

r -Minimal submanifolds in space forms

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Abstract Let $x: M \rightarrow R^{n+p}(c)$ be an n -dimensional compact, possibly with boundary, submanifold in an $(n+p)$ -dimensional space form $R^{n+p}(c)$. Assume that r is even and $r \in \{0, 1, \dots, n-1\}$, in this paper we introduce r th mean curvature function S_r and $(r+1)$ -th mean curvature vector field \mathbf{S}_{r+1} . We call M to be an r -minimal submanifold if $\mathbf{S}_{r+1} \equiv 0$ on M , we note that the concept of 0-minimal submanifold is the concept of minimal submanifold. In this paper, we define a functional $J_r(x) = \int_M F_r(S_0, S_2, \dots, S_r) dv$ of $x: M \rightarrow R^{n+p}(c)$, by calculation of the first variational formula of J_r we show that x is a critical point of J_r if and only if x is r -minimal. Besides, we give many examples of r -minimal submanifolds in space forms. We calculate the second variational formula of J_r and prove that there exists no compact without boundary stable r -minimal submanifold with $S_r > 0$ in the unit sphere S^{n+p} . When $r = 0$, noting $S_0 = 1$, our result reduces to Simons' result: there exists no compact without boundary stable minimal submanifold in the unit sphere S^{n+p} .

Keywords r th Mean curvature function · $(r+1)$ th Mean curvature vector field · L_r operator · r -Minimal submanifold · Stability

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1 Introduction

Let $x: M \rightarrow R^{n+p}(c)$ be an n -dimensional compact, possibly with boundary, submanifold of an $(n+p)$ -dimensional space form $R^{n+p}(c)$ of constant sectional curvature c ,

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where $R^{n+p}(c)$ is Euclidean space R^{n+p} when $c = 0$, $R^{n+p}(c)$ is a unit sphere S^{n+p} when $c = 1$, and $R^{n+p}(c)$ is a hyperbolic space H^{n+p} when $c = -1$. We choose an orthonormal frame field $\{e_1, \dots, e_n, e_{n+1}, \dots, e_{n+p}\}$ along M such that $\{e_i\}_{i=1}^n$ are tangent to M and $\{e_\alpha\}_{\alpha=n+1}^{n+p}$ are normal to M , their dual frame are $\{\theta_i\}_{i=1}^n$ and $\{\theta_\alpha\}_{\alpha=n+1}^{n+p}$. If h_{ij}^α denote the components of the second fundamental form of the immersion $x: M^n \rightarrow R^{n+p}(c)$, we write

$$B_{ij} = \sum_{\alpha=n+1}^{n+p} h_{ij}^\alpha e_\alpha. \tag{1.1}$$

If i_1, \dots, i_r and j_1, \dots, j_r are integers between 1 and n , then generalized Kronecker symbols $\delta_{j_1 \dots j_r}^{i_1 \dots i_r}$ is +1 or -1 according as the i 's are distinct and the j 's are an even or odd permutation of the i 's, and is 0 in all other cases. We define the following (0, 2)-tensor T_r for $r \in \{1, \dots, n - 1\}$, (see [11, 22]):

If r is even, we set

$$T_{rj}^i = \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle, \tag{1.2}$$

we also set for a fixed index $\alpha, n + 1 \leq \alpha \leq n + p$

$$T_{r-1}^\alpha{}_{ij} = \frac{1}{(r-1)!} \sum_{\substack{i_1 \dots i_{r-1} \\ j_1 \dots j_{r-1}}} \delta_{j_1 \dots j_{r-1}}^{i_1 \dots i_{r-1}} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha \tag{1.3}$$

