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Simulation of Typing Process on Different Layouts with Emphasis on Distance and Motion Issues

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Abstract—A new computer simulation for a typist is described. This is unique in the sense that it is based on decisions made by the typist during the look-ahead process, takes care of hand overlapping during typing, and handles simultaneously the shifted and unshifted characters. The simulation is applied to several layouts (two of which are suggested by the authors). The results cover the classical topic of productivity and other topics discussed for the first time. These include distance traveled by the hands, number of hand motions, and alterations.

INTRODUCTION

Since its invention a century ago, Shole's QWERTY design of the typewriter keyboard has faced many challenges. Numerous physical designs were proposed to facilitate the process of typing and to increase the productivity of typists. Examples of these designs are the wipe keyboard [1], chord keyboard [2], and the K-keyboard [3].

On the other hand, it was thought that reassigning letters to keys, without changing the physical design of the Shole's keyboard, could increase the productivity (i.e., more words per minute) compared to Shole's. One of the first attempts was the Dvorak simplified keyboard (DSK). It was claimed to increase productivity by more than 30 percent because it had better hand

alterations, better finger loads, and minimum finger motions [4], [5].

For practical and economical considerations, it is difficult to retrain typists on every proposed layout till they gain adequate experience. Therefore, modeling the typing process is a reasonable alternative to evaluate the typist's performance with new layouts. It is assumed that model parameters derived from the typing process based on the Shole's layout held true for any given layout with the same physical structure.

Ramakrishna [6] suggested a one-finger typist model. But due to the absence of the effect of parallelism, his model could not predict the typist's performance using all of the ten fingers.

Kinhead [7], with the help of a computer, collected real data about keystrokes during a speed-typing test, and hence he was able to find the overall time for each key. He constructed a model using the above approach in conjunction with frequencies of possible combinations of letters to find the overall time to type a text. However, this model has drawbacks in several aspects. For instance, the effect of shift keys is neglected, no adequate analysis is made for the effect of look-ahead and overlapping, and finally, he assumed an equal reach time to reach all the keys within a row.

Gershoni *et al.* [8] used the methods-time measurement (MTM) technique to establish the overall typing time for each key and hence built a model similar to that of Kinhead's. Again this model neglected the complex effect of overlapping and look-ahead processes.

Rumelhart and Norman [12] developed a computer simulation of a skilled typist. The fact that the overall typing time was given in units of time independent of the actual time is a drawback in his model. In addition to that, the model did not take care of the combined shifted and unshifted characters. In spite of this, Norman and Fisher [9] implemented the same model to compare between a few layouts.

All of the above-mentioned models agreed that the productivity of a typist could not be improved by more than eight percent, and none of them has tackled the distance and motion issues.

In this correspondence a new computer simulation for a ten-finger typist is constructed based on decisions made by the typist during the look-ahead process. The model takes care of mixed shifted and unshifted characters, overlapping, and look-ahead effects. This model also covers the issue of productivity, in addition to the new topics of the distance traveled by the hands, the number of finger motions, and the number of hand alterations for several layouts (two of which are suggested by the authors).

THE TYPING PROCESS

The one-finger hunt and peck operation was the earliest method used in typing. To improve the speed, the touch method was developed. In the latter all of the fingers of both hands are involved. Each finger is assigned certain keys to type. The typist should not look at the keyboard, but from a home position he should know where to get the required character. At the same time, the typist should be able to return from everywhere to the home position.

Sometimes, when there is a long string to be typed, the typist will not deal with each character as a separate entity. Instead, he will look at a group of characters simultaneously with a certain look-ahead buffer width. So, it is possible that one hand is processing a character while the other hand is reaching the position of the next. Here, overlapping between the times of each character takes place, and the overall time is reduced.

