movement, Modality)

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Contents

Movement Compatibility

Movement Compatibility

- Cases when movement compatibility is important:
  - Movement of control device to *follow* (e.g. right) movement of display
  - Movement of control device to *control* movement of display (e.g. radio)
  - Movement of control device to produce specific system response (e.g. turning steering wheel left/right)
  - Movement of display indicator with no related response (e.g. clock)

- *Population stereotypes*:
  - This is expectation of people regarding movement relationships
  - Some stereotypes are stronger than others

- Factors affecting movement compatibility:
  - Features of controls and displays
  - Physical orientation (i.e. position) of user (e.g. is user in same/different plane than control?)

Cont. Movement Compatibility

- Principles of movement compatibility:
  1. Rotary Controls and Rotary Displays in Same Plane
  2. Rotary Controls and Linear Displays in Same Plane
  3. Movement of Displays and Controls in Different Planes
  4. Movement Relationships of Rotary Vehicular Controls
  5. Movement Relationships of Power Switches
  6. Orientation of Operator and Movement Relationships
  - Discussion

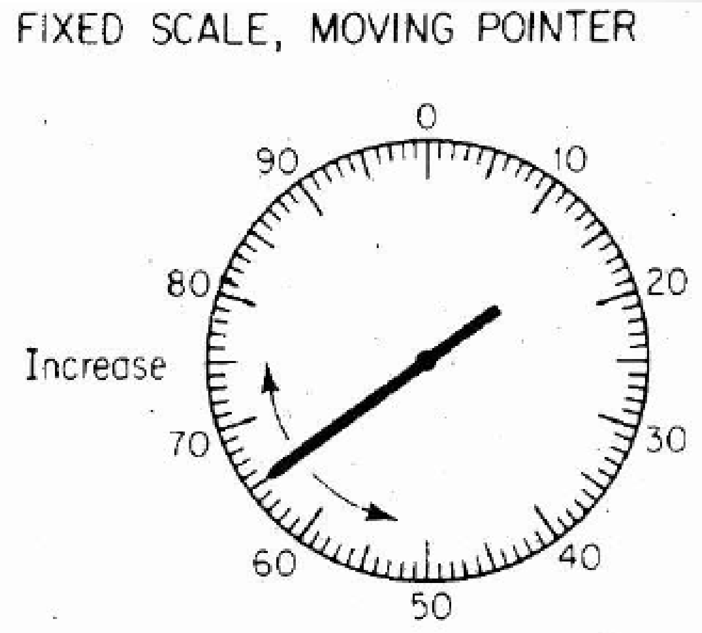
Cont. Movement Compatibility

Cont. Principles of movement compatibility:

1. Rotary Controls and Rotary Displays in Same Plane:
   A. Fixed rotary scales with moving pointers
   B. Moving scales with fixed pointers

A. Fixed rotary scales with moving pointers:

- o Well-established principles
- o CW rotation of control ⇒
  - CW rotation of pointer
  - Increase in value of variable
- o CCW rotation of control ⇒
  - CCW rotation of pointer
  - Decrease in value of variable



Cont. Movement Compatibility

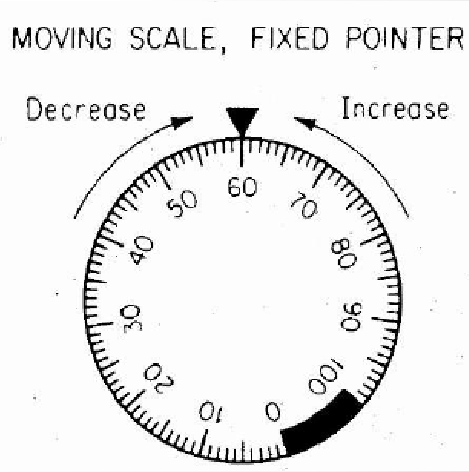
Cont. Principles of movement compatibility:

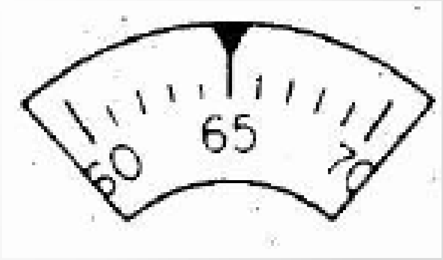
1. Rotary Controls and Rotary Displays in Same Plane:
   - A. Fixed rotary scales with moving pointers
   - B. Moving scales with fixed pointers

B. Moving scales with fixed pointers (*Bradley, 1954*):

1. Scale should rotate in same direction (AKA “direct drive”) as its knob
2. Scale numbers should increase: left to right
3. Control should turn CW to increase settings

- o Note, not possible to implement all 3 principles at the same time (in one setup)
- o Can you test this from figures on right?





