

# Modelling & Simulation of Chemical Engineering Systems

٥٠١ هـم : تمثيل الأنظمة الهندسية على الحاسب الآلي

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# LECTURE #9

## Numerical Solution of Boundary-Value Differential Equations



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# BVP Examples

- Diffusion with chemical reaction in a catalyst.

$$\frac{d^2c}{dx^2} = kc^2, \quad c(0) = c_o, \quad c(1) = c_1$$

- Diffusion or condition in a tubular reactor

$$D \frac{d^2c}{dz^2} + v \frac{dc}{dz} - kc^2 = 0, \quad c(0) = c_o, \quad dc(L)/dz = c_1$$

- Heat & mass transfer in boundary layer problems.
  - Discretization of nonlinear PDEs
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# Initial & Boundary Conditions

$$\alpha \frac{\partial^2 T}{\partial x^2} = \frac{\partial T}{\partial t}, \quad \text{Heat Conduction Equation}$$

$$\text{IC: } T = f(x) \quad \text{or} \quad T = T_0 \quad t = 0, \quad 0 \leq x \leq 1$$

*BC :*

Dirichlet BC:

$$T = f(t) \quad \text{at} \quad x = 0, \quad t > 0$$

$$T = T_2 \quad \text{at} \quad x = 1 \quad t > 0$$

*Neumann*

$$\frac{dT}{dx} = 0 \quad \text{at} \quad x = 1 \quad t > 0$$

*Cauchy* : Neumann+Dirichlet

Robbins Conditions

$$\frac{dT}{dx} = h(T - T_f) \quad \text{at} \quad x = 1 \quad t \geq 0$$

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# Numerical Methods

Shooting Method

Finite difference method

Methods of weight residuals, Collocation method

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# BVP Formulation

■ Canonical Form  $\frac{dy_j}{dx} = f_j(x, y_1, y_2, \dots, y_n) \quad x_o \leq x \leq x_f$

$$y_j(x_o) = y_{jo} \quad j = 1, 2, \dots, r$$

$$y_j(x_f) = y_{jf} \quad j = r+1, \dots, n$$

■ Original Form

$$\frac{d^2 y}{dx^2} = f\left(x, y, \frac{dy}{dx}\right) \quad x_o \leq x \leq x_f$$

$$a_o y(x_o) + b_o \frac{dy(x_o)}{dx} = \gamma_o$$

$$a_f y(x_f) + b_f \frac{dy(x_f)}{dx} = \gamma_f$$

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# Shooting Method

- An initial-value technique
  - Use successive approximation to solve for the missing initial conditions.
  - It can utilize highly efficient initial value procedure.
  - Shooting can be tried from either end of the BVP.
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# Shooting Method Algorithm

- Problem:
- Guess initial condition for  $y_2$  :
- Integrate the system forward, calculated  $y_2$  at  $x_f$  is
- Define the function

$$\begin{aligned}\frac{dy_1}{dx} &= f_1(x, y_1, y_2) & y_1(x_o) &= y_{10} \\ \frac{dy_2}{dx} &= f_2(x, y_1, y_2) & y_2(x_f) &= y_{2f}\end{aligned}$$

$$y_2(x_o) = \gamma$$

$$y_2(x_f) \Big|_{\text{calculated}} = y_2(x_f, \gamma)$$
$$\phi(\gamma) = y_2(x_f, \gamma) - y_{2f} = 0$$

- Solution : Nonlinear function need to be solved for  $\gamma$

$$\Delta \gamma = \frac{-\phi(\gamma)}{\left[ \frac{\partial \phi}{\partial \gamma} \right]} \quad \gamma_{new} = \gamma_{old} + \rho \Delta \gamma, \quad 0 < \rho \leq 1$$

# Example

- Solve the boundary-value differential equation:

$$\frac{d^2T}{dx^2} = 0.01(T - 20)^{1.4} \quad 0 \leq x \leq 10$$
$$T(0) = 200, \quad T(10) = 40$$

- Canonical Form:

$$T' = z; \quad z' = 0.01(T - 20)^{1.4}; \quad T(0) = 200;$$
$$T(10) = 40$$

Convert the BVP into IVP:

$$T' = z; \quad z' = 0.01(T - 20)^{1.4}; \quad T(0) = 200; \quad z(0) = \gamma$$

$$\Delta\gamma = \frac{-\phi(\gamma)}{\begin{bmatrix} \frac{\partial\phi}{\partial\gamma} \end{bmatrix}} \quad \gamma_{new} = \gamma_{old} + \rho\Delta\gamma, \quad 0 < \rho \leq 1$$