In some cases, the typist may decide to stay at the current key position in order to reduce work and effort. As an example consider the case of typing the word "que". After typing "q" the left hand, due to the look-ahead process, will not go directly to

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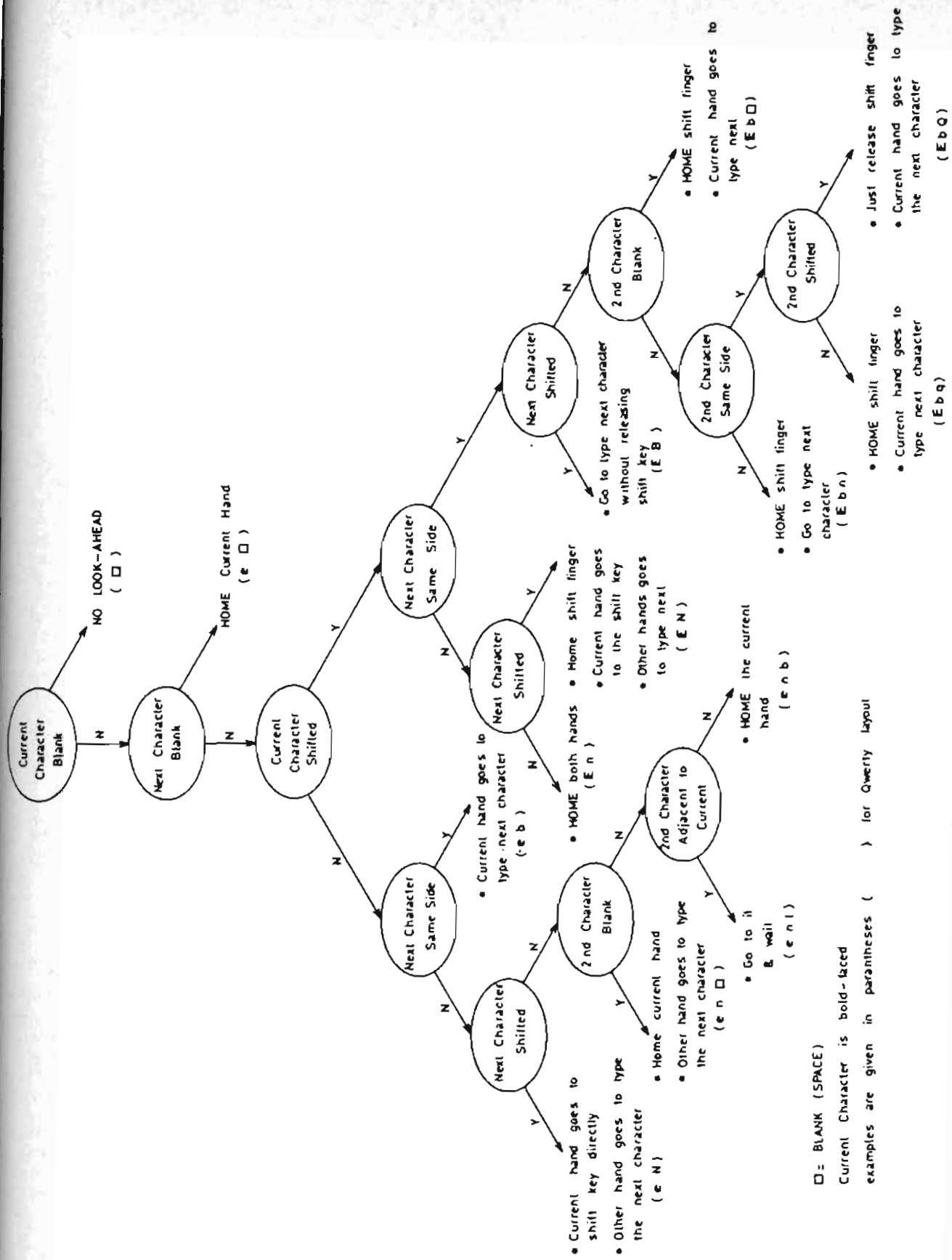
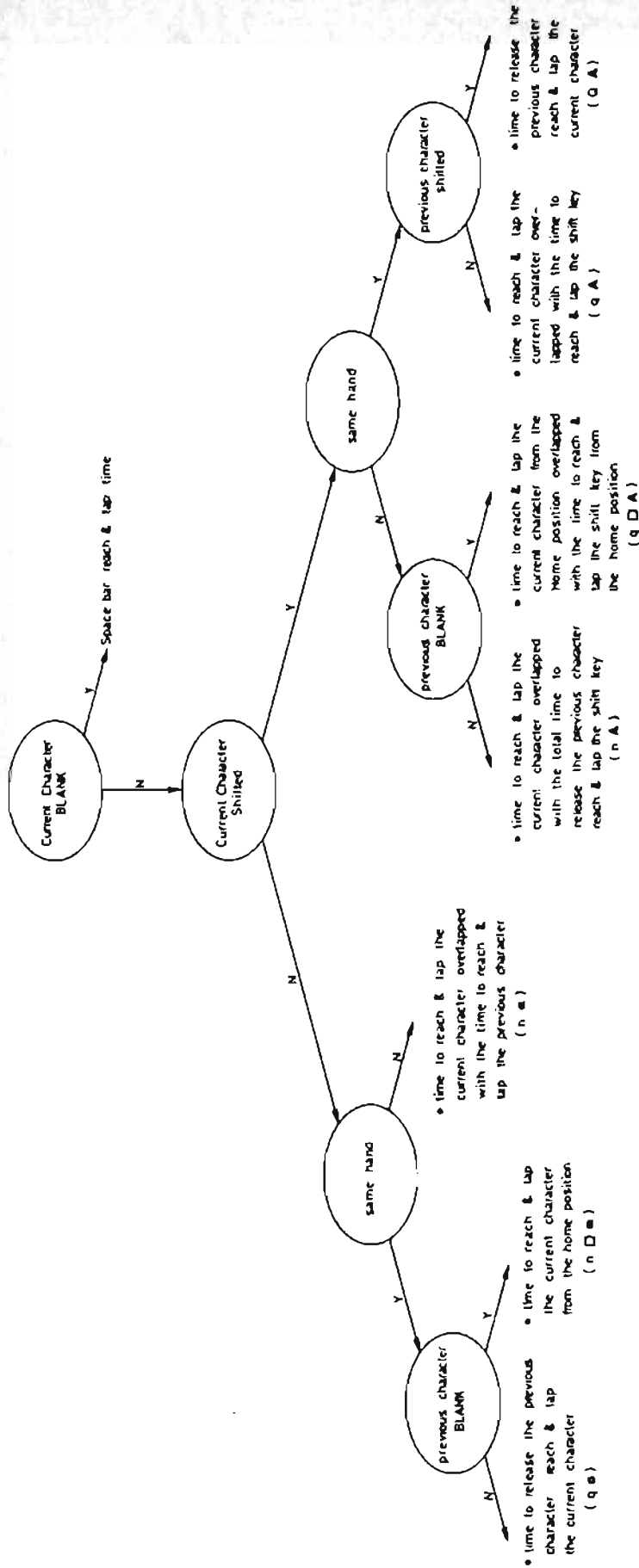