Cont. Movement Compatibility

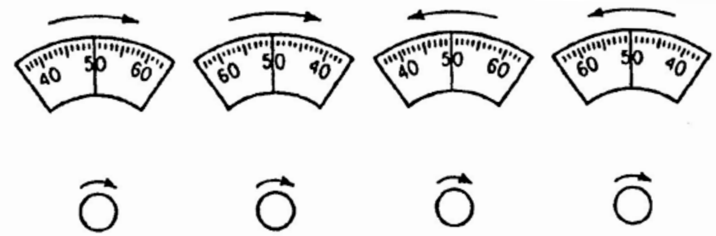
Cont. Principles of movement compatibility:

1. Rotary Controls and Rotary Displays in Same Plane:
   A. Fixed rotary scales with moving pointers
   B. Moving scales with fixed pointers

B. Moving scales with fixed pointers (*Bradley, 1954*)

- Experiment by *Bradley*: (next slide)
  - Only two principles can be achieved at the same time
  - Tested various control-display assemblies
  - Criteria:
    - starting errors (initial movement in wrong direction)
    - setting errors (incorrect settings)
    - rank-order preferences of subjects (i.e. subjective preference)
  - Results: most important principles (in desc. order of preference)
    1. Direct linkage ("drive") between control and display (A & B) (most imp)
    2. Scale numbers increase left to right
    3. CW control movement ⇒ increased setting (least imp)

Cont. Movement Compatibility



Assembly	A	B	C	D
Drive	Direct	Direct	Reversed	Reversed
Scale numbers increase	Left to right	Right to left	Left to right	Right to left
With clockwise knob movement setting will:	Decrease	Increase	Increase	Decrease

	A	B	C	D
Starting errors	13	11	87	106
Setting errors	0	9	1	8
Preference (number of times ranked "first")	31	22	17.5	1.5

FIGURE 10-5.
Some of the moving-display and control-assembly types used in a study by Bradley. The various features relate to three desirable characteristics given below the diagrams; crosshatching indicates an undesirable feature. With the usual display orientation all three desirable features are not possible. Some data on three criteria are given at the bottom of the figure, indicating the general preferability of A. (*Source: Adapted from Bradley, 1954.*)

Cont. Movement Compatibility

Cont. Principles of movement compatibility:

2. Rotary Controls and Linear Displays in Same Plane
   - o Control can be placed: above, below, to left, or to right of display

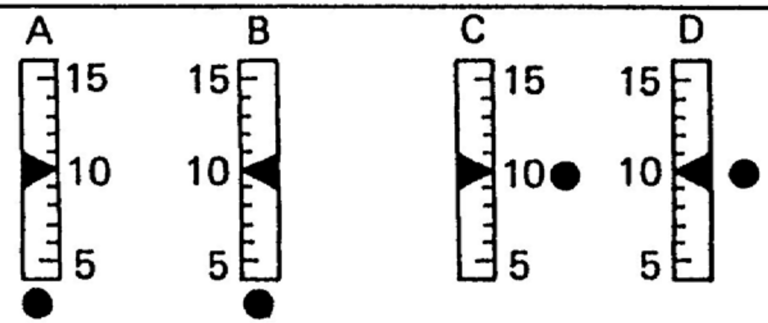
- Three Compatibility principles:
  1. ***Warrick's* principle** (*Warrick, 1947*):
     - pointer on display should move in same direction as the side of control nearest to it is
     - Note, this applies only when control is located to side of display
     - e.g. when control is on right ⇒ CW rotation will make pointer go up

  - o Two more principles (*Brebner*, 1976), specifically for vertical displays:

  2. **Scale side principle**: pointer should move in same direction as side of control knob which is on same side as scale markings on display*
     - This works when control is top / bottom / side of vertical display
  3. **Clockwise-for-increase principle**: when people turn rotary control CW ⇒ value of display increases no matter where control is (relative to display)

  - o Three principles compared on next slide (1976, 1981)