Then for any even integer $r \in \{0, 1, \dots, n - 1\}$, we introduce r th mean curvature function S_r and $(r + 1)$ th mean curvature vector field \mathbf{S}_{r+1} as follows:

$$\begin{aligned} S_r &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\ &= \frac{1}{r} \sum_{i, j, \alpha} T_{r-1}^\alpha{}_{ij} h_{ij}^\alpha, \end{aligned} \tag{1.4}$$

$$\begin{aligned} \mathbf{S}_{r+1} &= \frac{1}{(r+1)!} \sum_{\substack{i_1 \dots i_{r+1} \\ j_1 \dots j_{r+1}}} \delta_{j_1 \dots j_{r+1}}^{i_1 \dots i_{r+1}} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle B_{i_{r+1} j_{r+1}} \\ &= \frac{1}{r+1} \sum_{i, j, \alpha} T_{rj}^i h_{ij}^\alpha e_\alpha, \end{aligned} \tag{1.5}$$

$$S_r = \binom{n}{r} H_r, \quad \mathbf{S}_{r+1} = \binom{n}{r+1} \mathbf{H}_{r+1}, \tag{1.6}$$

where $\binom{n}{r}$ being the binomial coefficient, $\delta_{j_1 \dots j_r}^{i_1 \dots i_r}$ is the generalized Kronecker symbol. By convention, we put $H_0 = S_0 = 1$.

Motivated by the works of Barbosa–Colares in [5] about hypersurfaces in space forms, we introduce a curvature integral J_r for an n -dimensional compact submanifold

M in $R^{n+p}(c)$, r is even and $r \in \{0, 1, \dots, n - 1\}$

$$J_r = \int_M F_r(S_0, S_2, \dots, S_r) dv$$

where the function F_r are defined inductively by

$$\begin{cases} F_0 = 1 \\ F_r = S_r + \frac{(n-r+1)c}{r-1} F_{r-2}, \quad \text{for } 2 \leq r \leq n - 1. \end{cases}$$

Now we give the variational formula of J_r . In this paper, we consider only deformations which leaves ∂M strongly fixed. Of course, if M is compact and ∂M is empty, then there is no restriction on the deformation.

Theorem 1.1 (the first variational formula) *Let M be an n -dimensional compact, possibly with boundary, submanifold in an $(n + p)$ -dimensional space form $R^{n+p}(c)$. Assume that r is even and $r \in \{0, 1, \dots, n - 1\}$, then we have*

$$J_r'(t) = -(r + 1) \int_{M_t} \langle \mathbf{S}_{r+1}, V \rangle dv_{g_t}$$

where V is the variational vector field.

Definition 1.1 Let M be an n -dimensional submanifold in an $(n + p)$ -dimensional space form $R^{n+p}(c)$. Assume that r is even and $r \in \{0, 1, \dots, n - 1\}$, we call x to be r -minimal if its $(r + 1)$ -th mean curvature vector \mathbf{S}_{r+1} vanishes on M .

Definition 1.2 Assume that r is even and $r \in \{0, 1, \dots, n - 1\}$, and let M be an n -dimensional compact r -minimal submanifold in an $(n + p)$ -dimensional space form $R^{n+p}(c)$. If $J_r''(0) \geq 0$ for arbitrary variations, we call M to be stable.

In this paper we get the following generalized Takahashi theorem:

Theorem 1.2 *Let $x : M \rightarrow R^{n+p}(c)$ be an n -dimensional submanifold of an $(n + p)$ -dimensional space form $R^{n+p}(c)$. For any even integer $r \in \{0, 1, \dots, n - 1\}$, then M is r -minimal if and only if*

$$L_r x = -(n - r)cS_r x,$$

where the operator L_r is defined in Sect. 4.

Remark 1.1 From Definition 1.1, we know that concept of 0-minimal submanifolds is the concept of minimal submanifolds. When $r = 0$, $L_0 = \Delta$ is the Laplacian of M , our Theorem 1.2 reduces to Takahashi’s well-known result about minimal submanifolds (see [25]).