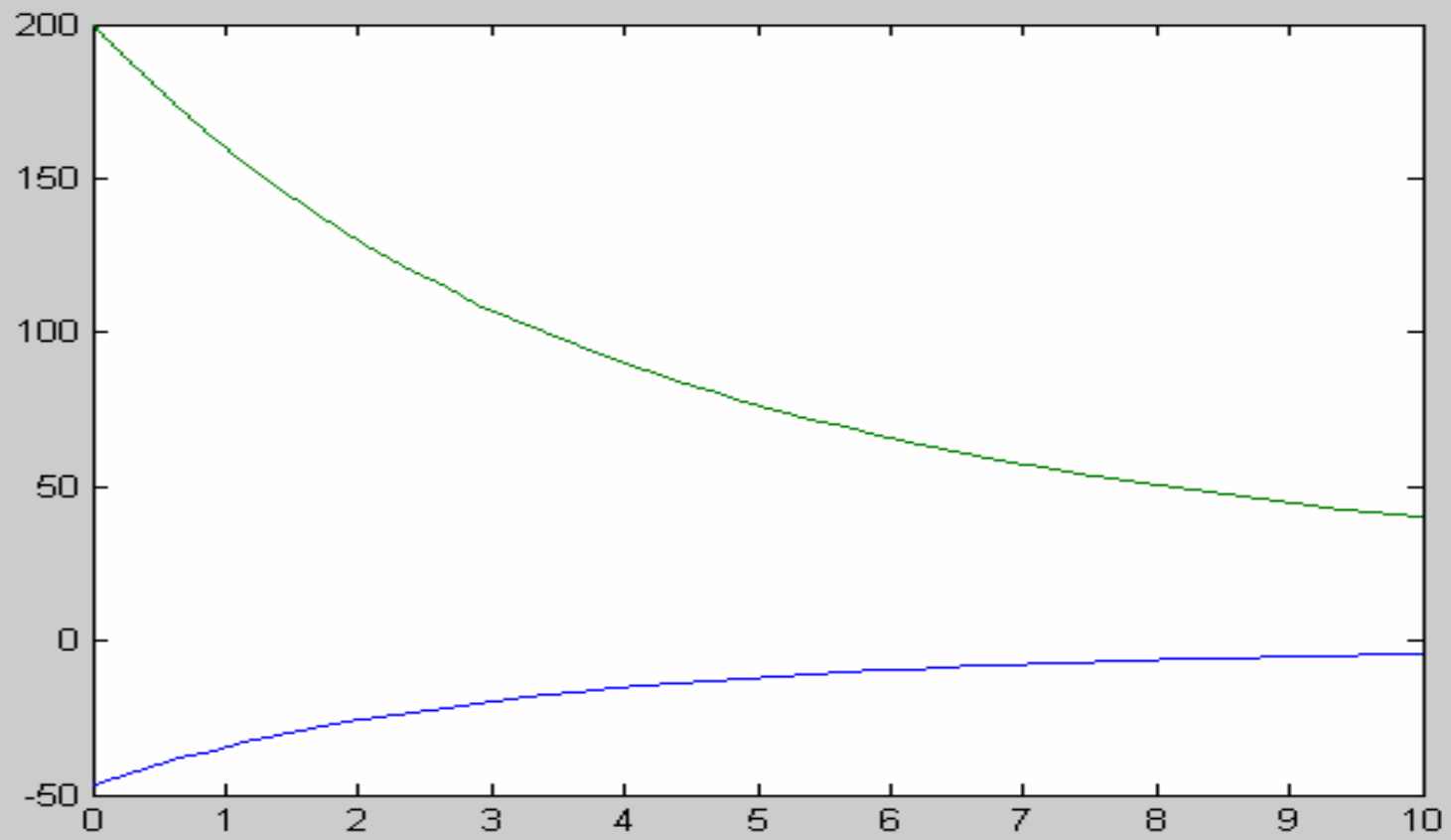
# MATLAB Code

```
% Shooting Method for BVP
%  $dT^2/dx^2=0.01(T-20)^{1.4}$ 
%  $T(0)=200$ ,  $T(10)=40$ 
%
% Canonical Form:  $T'=z$ ;  $z'=0.01(T-20)^{1.4}$ ;
% $T(0)=200$ ;  $z(0)=g1$ 
g0=20;
t0=200;
y2f_exact=40
tspan=[0 10]';
g=g0
xx0=[t0 g]';
[x,y]=ode23('bvp1', tspan, xx0);
z=size(y)
y1f_g=y(z(1),1);
delta_g=0.1
delta_y2=1.0
```

```
while delta_y2 >= 0.0001

    g=g+delta_g
    x0=[t0 g]';
    yold=y1f_g
    [x,y]=ode45('bvp1', tspan, x0);
    z=size(y)
    y1f_g=y(z(1),1)
    delta_y2=y1f_g-y2f_exact
    dif_y2=y1f_g-yold
    Der_y2_g=dif_y2/delta_g
    delta_g=-delta_y2/Der_y2_g

end
g
plot(x,y(:,2),x,y(:,1))
```