Fig. 1. Look-ahead decision process (buffer width = 2 characters).



Note- □ = BLANK (SPACE)
 Current Character is bold-faced
 Examples are given in parentheses () for Qwerty layout

Fig. 2. Reach and lap tree.

TABLE I
THE REACH-AND-TAP TIMETABLE (MILLISECONDS)

		Reach to side (Keys)					
		0	1	2	3	4	5
Rows up or down	0	136	174	192	192	216	252
	1	174	174	192	216	216	252
	2	192	192	216	216	252	306
	3	192	216	216	252	306	306

the home position. Instead it will stay until the other hand types "u", then it will proceed to type "e".

Finally, the typist might prefer to home his hand(s) whenever he encounters some complex combination of characters. This case happens for some clumsy keystrokes, like the shifted characters.

Decisions based on look-ahead taken by the typist during the typing process were observed for many typists and were found to have the structure of a binary tree (Fig. 1).

The timing of each keystroke depends on the decisions to be made by the typist about the next motion(s). Due to the overlapping and the look-ahead processes, the times of all keystrokes cannot be added in a sequential manner. Timing was also found to follow the structure of a binary tree, as shown in Fig. 2. Overlapping takes place whenever there is a hand alteration. The following formula can be used to find the next character's reach time with the overlapping effect:

$$\text{next character's reach time after overlapping} = \begin{cases} 0, & \text{if it is reached before the current key has been tapped;} \\ \text{the difference between the next and current keys reach time (without overlapping),} & \\ \text{otherwise.} & \end{cases}$$

ESTIMATION OF THE MODEL PARAMETERS

For the sake of analysis we can divide the cycle of typing a single character into three operations: reach, tap, and release the character.

The work factor method [13] and Kinkead's real data [7] were used to establish the actual time of each operation of the cycle. The combined reach and tap times for each key (excluding those at the home position), without an overlapping effect, were determined using the work factor method [13]. The time for a reach motion depends upon four variables: the body member employed, the distance moved, the manual control required to make the motion, and the resistance involved. The following is a brief description of how these major variables were obtained.