Cont. Movement Compatibility



	A	B	C	D
Predictions:				
Warrick's principle	NA	NA	C	C
Scale-side principle	CC	C	CC	C
Clockwise-for-increase	C	C	C	C
Results: Percent choosing:				
Clockwise	43 (45)	80 (72)	73 (57)	86 (85)
Counterclockwise	57 (55)	20 (28)	27 (43)	14 (15)

NA = not applicable   C = clockwise   CC= counterclockwise

FIGURE 10-6.
Four configurations of rotary controls and vertical linear scales. Shown are the predicted stereotypes based on three principles. The percentages choosing each direction of rotation to move the pointer to 15 are shown for two studies: Brebner and Sandow (1976) and, in parentheses, Petropoulos and Brebner (1981).

Cont. Movement Compatibility

Cont. Principles of movement compatibility:

3. Movement of Displays and Controls in Different Planes (i.e. 3-D device)

- Investigated types:
  - A. Rotary controls with linear displays (in different planes)
  - B. Stick-type controls with linear displays (in different planes)

A. Principles for rotary controls (*Holding,1957*):
  1. General CW for increase
  2. Helical/screwlike hand tendency for movement:*
     - CW rotation is associated with moving away from individual
     - CCW rotation is associated with moving towards individual

Cont. Movement Compatibility

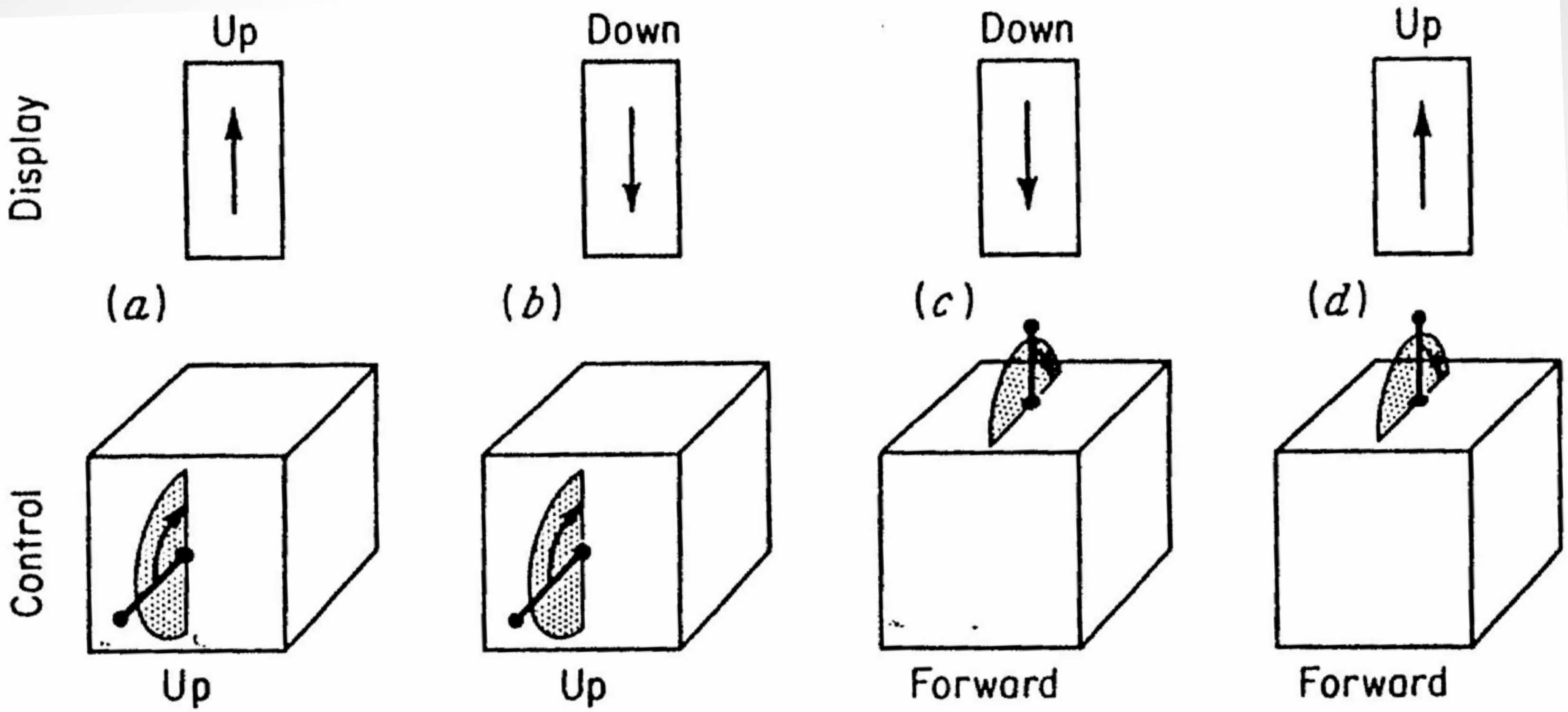
Cont. Principles of movement compatibility:

3. Cont. Movement of Displays and Controls in Different Planes (i.e. 3-D device)

B. Stick-type controls with linear displays

- Case 1: study by *Spragg, Finck, and Smith* (1959)
  - o Investigated 4 combinations of control-display movements (next slide)
  - o Involved with tracking task
  - o For horizontally mounted stick (vertical plane):
    - Up-up relationship (i.e. move control up $\Rightarrow$ display moves up): preferred
    - Up-down relationship: less preference
  - o For vertically mounted stick (horizontal plane):
    - Less difference between forward-up and forward-down relationship

Cont. Movement Compatibility



Average Tracking Score	239	149	221	227

FIGURE 10-7.
Tracking performance with horizontally mounted and vertically mounted stick controls and varying control-display relationships. (*Source: Adapted from Spragg, Finck, and Smith, 1959, data based on trials 9 to 16.*)

Cont. Movement Compatibility

Cont. Principles of movement compatibility:

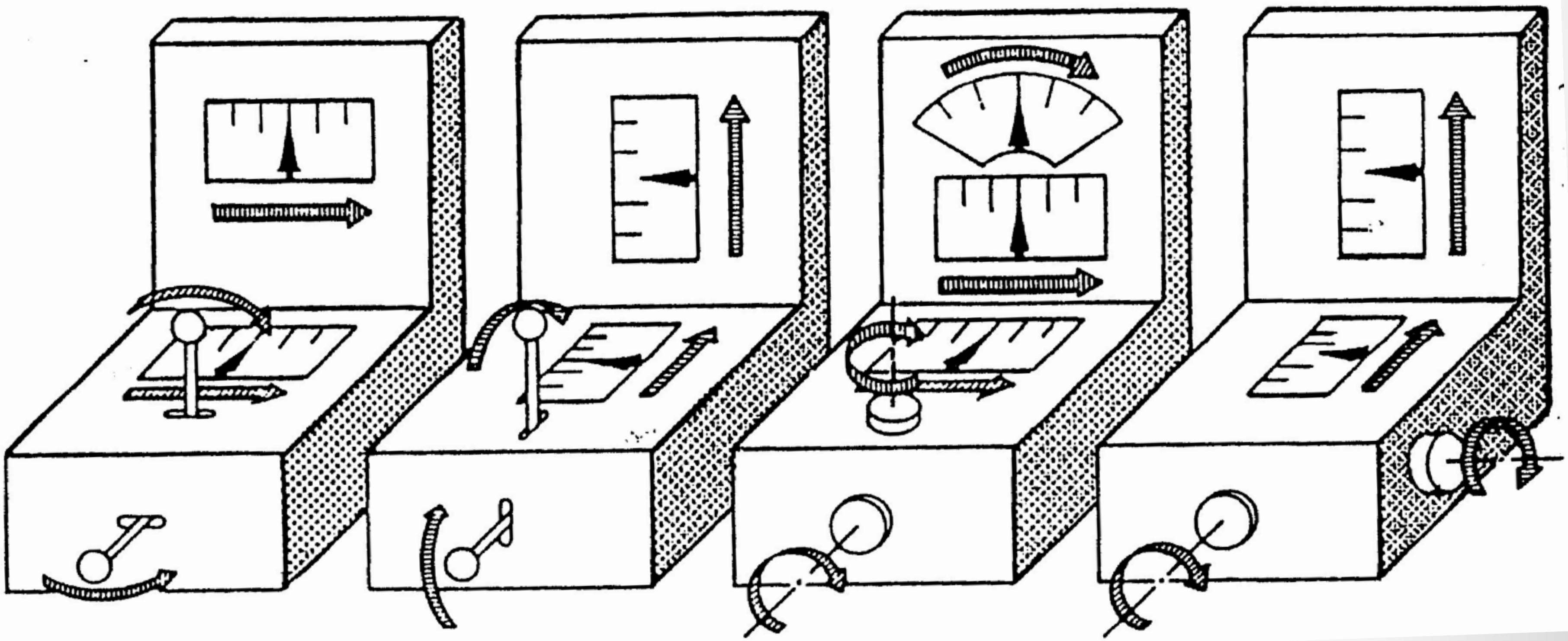
3. Cont. Movement of Displays and Controls in Different Planes (i.e. 3-D device)

