

Convergence Concepts

Definition 5.8

Suppose that X_1, X_2, \dots is a sequence of random variables. We say that this sequence *converges in distribution* to a random variable X if

$$\lim_{n \rightarrow \infty} P(X_n \leq x) = P(X \leq x)$$

at all points x at which $F_X(x) = P(X \leq x)$ is continuous.

- This is quite a weak form of convergence since it only says that the distribution functions converge.

Definition 5.9

A sequence of random variables, X_1, X_2, \dots converges in probability to a random variable X if, for every $\epsilon > 0$

$$\lim_{n \rightarrow \infty} P(|X_n - X| < \epsilon) = 1$$

We will generally write this as

$$X_n \xrightarrow{p} X$$

Theorem 5.19 (Chebychev's Inequality)

Let X be a random variable and let $g(x)$ be any non-negative function then

$$P(g(X) \geq r) \leq \frac{E[g(X)]}{r}$$

Theorem 5.20 (Weak Law of Large Numbers)

Let X_1, X_2, \dots be iid random variables with $E[X_i] = \mu$ and $\text{Var}(X_i) = \sigma^2 < \infty$. Define the sample mean $\bar{X}_n = n^{-1} \sum_1^n X_i$. Then the sequence of random variables $\bar{X}_1, \bar{X}_2, \dots$ converges in probability to the constant μ . That is for every $\epsilon > 0$

$$\lim_{n \rightarrow \infty} P(|\bar{X}_n - \mu| < \epsilon) = 1$$

- Using characteristic functions we can prove that the requirement for finite variance is not needed.

Definition 5.10

Suppose that $T_n = T(X_1, \dots, X_n)$ is an estimator of a parameter θ . Then T_n is said to be a *consistent estimator* if T_n converges in probability to θ .

Theorem 5.21

Suppose that X_1, X_2, \dots converges in probability to a random variable X and that h is a continuous function. Then

$$h(X_n) \xrightarrow{p} h(X)$$

Theorem 5.22

If a sequence of random variables X_1, X_2, \dots converges in probability to a random variable X then the sequence also converges in distribution to X .

Theorem 5.23

A sequence of random variables X_1, X_2, \dots converges in probability to a constant μ if, and only if, the sequence converges in distribution to μ .

Definition 5.11

A sequence of random variables X_1, X_2, \dots *converges almost surely* to a random variable X if, for every $\epsilon > 0$,

$$P(\lim_{n \rightarrow \infty} |X_n - X| < \epsilon) = 1$$

Theorem 5.24

If a sequence of random variables X_1, X_2, \dots converges almost surely to a random variable X , it converges in probability to X also.

Theorem 5.25 (Strong Law of Large Numbers)

Let X_1, X_2, \dots be iid random variables with $E[X_i] = \mu$ and $\text{Var}(X_i) = \sigma^2 < \infty$. Define the sample mean $\bar{X}_n = n^{-1} \sum_1^n X_i$. Then the sequence of random variables $\bar{X}_1, \bar{X}_2, \dots$ converges almost surely to the constant μ . That is for every $\epsilon > 0$

$$P(\lim_{n \rightarrow \infty} |\bar{X}_n - \mu| < \epsilon) = 1$$

Theorem 5.26 (Central Limit Theorem)

Let X_1, X_2, \dots be a sequence of iid random variables with $E[X_i] = \mu$ and $\text{Var}(X_i) = \sigma^2 < \infty$. Define the sample mean $\bar{X}_n = n^{-1} \sum_1^n X_i$ and let $F_n(x)$ denote the cdf of the random variable

$$Z_n = \frac{\sqrt{n}(\bar{X}_n - \mu)}{\sigma}$$

Then for any $x \in \mathbb{R}$,

$$\lim_{n \rightarrow \infty} F_n(x) = \Phi(x) = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-z^2/2} dz$$

Theorem 5.27 (Slutsky's Theorem)

If $X_n \xrightarrow{d} X$ and $Y_n \xrightarrow{p} a$ where a is a constant then

(i) $X_n Y_n \xrightarrow{d} aX$

(ii) $X_n + Y_n \xrightarrow{d} X + a$

Theorem 5.28 (Delta Method)

Let Y_1, Y_2, \dots be a sequence of random variables such that $\sqrt{n}(Y_n - \theta)$ converges in distribution to a $\text{normal}(0, \sigma^2)$ random variable. Suppose that g is a function such that $g'(\theta)$ exists and is not 0, then

$$\sqrt{n}[g(Y_n) - g(\theta)] \xrightarrow{d} \text{normal}(0, [g'(\theta)]^2 \sigma^2)$$

Theorem 5.29 (Second Order Delta Method)

Let Y_1, Y_2, \dots be a sequence of random variables such that $\sqrt{n}(Y_n - \theta)$ converges in distribution to a $\text{normal}(0, \sigma^2)$ random variable. Suppose that g is a function such that $g'(\theta) = 0$ and $g''(\theta)$ exists and is not 0, then

$$n[g(Y_n) - g(\theta)] \xrightarrow{d} \sigma^2 \frac{g''(\theta)}{2} \chi_1^2$$

6. Principles of Data Reduction

- In statistics we use a sample X_1, \dots, X_n to make inference about a parameter θ through the use of a statistic $T(\mathbf{X})$.
- The aim of data reduction is to keep all of the relevant information in the sample through a smaller number of statistics.
- Any statistic $T(\mathbf{X})$ defines a partition of the sample space into sets

$$A_t = \{\mathbf{x} : T(\mathbf{X} = t)\}$$

- Within such a partition we treat two samples, \mathbf{x} and \mathbf{y} as equal if $T(\mathbf{x}) = T(\mathbf{y})$.

