

FINAL EXAMINATION, SEMESTER II: 1438-1439
DEPARTMENT OF MATHEMATICS, COLLEGE OF SCIENCE
KING SAUD UNIVERSITY
MATH: 240 FULL MARK: 40 TIME: 3 HOURS

1. (a) Decide if the vectors $\mathbf{v}_1 = (1, 0, 1, 2)$, $\mathbf{v}_2 = (2, 1, 1, 1)$ and $\mathbf{v}_3 = (1, 1, 0, -1)$ in \mathbb{R}^4 form a linearly dependent or independent set. **Marks: 4**
(b) Find the coordinate vector for $\mathbf{v} = (5, -12, 3)$ relative to the basis $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ for \mathbb{R}^3 , where $\mathbf{v}_1 = (1, 2, 3)$, $\mathbf{v}_2 = (-4, 5, 6)$, $\mathbf{v}_3 = (7, -8, 9)$. **Marks: 3**
2. Find eigenvalues and eigenvectors of the the matrix A :

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 0 \\ 1 & 3 & 1 \end{bmatrix}$$

Is the matrix diagonalizable? Explain in detail. **Marks: 2+2+3=7**

3. Check whether the vectors $\mathbf{w}_1 = (0, 2, 0)$, $\mathbf{w}_2 = (3, 0, 3)$, $\mathbf{w}_3 = (-4, 0, 4)$ form an orthogonal basis for \mathbb{R}^3 with the Euclidean inner product; if so, then use that basis to find an orthogonal basis by normalizing each vector. **Marks: 4+3=7**

4. Assume that the vector space \mathbb{R}^4 has the Euclidean inner product. Apply the Gram-Schmidt process to transform the basis vectors $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$, where $\mathbf{v}_1 = (1, 1, 1, 1)$, $\mathbf{v}_2 = (3, 1, -1, 1)$, $\mathbf{v}_3 = (1, 1, 3, 3)$ into an orthogonal basis $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$, and then normalize the orthogonal basis vectors to obtain an orthogonal basis $\{\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3\}$. **Marks: 5+2=7**

5. Find all least squares solutions of the linear system. **Marks: 4**

$$\begin{aligned} 2x_1 - 2x_2 &= 1 \\ x_1 + x_2 &= -1 \\ 2x_1 + x_2 &= 1 \end{aligned}$$

6. (a) Let

$$A = \begin{bmatrix} 1 & -1 & 3 \\ 5 & 6 & -4 \\ 7 & 4 & 2 \end{bmatrix}$$

Find the rank and nullity of T . **Marks: 2+2=4**

- (b) Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be multiplication by A , where

$$A = \begin{bmatrix} 2 & 6 & 10 \\ 0 & 1 & -1 \\ 2 & 4 & 6 \end{bmatrix}$$

Determine whether T has an inverse; if so, find $T^{-1}([x_1 \ x_2 \ x_3]^t)$. **Marks: 3+1=4**