

## Final Exam model solution

### Question 1

$$T(s) = \frac{k_p(\tau s + 1)}{(\tau_1 s + 1)(\tau_2 s + 1)} = \frac{a}{s} + \frac{b}{\tau_1 s + 1} + \frac{c}{\tau_2 s + 1}$$

$$a = \frac{k_p \tau}{\tau_1 \tau_2}$$

$$b = \frac{k_p(\tau - \tau_1)}{1 - \tau_2 / \tau_1}$$

$$c = \frac{k_p(\tau - \tau_2)}{1 - \tau_1 / \tau_2}$$

Inverting  $T(s)$  using the definition of  $a$ ,  $b$  and  $c$  yields:

$$T(t) = k_p \left[ \frac{\tau}{\tau_1 \tau_2} + \frac{\tau - \tau_1}{\tau_1 - \tau_2} e^{-t/\tau_1} + \frac{\tau - \tau_2}{\tau_2 - \tau_1} e^{-t/\tau_2} \right]$$

$$T(t) = \left[ \frac{20}{45} + \frac{17}{-12} e^{-t/3} + \frac{5}{12} e^{-t/15} \right]$$

$$\frac{\partial T}{\partial t} = \left[ \frac{17}{12 \times 3} e^{-t/3} - \frac{5}{12 \times 15} e^{-t/15} \right] = 0$$

$$\Leftrightarrow t = 10.6$$

$$T = 0.6$$

## Question 2

(a) System is unstable because of positive root

(b)

$$y(s) = \frac{\frac{k_c}{(s-1)(s+2)}}{1 + \frac{k_c}{(s-1)(s+2)}} r(s) = \frac{k_c}{(s-1)(s+2) + k_c} r(s)$$

$$y(s) = \frac{k_c}{s^2 + s - 2 + k_c} r(s) = \frac{\frac{k_c}{k_c - 2}}{\frac{1}{k_c - 2} s^2 + \frac{1}{k_c - 2} s + 1} r(s)$$

$k_c > 2$  makes the system stable

(c)

$$y(s) = \frac{\frac{k_c}{(s-1)(s+2)}}{1 + \frac{k_c k_m}{(s-1)(s+2)(\tau_m s + 1)}} r(s) = \frac{k_c (\tau_m s + 1)}{(s-1)(s+2)(\tau_m s + 1) + k_c k_m} r(s)$$

$$y(s) = \frac{2(\tau_m s + 1)}{\tau_m s^3 + (\tau_m + 1)s^2 + (1 - 2\tau_m)s + 2} r(s)$$

The characteristic equation:

$$\tau_m (s)^3 + (\tau_m + 1)(s)^2 + (1 - 2\tau_m)s + 2 = 0$$

Setting  $s=iw$  gives:

$$\tau_m (iw)^3 + (\tau_m + 1)(iw)^2 + (1 - 2\tau_m)iw + 2 = 0$$

Or

$$-\tau_m iw^3 - (\tau_m + 1)w^2 + (1 - 2\tau_m)iw + 2 = 0$$

Imaginary part gives:

$$-\tau_m w^3 + (1 - 2\tau_m)w = 0 \quad \rightarrow \quad w = \sqrt{\frac{1 - 2\tau_m}{\tau_m}} \quad (1)$$

The real part gives:

$$-(\tau_m + 1)w^2 + 2 = 0 \quad (2)$$

From the last two equations we get  $\tau_m = 0.28$

### Question 3

The close loop characteristic equation is:

$$CE = 1 + G_c(s)G_v(s)G_p(s)G_m(s)$$

$$CE = 1 + \frac{k_c(4s+1)}{(2s+1)(s+1)(0.2s+1)(0.1s+1)}$$

$$CE = (2s+1)(s+1)(0.2s+1)(0.1s+1) + k_c(4s+1)$$

$$CE = 0.04s^4 + 0.66s^3 + 2.92s^2 + (3.3 + 4k_c)s + 1 + k_c$$

$$s = iw$$

$$CE = 0 = 0.04(w)^4 - 0.66(iw)^3 - 2.92(w)^2 + (3.3 + 4k_c)iw + 1 + k_c$$

Real Part gives:

$$\Rightarrow -\omega = \sqrt{\frac{3.3 + 4k_c}{0.66}} \quad (1)$$

Imaginary part:

$$0 = 0.04(w)^4 - 2.92(w)^2 + 1 + k_c \quad (2)$$

From (1) & (2)

$$0 = 16(k_c)^2 + 19.7k_c + 5.44$$

Solving for  $K_c$  yields:

$$K_c = 0.8$$

#### Question 4

The close loop characteristic equation is:

$$CE = 1 + G_c(s)G_v(s)G_p(s)G_m(s)$$

$$CE = 1 + \frac{k_c(\tau_I s + 1)}{\tau_I s} \frac{1}{s - 1}$$

$$CE = \tau_I s(s - 1) + k_c(\tau_I s + 1)$$

$$0 = \tau_I s^2 + \tau_I(k_c - 1)s + k_c$$

$$0 = \frac{\tau_I}{k_c} s^2 + \tau_I \frac{(k_c - 1)}{k_c} s + 1$$

$$\text{For } k_c = 2 \rightarrow 0 = \frac{\tau_I}{2} s^2 + \tau_I \frac{1}{2} s + 1$$

$$\zeta = \frac{\sqrt{\tau_I/2}}{2}$$

For Over-damped systems  $\zeta > 1$

$$\Rightarrow \tau_I > 8$$