The Sufficiency Principle

- The sufficiency principle relies on the concept of a **sufficient statistic**.
- Such statistics are functions of the data which contain all of the information about the parameter of interest.

Definition 6.1

A statistic $T(x)$ is a **sufficient statistic for a parameter θ** if the conditional distribution of the sample \mathbf{X} given the value of $T(\mathbf{X})$ does not depend on θ .

The Sufficiency Principle

If $T(\mathbf{X})$ is a sufficient statistic for θ then any inference about θ should depend on the sample \mathbf{X} only through the value of $T(\mathbf{X})$.
If two sample points \mathbf{x} and \mathbf{y} have $T(\mathbf{x}) = T(\mathbf{y})$ then inference about θ should be the same whether $\mathbf{X} = \mathbf{x}$ or $\mathbf{X} = \mathbf{y}$.

Theorem 6.1

Let \mathbf{X} be a random vector with pdf or pmf $f_{\mathbf{X}}(\mathbf{x} | \theta)$ and let $T(\mathbf{X})$ be a statistic with pdf or pmf $f_T(t | \theta)$. Then $T(\mathbf{X})$ is a sufficient statistic if, for every \mathbf{x} with $f_{\mathbf{X}}(\mathbf{x} | \theta) > 0$, the ratio

$$\frac{f_{\mathbf{X}}(\mathbf{x} | \theta)}{f_T(T(\mathbf{x}) | \theta)}$$

is constant as a function of θ .

Theorem 6.2 (Factorization Criterion)

Let $f_{\mathbf{X}}(\mathbf{x} \mid \theta)$ be the joint pdf (pmf) of a sample \mathbf{X} . A statistic $T(\mathbf{X})$ is a sufficient statistic for θ if, and only if, there exist two non-negative functions $g(t, \theta)$ and $h(\mathbf{x})$ such that $h(\mathbf{x})$ is free of θ and for all sample points \mathbf{x}

$$f_{\mathbf{X}}(\mathbf{x} \mid \theta) = g(T(\mathbf{x}), \theta)h(\mathbf{x}).$$

Theorem 6.3

If X_1, \dots, X_n is a random sample from a distribution having an exponential family form

$$f(x; \boldsymbol{\theta}) = h(x)c(\boldsymbol{\theta}) \exp \left\{ \sum_{j=1}^k w_j(\boldsymbol{\theta})t_j(x) \right\}$$

Then a sufficient statistic for $\boldsymbol{\theta}$ is the vector

$$T(X_1, \dots, X_n) = \left\{ \sum_i t_1(x_i), \dots, \sum_i t_k(x_i) \right\}$$

- In general, there are many sufficient statistics available for any model.

Theorem 6.4

Any one-to-one function of a sufficient statistic is also a sufficient statistic.

Definition 6.2

*A sufficient statistic $T(\mathbf{X})$ is **minimal sufficient** if, and only if, for every other sufficient statistic $T'(\mathbf{X})$, $T(\mathbf{X})$ is a function of $T'(\mathbf{X})$.*

By saying that $T(\mathbf{X})$ is a function of $T'(\mathbf{X})$ we simply mean that if \mathbf{x} and \mathbf{y} are sample points such that $T'(\mathbf{x}) = T'(\mathbf{y})$ then $T(\mathbf{x}) = T(\mathbf{y})$.

Theorem 6.5

Let $f(\mathbf{x} | \theta)$ be the pdf of a sample \mathbf{X} and suppose that there exists a function $T(\mathbf{x})$ such that, for any two points \mathbf{x} and \mathbf{y} , the ratio $f(\mathbf{x} | \theta)/f(\mathbf{y} | \theta)$ is constant in θ if, and only if, $T(\mathbf{x}) = T(\mathbf{y})$. Then $T(\mathbf{X})$ is a minimal sufficient statistic for θ .

Definition 6.3

Suppose that \mathbf{X} is a random sample from a distribution depending on a parameter θ . A statistic $S(\mathbf{X})$ is called an *ancillary statistic* if the sampling distribution of $S(\mathbf{X})$ does not depend on θ .

Definition 6.4

Suppose $f(t | \theta)$ is the family of distributions for a statistic $T(\mathbf{X})$ indexed by the parameter θ . This family of distributions is called **complete** if

$$E_{\theta}(g(T)) = 0 \implies P_{\theta}(g(T) = 0) = 1 \text{ for every } \theta.$$

- A statistic $T(\mathbf{X})$ from a complete family of pdfs or pmfs is usually called a **complete statistic**.
- Unfortunately, it is often quite difficult to prove completeness.

Theorem 6.6

Suppose that X_1, \dots, X_n is a random sample from an exponential family with pdf or pmf given by

$$f(x | \boldsymbol{\theta}) = h(x)c(\boldsymbol{\theta}) \exp \left(\sum_{i=1}^k w_i(\boldsymbol{\theta})t_i(x) \right)$$

and further suppose that the set $\{w_1(\boldsymbol{\theta}), \dots, w_k(\boldsymbol{\theta})\}$ contains an open subset in \mathbb{R}^k .

Then the statistic

$$T(X_1, \dots, X_n) = \left\{ \sum_i t_1(x_i), \dots, \sum_i t_k(x_i) \right\}$$

is complete and minimal sufficient.

Theorem 6.7 (Bahadur's Theorem)

If a minimal sufficient statistic exists, then any complete statistic is also a minimal sufficient statistic.

Theorem 6.8 (Basu's Theorem)

If $T(\mathbf{X})$ is a complete and minimal sufficient statistic then $T(\mathbf{X})$ is independent of any ancillary statistic.