B. Cont. Stick-type controls with linear displays

- Case 2: study by *Grandjean* (1988)
  - o Used results from earlier experiment
  - o Conducted experiment shown in next slide
  - o Note, Simpson (1988) found some reservations to these results:
    - When Controlling up-down movement is required e.g. drill presses, scoops
    - Stereotype: to move component up ⇒ need to move control forward
    - Another stereotype: to move component down ⇒ move control lever aft (behind)
    - Conclusion: use fore/aft control to raise/lower components (vs. up/down movements)

Cont. Movement Compatibility

FIGURE 10-8.
Recommended movement relationships for rotary and stick-type controls and linear displays located in various planes. (*Source: Grandjean, 1988, Fig. 112.*)



Cont. Movement Compatibility

Cont. Principles of movement compatibility:

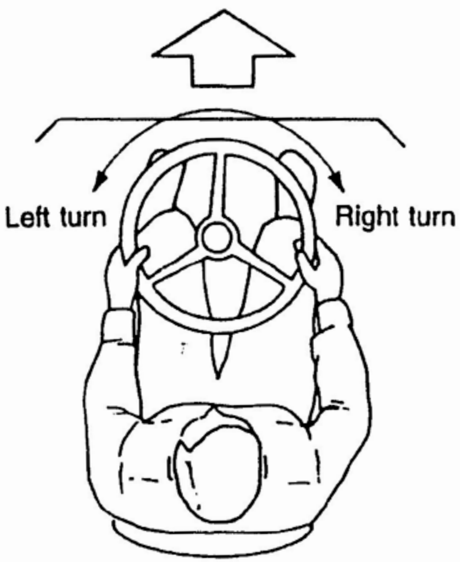
4. Movement Relationships of Rotary Vehicular Controls
   - In car, there is no “display” of system “output”
   - There is just “response” of vehicle (to control)

- Compatibility Principles
  1. If wheel is in horizontal plane ⇒ operator orients him/herself to forward point of control
  2. If wheel is in vertical plane ⇒ operator orients him/herself to top of control (see next slide)

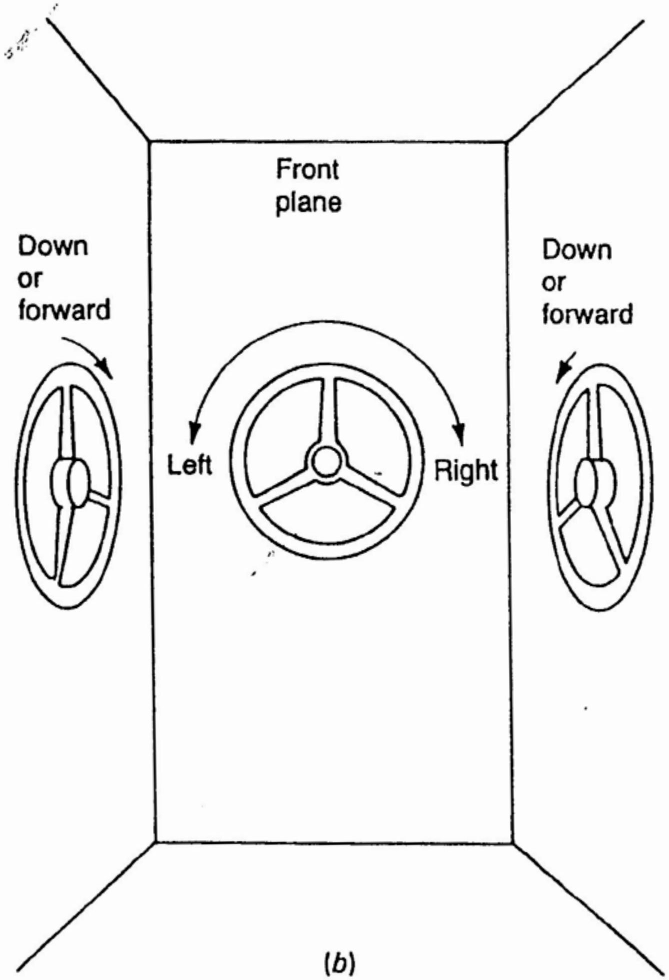
- Case study: shuttle cars for underground coal miners:
  - Control wheel exists for controlling left/right turns
  - Wheel is on **right side** of car relative to driver as car goes in one direction
  - Thus, when going in opposite direction ⇒ wheel is on driver’s left
  - Result: new drivers have significant problem learning to control cars
  - Can you suggest solution?