# Finite Difference Method

- Replace the derivative with finite difference approximation
- ODEs become algebraic equations

$$y' = \frac{y_{i+1} - y_i}{h} \quad \text{Forward}$$

$$y' = \frac{y_i - y_{i-1}}{h} \quad \text{Backward}$$

$$y' = \frac{y_{i+1} - y_{i-1}}{2h} \quad \text{Central}$$

$$y'' = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$

Example:

$$\frac{d^2c}{dx^2} - 2c = 0 \quad \Rightarrow \quad \frac{c(x+h) - 2c(x) + c(x-h)}{h^2} - 2c(x) = 0$$

# Example of FD method

$$\frac{d^2c}{dx^2} = 2c, \quad \left. \frac{dc}{dx} \right|_{x=0} = 0 \quad c(1) = 1$$

Let  $h=0.25$

$$\begin{array}{cccccc} 0 & 0.25 & 0.5 & 0.75 & 1 \\ \hline & & h & & \end{array}$$

$$x = 0 \quad \frac{c(0.25) - c(0)}{h} = 0 \Rightarrow c(0.25) = c(0)$$

$$x = 0.25 \quad \frac{c(0.5) - 2c(0.25) + c(0)}{0.25^2} - 2c(0.25) = 0$$

$$x = 0.5 \quad \frac{c(0.75) - 2c(0.5) + c(0.25)}{0.25^2} - 2c(0.5) = 0$$

$$x = 0.75 \quad \frac{c(1) - 2c(0.75) + c(0.5)}{0.25^2} - 2c(0.75) = 0$$

$$x = 1.0 \quad c(1) = 1$$

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$$\mathbf{c(0)=c(0.25)=0.546, c(0.5)=0.615, c(0.75)=0.760, c(1)=1}$$

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## Example: solve the BVP using FD technique

$$\frac{d^2T}{dx^2} = 0.01(T - 20)^{1.4} \quad 0 \leq x \leq 10$$

$$T(0) = 200, \quad T(10) = 40$$

$$\frac{T_{i+1} - 2T_i + T_{i-1}}{h^2} = 0.01(T_i - 20)^{1.4}$$

$$T_{i+1} - 2T_i + T_{i-1} - h^2 * 0.01(T_i - 20)^{1.4} = 0$$

```
function f=bvp_fd(t)
f(1)=t(2)-2*t(1)+200-0.01*(t(1)-20)^1.4;
for n=2:8
    f(n)=t(n+1)-2*t(n)+t(n-1)-0.01*(t(n)-20)^1.4;
end
f(9)=40-2*t(9)+t(8)-0.01*(t(9)-20)^1.4;
```

h=1

```
% Finite difference method for solving
%nonlinear BVP
% Initial conditions
% nine nodes
to=[190 180 160 140 120 100 80 60 50]
xx=[1 2 3 4 5 6 7 8 9]'
t=fsolve('bvp_fd',to)
```

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## MATLAB command

**BVP4C** Solve two-point boundary value problems for ODEs by collocation.

`SOL = BVP4C(ODEFUN,BCFUN,SOLINIT)` integrates a system of ordinary differential equations of the form  $y' = f(x,y)$  on the interval  $[a,b]$ ,

- **Example**

- `solinit = bvpinit([0 1 2 3 4],[1 0]);`

- `sol = bvp4c(@twoode,@twobc,solinit);`

- solve a BVP on the interval  $[0,4]$  with differential equations and boundary conditions computed by functions `twoode` and `twobc`, respectively.

- This example uses `[0 1 2 3 4]` as an initial mesh, and `[1 0]` as an initial

- approximation of the solution components at the mesh points.

- `xint = linspace(0,4);`

- `yint = deval(sol,xint);`

- evaluate the solution at 100 equally spaced points in  $[0 4]$ . The first component of the solution is then plotted with

- `plot(xint,yint(1,:));`

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$$\frac{d^2T}{dx^2} = 0.01(T - 20)^{1.4} \quad 0 \leq x \leq 10$$
$$T(0) = 200, \quad T(10) = 40$$

```
function dydx = ge501pvb(x,y)
dydx = [ y(2); 0.01*(y(1)-20)^1.4 ];
```

```
function res = ge501_bc(ya,yb)
res = [ ya(1)-200; yb(1)-40 ];
```

```
solin=bvpinit([0 2 4 6 8 10],[50 50]);
sol=bvp4c(@ge501pvb,@ge501_bc,solin);
xint=linspace(0,10);
yint=deval(sol,xint);
plot(xint,yint(1,:))
```

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# HW

- Solve the problem of flow of a Newtonian flow fluid in a pipe described by the equation:
- Compare the solutions obtained using the shooting method, finite difference and MATLAB bvp4c solver

$$\frac{d^2v}{dr^2} = -\frac{1}{\mu} \frac{\Delta p}{L} - \frac{1}{r} \frac{dv}{dr}$$

$$\frac{dv}{dr}(r=0) = 0, \quad v(r=R) = 0$$

$$R = 0.0025$$

$$\Delta p = 2.8 \times 10^5$$

$$\mu = 0.492$$

$$L = 4.88$$

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