- 1) The dominant body member used in the reach motion is the finger-hand combination.
- 2) The actual distance between the keys of the Shole's layout were measured.
- 3) Manual control is required to direct the finger-hand combination toward a specific key and to terminate the motion at a definite stop. Thus, both steering and definite stop work factors are involved in the reach motion.

- 4) Since the finger-hand combination is moved for the purpose of reaching a key without resistance to overcome, no time is involved.

The tap motion is analyzed as a contact grasp motion occurring as a result of pressing a finger against a key. No time is involved in such a contact grasp, since it is actually made during the final portion of the reach motion.

Using these definitions, the combined reach and tap times for each key (without an overlapping effect) were established in milliseconds. The results are tabulated in Table I.

To complete the data for the model, Kinkead's real data [7] were used to deduce the following:

- 1) tapping time (at home position) = 136 ms,
- 2) release time = 47 ms,
- 3) space bar typing time = 155 ms.

Some manipulation of Kinkead's data is required to deduce the above values from his table.

- 1) The tapping time at the home position is obtained from the "alternate key" entry (136 ms). This is because the alternate hand will be ready to tap the next key without any reach operation.
- 2) The release time is deduced from the "same key" entry (183 ms). The typing of the same key requires two operations, releasing it and then tapping it again. Therefore it is a matter of subtraction to get the release time (47 ms).
- 3) The space bar typing time is obtained from the "space bar" entry (155 ms).

Many observations were performed to determine the look-ahead buffer width. It was taken to be two characters after the current. If a blank is within the buffer, the look-ahead is terminated at that blank.

THE MODEL IMPLEMENTATION

A program to simulate the typing process described earlier was written in PASCAL (a flowchart is shown in Fig. 3). The program was run on an HP3000 computer system.

A sample text (more than 15000 characters) was extracted from many nonscientific magazines and newspapers to ensure randomness.

The program was run to simulate the process of typing the sample text using Shole's layout. This gave the following statistics: the typing speed in gross words per minute (gw/min), finger loads for each hand, loads for each row, the average time to type