Cont. Movement Compatibility

FIGURE 10-9.
The most compatible relationships between the direction of movement of horizontally and vertically mounted rotary controls and the response of vehicles. (*Source: Adapted from Chapanis and Kinkade, 1972, Figs. 8-6 and 8-7.*)



(a) Horizontally mounted rotary control



(b)

Cont. Movement Compatibility

Cont. Principles of movement compatibility:

5. Movement Relationships of Power Switches
   - o US stereotype: up = on, down = off
   - o UK stereotype: opposite
   - o What about left-right operation?

- Experiment: *Lewis* (1986)
  - o Measure: %ge of subjects choosing option:
    - Up = on (97%)
    - Right = on (71%)
    - Away = on (52%)
  - o Conclusions:
    - stick with vertical power switches (as shown)
    - Other orientations are not encouraged

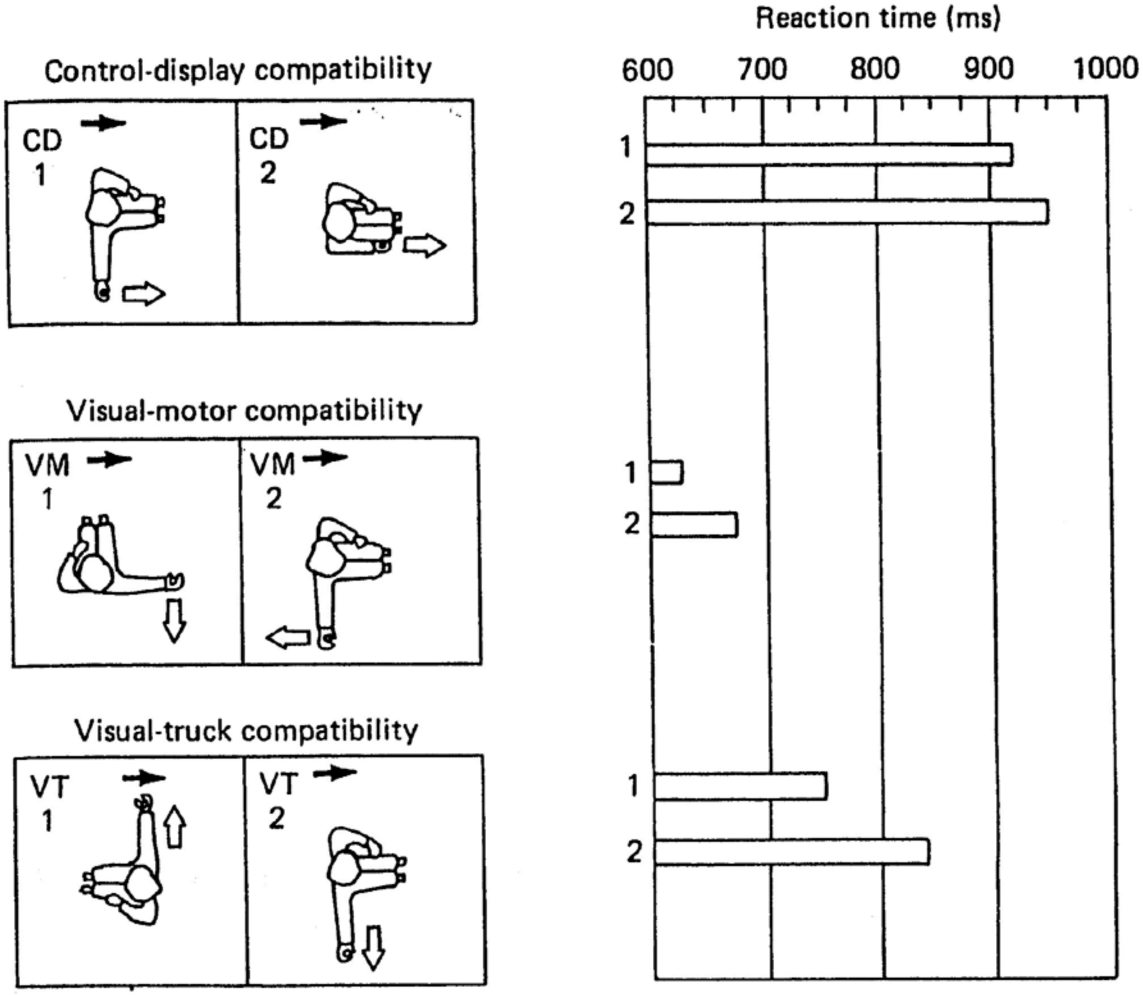
Cont. Movement Compatibility

Cont. Principles of movement compatibility:

6. Orientation of Operator and Movement Relationships
   - Previous cases: operator faces display, control in front of body
   - In some situations: operator looking at 90° or 180° angle from control
   - e.g.: adjusting car's right mirror remotely on dashboard (in front of driver) ⇒ mirror is at 90° angle to right of control

- Three principles of directional compatibility:
  - Experiments conducted by *Worringham and Beringer* (1989), next slide
  - Subjects were shown target on monitor, asked to move cursor to target using control lever
  - Measure: mean RT (to first movement)
  1. Control-display compatibility
     - Control movement in one direction ⇒ parallel movement of cursor on display, independent of operator position or orientation
     - i.e. it doesn't matter which way operator is facing

Cont. Movement Compatibility



Location of screen

Direction of arm movement for rightward cursor

FIGURE 10-10.
Relationships between direction of arm movement and cursor movement for various conditions investigated by Worringham and Beringer. See text for explanation of control-display, visual-motor, and visual-trunk compatibilities. Shown also are the mean reaction times (time to first movement) found in each situation. (*Source: Adapted from Worringham and Beringer, 1989, Fig. 2.*)

Cont. Movement Compatibility

Cont. Principles of movement compatibility:

6. Orientation of Operator and Movement Relationships

- Cont. Three principles of directional compatibility:
  1. Control-display compatibility