In [24], Simons gave an instability result for minimal submanifolds in the sphere as follows

Theorem 1.3 (Simons [24]) *There exists no compact without boundary stable minimal submanifold in the unit sphere S^{n+p} .*

In this paper, we generalize Simons’ result to r -minimal submanifolds. In fact, we prove

Theorem 1.4 *Assume that r is even and $r \in \{0, 1, \dots, n - 1\}$. If S_r is positive, then there exists no compact without boundary stable r -minimal submanifold in the unit sphere S^{n+p} .*

Remark 1.2 When $r = 0$, i.e. $S_0 = 1$, it is easy to see that our Theorem 1.4 reduces to Simons’ Theorem 1.3. When $r \geq 2$, the following Theorem 1.5 tells us that the geodesic sphere ($S_r \equiv 0$) is stable r -minimal hypersurface, thus the assumption condition $S_r > 0$ in Theorem 1.4 is necessary, thus our Theorem 1.4 is the best possible result in this sense.

Theorem 1.5 *Assume that r is even and $r \in \{1, \dots, n - 1\}$. If $S_r \geq 0$, then any compact without boundary stable r -minimal hypersurface in unit sphere S^{n+1} must be a geodesic sphere.*

This paper consists of seven sections. In Sect. 2, we first review Gauss equation, Codazzi equation and Ricci equation for submanifolds in space forms. In Sect. 3, we give the definitions of r -th mean curvature function S_r , $(r + 1)$ -th mean curvature vector \mathbf{S}_{r+1} and $(0, 2)$ -tensor T_r for submanifolds in space forms, we also give some properties of them. In Sect. 4 we introduce the L_r operator and prove the Theorem 1.2 which is the generalized Takahashi theorem. In Sect. 5 we define a curvature integral J_r on submanifolds in space forms and calculate its first variational formula, thus complete the proof of the Theorem 1.1. We also give some examples of r -minimal submanifolds in space forms. In Sect. 6 we calculate the second variational formula for r -minimal submanifolds in space forms. As an application we prove that Theorem 1.4 and Theorem 1.5 in Sect. 7.

2 Preliminaries

In this section, we give some formulas and notations of submanifolds in space forms by using the method of moving frames. Let $x: M \rightarrow R^{n+p}(c)$ be an n -dimensional submanifold of an $(n + p)$ -dimensional space form $R^{n+p}(c)$ of constant sectional curvature c . We will agree on the following index convention:

$$1 \leq i, j, k \dots \leq n; \quad n + 1 \leq \alpha, \beta, \gamma \dots \leq n + p; \quad 1 \leq A, B, C \dots \leq n + p.$$

Let $\{e_A\}$ be a local orthonormal basis for $TR^{n+p}(c)$ with dual basis $\{\theta_A\}$ such that when restricted to M , $\{e_i\}$ is a local orthonormal basis for TM and $\{e_\alpha\}$ is a local orthonormal basis for the normal bundle of $x: M \rightarrow R^{n+p}(c)$.

Then we have the structure equations (see [9])

$$dx = \sum_i \theta_i e_i, \tag{2.1}$$

$$de_i = \sum_j \theta_{ij} e_j + \sum_{\alpha, j} h_{ij}^\alpha \theta_j e_\alpha - c \theta_i x \tag{2.2}$$

$$de_\alpha = - \sum_{ij} h_{ij}^\alpha \theta_j e_i + \sum_\beta \theta_{\alpha\beta} e_\beta \tag{2.3}$$

where h_{ij}^α denote the components of the second fundamental form of M .

The Gauss equations are

$$R_{ijkl} = (\delta_{ik}\delta_{jl} - \delta_{il}\delta_{jk})c + \sum_{\alpha} (h_{ik}^{\alpha}h_{jl}^{\alpha} - h_{il}^{\alpha}h_{jk}^{\alpha}) \tag{2.4}$$

$$R_{ik} = (n - 1)c\delta_{ik} + n \sum_{\alpha} H^{\alpha}h_{ik}^{\alpha} - \sum_{\alpha,j} h_{ij}^{\alpha}h_{jk}^{\alpha} \tag{2.5}$$

$$R = n(n - 1)c + n^2H^2 - S \tag{2.6}$$

where R is the scalar curvature of M and $S = \sum_{\alpha,i,j} (h_{ij}^{\alpha})^2$ is the norm square of the second fundamental form, $\mathbb{H} = \sum_{\alpha} H^{\alpha}e_{\alpha} = \frac{1}{n} \sum_{\alpha} (\sum_i h_{ii}^{\alpha})e_{\alpha} = \frac{1}{n}S_1$ is the mean curvature vector field and $H = |\mathbb{H}|$ is the mean curvature of M .