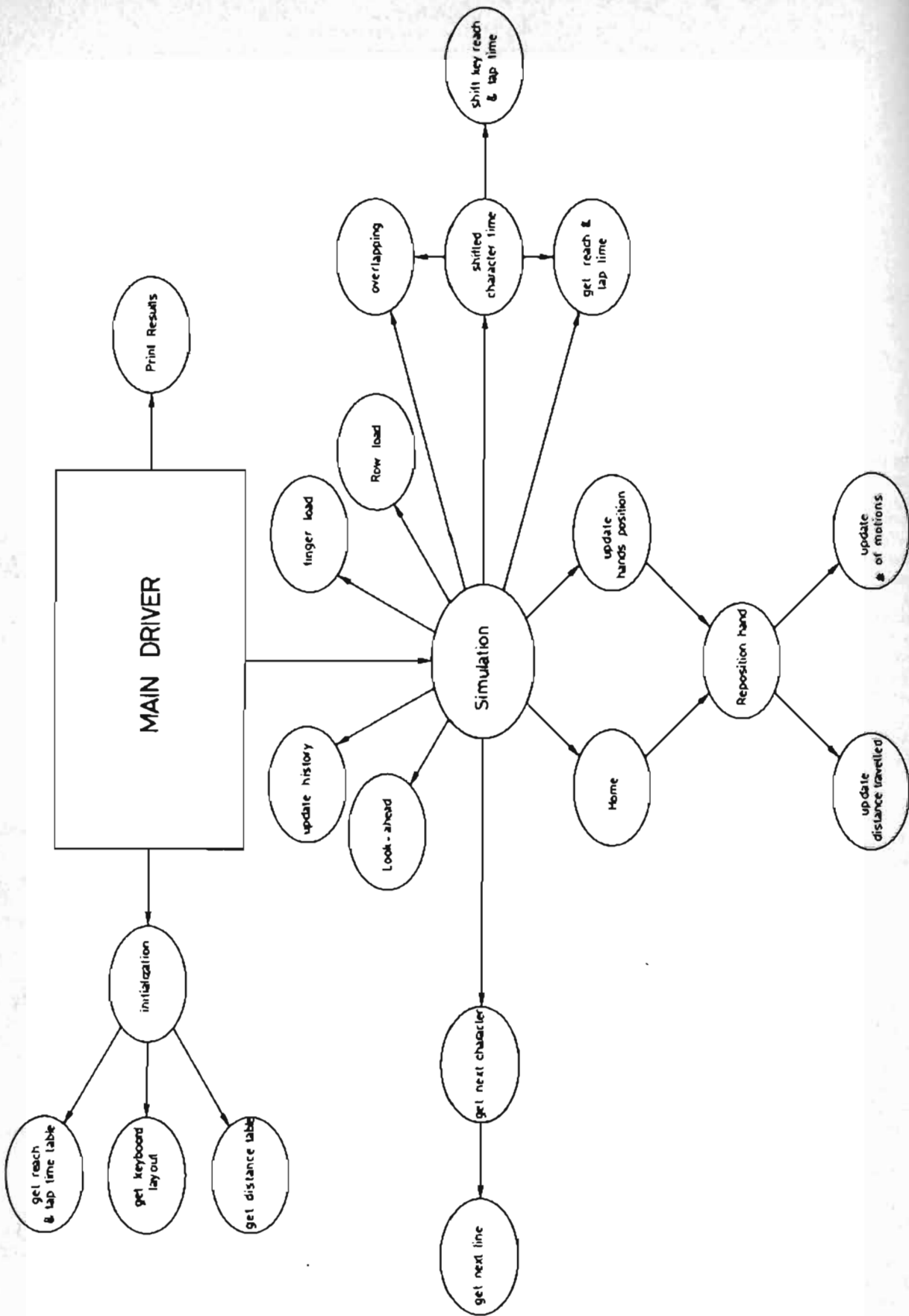


Fig. 3. Implemented programs flow diagram.