  2. Visual-motor compatibility
     - Direction of motion of cursor in subject's visual field while looking at display = same as direction of motor response if looking at controlling limb
     - e.g. to move cursor to right as subject looks at display ⇒ move control to right (just as if you were looking at control)
     - This compatibility produced shortest RT
  3. Visual-trunk compatibility
     - Direction of movement of cursor in subject's visual field while looking at display = same as direction of movement control relative to subject's trunk
     - e.g. to move cursor to right as subject looks at display ⇒ move control right from body centerline (regardless of head/body position)

Cont. Movement Compatibility

Cont. Principles of movement compatibility:

- Discussion
  - Clear stereotypes exist (yet not universal, and not in every case)
  - When stereotype is not present, or when principles are in conflict:
    - Designer must make decision, e.g.:
    - Design control-display relationships to match those existing in other systems already being used by intended population
    - Choose relationship that is logical/explainable (this also makes it easier to train people to use it)
  - In absence of stereotype, previous experience, and logical principle:
    - Base design decision on empirical tests of possible relationships using intended user population

Modality Compatibility

Modality Compatibility

- What modality compatibility* refers to:
  - o Some stimulus-response modality combinations: more compatible with certain tasks than others
- Study by *Wickens, Sandry, and Vidulich* (1983):
  - o Participants performed either (see next slide),
    - **Verbal** task (respond to command, "turn on radar beacon tacan**")
    - **Spatial** task (bring cursor over a specified target)
  - o Each task presented through either,
    - **Auditory** (A) modality (speech)
    - **Visual** (V) modality (display on screen)
  - o Participant responded either by,
    - **Speaking** (S) response
    - **Manually** (M) performing the command
  - o Results shown in next slide (all presentation/response modalities):
    - **RT** measured for each of the presentation/response modalities
  - o Most compatible combinations (fastest performance):
    - **Verbal** task: **A** presentation with **S** response
    - **Spatial** task: **V** presentation with **M** response
  - o Note, can you explain findings above? ***