The Codazzi equations are (see [15, 17, 18, 20])

$$h_{ijk}^{\alpha} = h_{ikj}^{\alpha} \tag{2.7}$$

where the covariant derivative of h_{ij}^{α} is defined by

$$\sum_k h_{ijk}^{\alpha}\theta_k = dh_{ij}^{\alpha} + \sum_k h_{kj}^{\alpha}\theta_{ki} + \sum_k h_{ik}^{\alpha}\theta_{kj} + \sum_{\beta} h_{ij}^{\beta}\theta_{\beta\alpha}. \tag{2.8}$$

If we denote by $R_{\alpha\beta ij}$ the curvature tensor of normal connection $\theta_{\alpha\beta}$ in the normal bundle of $x: M \rightarrow R^{n+p}(c)$, Then the Ricci equations are

$$R_{\alpha\beta ij} = \sum_k (h_{ik}^{\alpha}h_{kj}^{\beta} - h_{jk}^{\alpha}h_{ki}^{\beta}). \tag{2.9}$$

Let f be a smooth function on M , we define the first, the second covariant derivative f_i, f_{ij} and the Laplacian of f as follows

$$df = \sum_i f_i\theta_i, \quad \sum_j f_{ij}\theta_j = df_i + \sum_j f_j\theta_{ji}, \quad \Delta f = \sum_i f_{ii} \tag{2.10}$$

3 rth Mean curvature function and (r + 1)th mean curvature vector field for submanifolds in space forms

We will follow notations in the introduction and preliminaries. We recall the definition of the generalized Kronecker symbols. If i_1, \dots, i_r and j_1, \dots, j_r are integers between 1 and n , then $\delta_{j_1 \dots j_r}^{i_1 \dots i_r}$ is +1 or -1 according as the i 's are distinct and the j 's are an even or odd permutation of the i 's, and is 0 in all other cases. In fact, it easy to check that

$$\delta_{j_1 \dots j_r}^{i_1 \dots i_r} = \begin{vmatrix} \delta_{j_1}^{i_1} & \delta_{j_2}^{i_1} & \dots & \delta_{j_r}^{i_1} \\ \vdots & \vdots & \dots & \vdots \\ \delta_{j_1}^{i_r} & \delta_{j_2}^{i_r} & \dots & \delta_{j_r}^{i_r} \end{vmatrix} = \delta_{i_1 \dots i_r}^{j_1 \dots j_r}.$$

Let (M, g) be an n -dimensional submanifold in an $(n + p)$ -dimensional space form $R^{n+p}(c)$ ($c = 1, 0$ or -1 , respectively for Euclidean space R^{n+p} , unit sphere S^{n+p} or

hyperbolic space H^{n+p}) whose canonical metric will be denoted by \tilde{g} and B be the second fundamental form of M . Suppose $\{\theta_i\}$ is a local orthonormal basis for TM with dual basis $\{\theta_j\}$ and $\{e_\alpha\}$ is a local orthonormal basis for the normal bundle of $x: M^n \rightarrow R^{n+p}(c)$, (B_{ij}) is the matrix with respect to the frame $\{e_1, \dots, e_n\}$ on M . We define the following $(0, 2)$ -tensor T_r for $r \in \{1, \dots, n - 1\}$, (see [11, 22]):