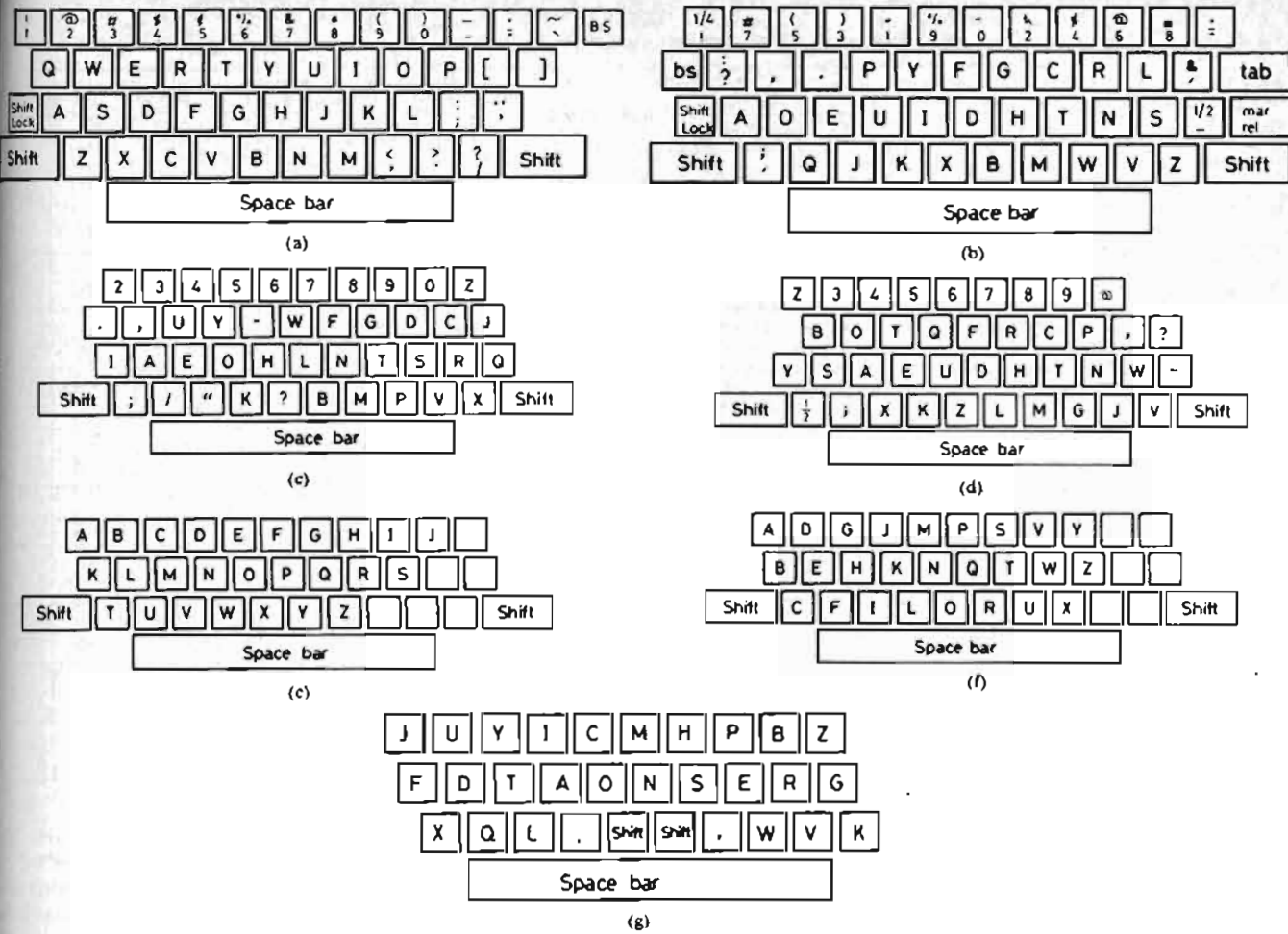


Fig. 4. (a) QWERTY layout. (b) Dvorak simplified layout. (c) Minimotion layout. (d) Rhythmic layout. (e) Horizontal layout. (f) Diagonal layout. (g) Revised QWERTY layout.

a character, and the average keystroke time. Other statistics were normalized to be independent of the text length (i.e., of the number of characters typed). These include average distance traveled per character, average distance per motion, and average length of homing. Another set of normalized data was produced: number of characters that could be typed per hand alteration, per homing, and per motion. This last group is important for later comparisons.

THE VALIDATION OF THE MODEL

To validate the implemented model, results from the model for the Shole's layout were compared to Kinkead's real data [7]. The model gave a mean time of 172.2 ms/character, and 168.2 ms/keystroke (a shifted character requires two strokes), while Kinkead's real data gave a mean of 152 ms/keystroke. It is expected that our model yields slower rates than Kinkead's data because the latter data were collected during speed tests, whereas the former reflect the productivity of an average skilled operator under normal working conditions [13].

APPLICATIONS

The program was run to evaluate different layouts using the same sample text. These layouts are the Shole (QWERTY), the Dvorak [10], the minimotion [10], the rhythmic [10], the horizontal [9], the diagonal [9], and a revised QWERTY layout [10] (see Fig. 4(a)-(g), respectively). Two new heuristic layouts, a modified Dvorak and a modified minimotion (named so after the layouts they were derived from), which were suggested by the authors and respectively shown in Fig. 5(a) and (b), were also included in the evaluation.

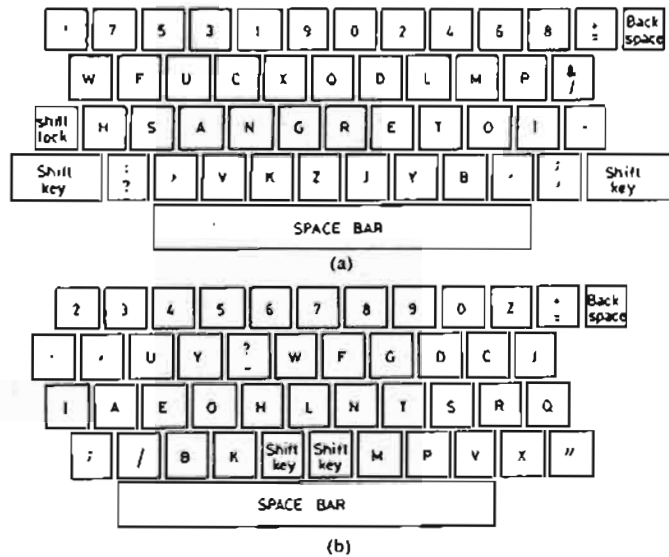


Fig. 5. (a) Modified Dvorak layout. (b) Modified minimotion layout.

DISCUSSION

The results are summarized in Table II. Some of the comparisons, such as speed and distance improvements, were done with respect to Shole's layout.