Cont. Modality Compatibility

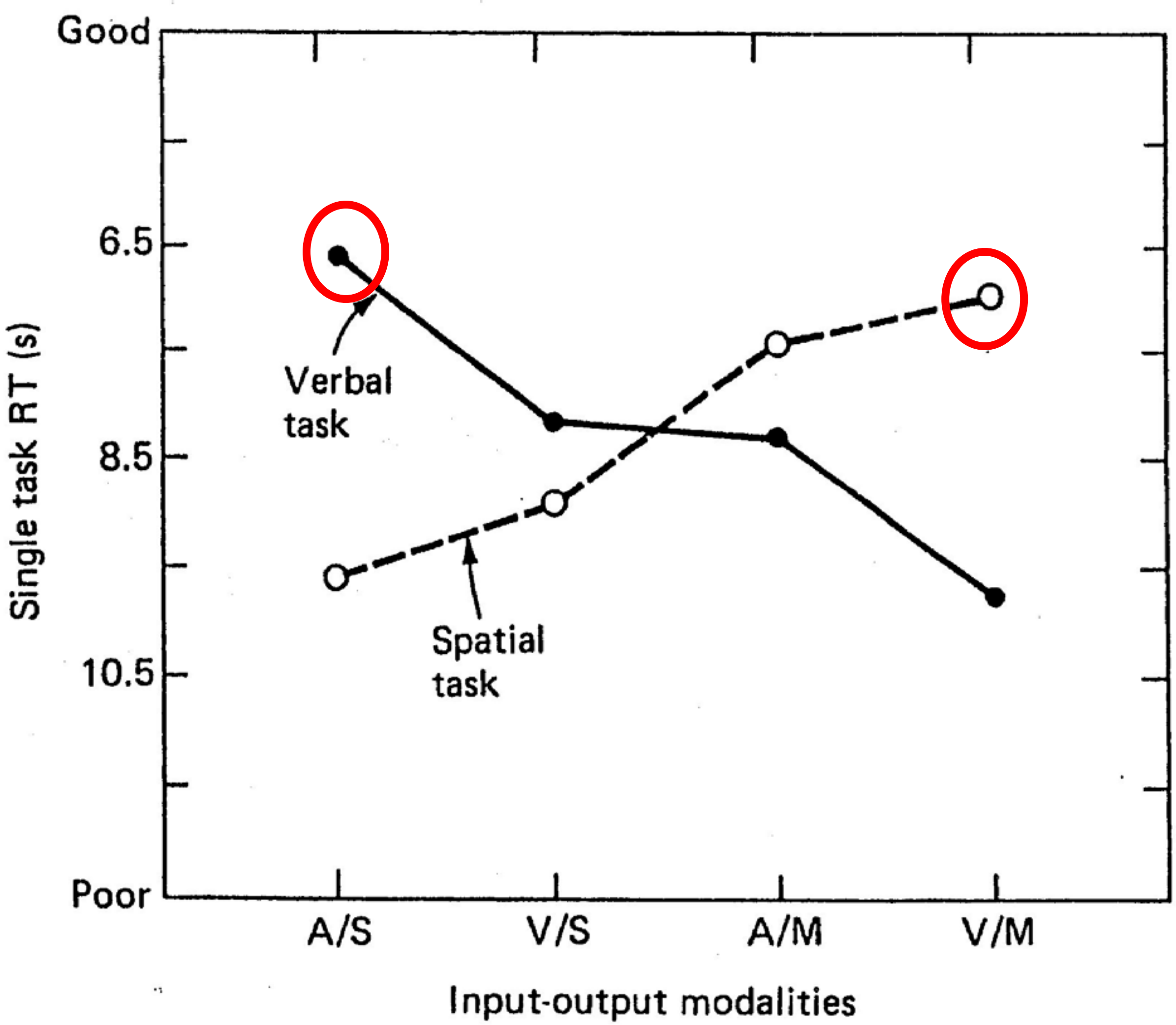


FIGURE 3-1
An example of modality compatibility. Input modality: A = auditory (speech) and V = visual (displayed on screen). Output modality: S = spoken response and M = manual response. For verbal tasks, the best input-output combination is A/S. For spatial tasks, the best combination is V/M. (*Source: Wickens, Sandry, and Vidulich, 1983, Fig. 6. Reprinted with permission of the Human Factors Society, Inc. All rights reserved.*)