If r is even, we set

$$\begin{aligned} T_r &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \theta_i \otimes \theta_j \\ &= \sum_{i, j} T_{rj}^i \theta_i \otimes \theta_j, \end{aligned}$$

that is

$$T_{rj}^i = \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle, \tag{3.1}$$

we also set

$$\begin{aligned} T_{r-1} &= \frac{1}{(r-1)!} \sum_{\substack{i_1 \dots i_{r-1} \\ j_1 \dots j_{r-1}}} \delta_{j_1 \dots j_{r-1}}^{i_1 \dots i_{r-1}} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle B_{i_{r-1} j_{r-1}} \theta_i \otimes \theta_j \\ &= \sum_{i, j, \alpha} T_{r-1}^\alpha{}_{ij} \theta_i \otimes \theta_j e_\alpha, \end{aligned}$$

that is, for a fixed index α , $n + 1 \leq \alpha \leq n + p$

$$T_{r-1}^\alpha{}_{ij} = \frac{1}{(r-1)!} \sum_{\substack{i_1 \dots i_{r-1} \\ j_1 \dots j_{r-1}}} \delta_{j_1 \dots j_{r-1}}^{i_1 \dots i_{r-1}} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha. \tag{3.2}$$

Then for any even integer $r \in \{0, 1, \dots, n - 1\}$, we introduce r th mean curvature function S_r and $(r + 1)$ th mean curvature vector field \mathbf{S}_{r+1} as follows:

$$\begin{aligned} S_r &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\ &= \frac{1}{r} \sum_{i, j, \alpha} T_{r-1}^\alpha{}_{ij} h_{ij}^\alpha, \end{aligned} \tag{3.3}$$

$$\begin{aligned} \mathbf{S}_{r+1} &= \frac{1}{(r+1)!} \sum_{\substack{i_1 \dots i_{r+1} \\ j_1 \dots j_{r+1}}} \delta_{j_1 \dots j_{r+1}}^{i_1 \dots i_{r+1}} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle B_{i_{r+1} j_{r+1}} \\ &= \frac{1}{r+1} \sum_{i, j, \alpha} T_{rj}^i h_{ij}^\alpha e_\alpha, \end{aligned} \tag{3.4}$$

$$S_r = \binom{n}{r} H_r, \quad \mathbf{S}_{r+1} = \binom{n}{r+1} \mathbf{H}_{r+1}, \tag{3.5}$$

where $\binom{n}{r}$ being the binomial coefficient, $\delta_{j_1 \dots j_r}^{i_1 \dots i_r}$ is the generalized Kronecker symbol. By convention, we put $H_0 = S_0 = 1$.

By convention $T_0 = \text{identity}$. When the codimension $p = 1$, we have the unified formula for the tensors T_r . In this case, we denote the unit normal vector to M (determined by the orientation on M) by e_{n+1} , if r is odd we replace T_r by the tensor $T_r = \tilde{g}(T_r(\cdot, \cdot), e_{n+1})$. Write $h_{ij}^{n+1} = h_{ij}$, then we have

$$\begin{aligned} T_r &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} h_{i_1 j_1} \dots h_{i_r j_r} \theta_i \otimes \theta_j \\ &= \sum_{i,j} T_{rj}^i \theta_i \otimes \theta_j. \end{aligned}$$

The following properties of T_r are fundamental

Lemma 3.1 *Let M be an n -dimensional submanifold in $R^{n+p}(c)$. Let r be even and $r \in \{0, 1, \dots, n - 1\}$. Then T_r is a symmetric and divergence-free $(0, 2)$ -tensor, that is*

$$T_{rj}^i = T_{ri}^j, \quad \sum_{i=1}^n T_{rj}^i = 0. \tag{3.6}$$

Proof By (3.1), we have the following calculation:

$$\begin{aligned} T_{rj}^i &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\ &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{i_1 \dots i_r}^{j_1 \dots j_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\ &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{j_1 i_1}, B_{j_2 i_2} \rangle \dots \langle B_{j_{r-1} i_{r-1}}, B_{j_r i_r} \rangle \\ &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\ &= T_{ri}^j, \end{aligned}$$

$$\begin{aligned} \text{div} T_r &= \sum_{i=1}^n T_{rj}^i \\ &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \{ \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \}, i \\ &= \frac{1}{(r-1)!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ i, \alpha}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha h_{i_r j_r}^\alpha \end{aligned}$$

$$\begin{aligned}
 &= \frac{1}{(r-1)!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ i_\alpha}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha h_{i_r j_r}^\alpha \\
 &\stackrel{(2)}{=} 0
 \end{aligned}$$