The model gave a speed of 69.7 gross words per minute (gw/min) based on five characters per word for Shole's layout (172.2 ms/character). According to the by-laws of the international contest of typing [11], this rate falls within the speed of an

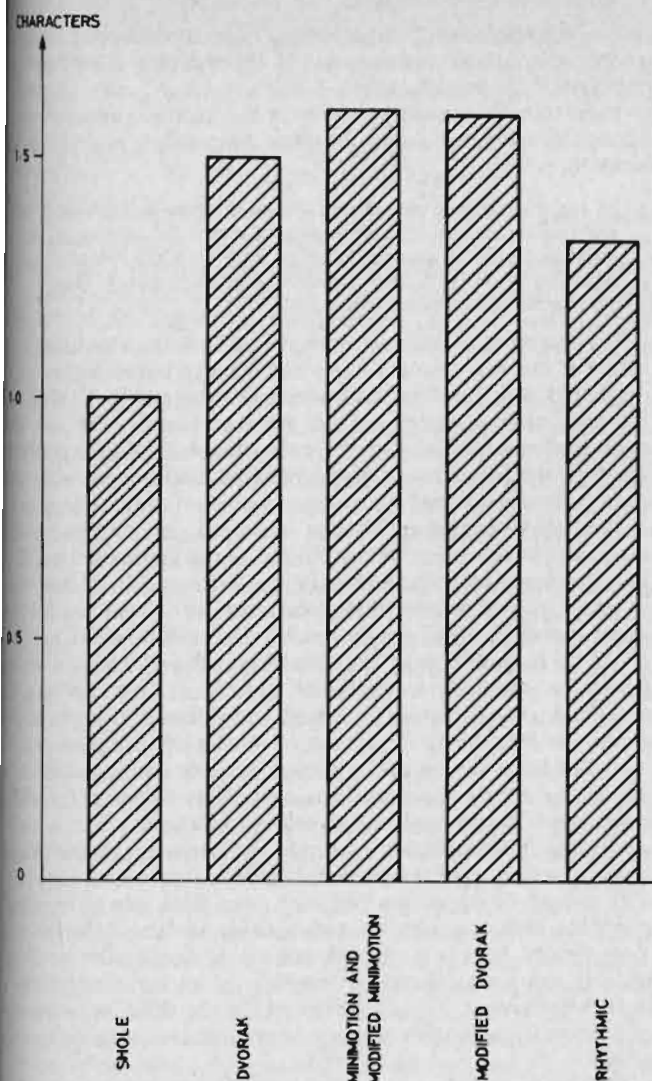


Fig. 7. Number of characters/hand motion normalized to Shole's = 1.

they encounter a clumsy combination of characters. This means that it is beneficial for layout when the number of characters typed before homing is maximized. In this respect the modified Dvorak is the best while Shole's is the worst.

CONCLUSION

The reassignment of characters to keys on the Shole's layout yields insignificant tangible improvement on typing productivity in terms of gross words per minute. However, regarding its effect on the distance traveled by the typist's fingers and the number of motions, considerable tangible improvement on typing process is realizable in terms of ease of operation and possibly less hand fatigue. This logic is an impetus for further research on new layouts.

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On Systems Theory and Models of Heat Flow

JOHN W. CHINNECK

Abstract—System-theoretic models of most physical systems have certain generic characteristics. However, models of heat flow are anomalous in several respects. The product of the through and across variables does not yield power, an inductive component does not exist, and the through variable is not measured in the usual way. A closer study of these anomalies has broad implications for the methods of systems theory in general. Among these implications are 1) for every physical phenomenon there is a variable set that provides all of the generic characteristics; 2) every physical system has an alternate formulation using energy flow rate as the "through variable;" 3) physical systems that would normally be modelled using discrete variable sets can be united in a single model; and 4) methodological advances are required in order to deal with random diffusion processes such as heat flow.

Further, some insight is gained into the effect of a macroscopic versus a microscopic viewpoint in model building.

I. INTRODUCTION

Systems theory has been applied successfully to many types of physical systems including mechanical translation, mechanical rotation, electromagnetic, and hydraulic. The system-theoretic models are based on a pair of through and across variables, so named because of the method of their measurement. Another property of the through- and across-variable pairs for physical systems is that their product yields power.

The through and across variables are used to construct component models, which can be divided into three types: dissipative (resistive elements), capacitive, and inductive. A capacitive element stores energy due to a difference in an across-variable across its terminals. An inductive element stores energy due to a flow of a through-variable through it.

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