The equality (1) follows from the Codazzi equation (2.7), the equality (2) use the fact that the pair (i_r, i) is anti-symmetric in $\delta_{j_1 \dots j_r}^{i_1 \dots i_r}$ and is symmetric in the $h_{i_r j_r}^\alpha$. \square

Lemma 3.2 *Let M be an n -dimensional submanifold in R^{n+p} (c). Assume that r is odd and $r \in \{1, \dots, n - 1\}$. Then T_r is a symmetric and divergence-free normal-vectored value $(0, 2)$ -tensor. That is, for a fixed index α , $n + 1 \leq \alpha \leq n + p$, we have*

$$T_r^\alpha_{ij} = T_r^\alpha_{ji}; \quad \sum_{j=1}^n T_r^\alpha_{ij} = 0. \tag{3.7}$$

Proof

$$\begin{aligned}
 \sum_{j=1}^n T_r^\alpha_{ijj} &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ j}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \{ \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-2} j_{r-2}}, B_{i_{r-1} j_{r-1}} \rangle h_{i_r j_r}^\alpha \} j \\
 &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ j}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \{ (\langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-2} j_{r-2}}, B_{i_{r-1} j_{r-1}} \rangle) j h_{i_r j_r}^\alpha \\
 &\quad + \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-2} j_{r-2}}, B_{i_{r-1} j_{r-1}} \rangle h_{i_r j_r}^\alpha \} \\
 &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ j}} \{ (r-1) \delta_{j_1 \dots j_{r-1} j_r}^{i_1 \dots i_{r-1} i_r} \sum_{\beta} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-4} j_{r-4}}, B_{i_{r-3} j_{r-3}} \rangle \cdot \\
 &\quad h_{i_{r-2} j_{r-2}}^\beta h_{i_{r-1} j_{r-1}}^\beta h_{i_r j_r}^\alpha + \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-2} j_{r-2}}, B_{i_{r-1} j_{r-1}} \rangle h_{i_r j_r}^\alpha \} \\
 &= 0
 \end{aligned}$$

The last equality holds since in the first term the pair (j_{r-1}, j) is symmetric in $h_{i_{r-1} j_{r-1}}^\alpha$ according to the Codazzi equation (2.7) and is anti-symmetric in the Kronecker symbols $\delta_{j_1 \dots j_{r-1} j_r}^{i_1 \dots i_{r-1} i_r}$, thus the sums over $\{j_{r-1}, j\}$ vanish, the second term vanishes in similar reason with respect to pair (j_r, j) .

By use of similar skills as in the proof of Lemma 3.1, it is easy to verify the symmetry of $T_r^\alpha_{ij}$ for a fixed index α . \square

Now we will give the relations between the r th mean curvature functions, r th mean curvature vector fields and the tensors T_r , some of these relations are given in [11]. When the codimension is 1, the related results can be found in [1–3, 5–7, 10, 21, 23].

Lemma 3.3 *For any integer $r \in \{0, 1, \dots, n - 1\}$, when r is even, we have*

$$\text{trace}(T_r) = (n - r)S_r \tag{3.8}$$

and when r is odd, for each $n + 1 \leq \alpha \leq n + p$, we have

$$\text{trace}(T_r^\alpha) = \frac{n-r}{r} \sum_{i,j} T_{r-1j}^i h_{ij}^\alpha. \tag{3.9}$$

Proof We have by use of (3.1), (3.3) and (3.5)

$$\begin{aligned} \text{trace}(T_r) &= \sum_i T_r^i \\ &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r i}^{i_1 \dots i_r i} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\ &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ i \notin \{i_1, \dots, i_r\}}} \delta_{j_1 \dots j_r i}^{i_1 \dots i_r i} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\ &= \frac{n-r}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\ &= (n-r)S_r, \end{aligned}$$

$$\begin{aligned} \text{trace}(T_r^\alpha) &= \sum_i T_r^\alpha \\ &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r i}^{i_1 \dots i_r i} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-2} j_{r-2}}, B_{i_{r-1} j_{r-1}} \rangle h_{i_r j_r}^\alpha \\ &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ i \notin \{i_1, \dots, i_r\}}} \delta_{j_1 \dots j_r i}^{i_1 \dots i_r i} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-2} j_{r-2}}, B_{i_{r-1} j_{r-1}} \rangle h_{i_r j_r}^\alpha \\ &= \frac{n-r}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-2} j_{r-2}}, B_{i_{r-1} j_{r-1}} \rangle h_{i_r j_r}^\alpha \\ &= \frac{n-r}{r} \sum_{i,j} T_{r-1j}^i h_{ij}^\alpha. \quad \square \end{aligned}$$

Lemma 3.4 For any integer $r \in \{1, \dots, n-1\}$, when r is even, we have

$$T_{rj}^i = S_r \delta_j^i - \sum_{k,\alpha} T_{r-1kj}^\alpha h_{ki}^\alpha \tag{3.10}$$

Proof We have the following calculations

$$\begin{aligned} T_{rj}^i &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r j}^{i_1 \dots i_r i} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\ &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \left\{ \delta_j^i \delta_{j_1 \dots j_r}^{i_1 \dots i_r} - \delta_{jr}^i \delta_{j_1 \dots j_{r-1} j}^{i_1 \dots i_r} + \delta_{j_{r-1}}^i \delta_{j_1 \dots j_{r-2} j}^{i_1 \dots i_r} + \dots \right\} \\ &\quad \cdot \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \end{aligned}$$

$$\begin{aligned}
 &= S_r \delta_j^i + \frac{1}{r!} \left\{ - \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ \alpha}} \delta_{j_1 \dots j_{r-1} j}^{i_1 \dots i_{r-1} i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha h_{i_r j_r}^\alpha \right. \\
 &\quad \left. + \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ \alpha}} \delta_{j_1 \dots j_{r-2} j}^{i_1 \dots i_{r-2} i_{r-1} i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha h_{i_r j_r}^\alpha + \cdots \right\} \\
 &= S_r \delta_j^i - \frac{r}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ \alpha}} \delta_{j_1 \dots j_{r-1} j}^{i_1 \dots i_{r-1} i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha h_{i_r j_r}^\alpha \\
 &= S_r \delta_j^i - \sum_{i_r, \alpha} T_{r-1 i_r j}^\alpha h_{i_r i}^\alpha \\
 &= S_r \delta_j^i - \sum_{k, \alpha} T_{r-1 k j}^\alpha h_{k i}^\alpha. \quad \square
 \end{aligned}$$

4 L_r operator and proof of Theorem 1.2

Let $x : M \rightarrow R^{n+1}(c)$ be an n -dimensional compact without boundary hypersurface in $R^{n+1}(c)$, associated to each Newton transformation T_r of an immersion x , a second order differential operator L_r defined by (see [8, 23])

$$L_r f = \sum_{ij} T_{rj}^i f_{ij}$$

where f is any smooth function on M .

In Sect. 3, the definitions of operator T_r for submanifolds in the space form were given when r is even and r is odd, respectively, so we have the corresponding operator L_r .

- If r is even,

$$\begin{aligned}
 L_r : C^\infty(M) &\rightarrow C^\infty(M) \\
 f &\mapsto \sum_{ij} T_{rj}^i f_{ij}
 \end{aligned}$$

- If r is odd,

$$\begin{aligned}
 L_r : C^\infty(M) &\rightarrow \Gamma(T^\perp M) \\
 f &\mapsto \sum_{i,j,\alpha} T_r^\alpha f_{ij} e_\alpha
 \end{aligned}$$

where $\Gamma(T^\perp M)$ denotes the section of the normal bundle of M .

When r is odd, denote $L_r^* : \Gamma(T^\perp M) \rightarrow C^\infty(M)$ the adjoint operator of L_r above, i.e.

$$\int_M f L_r^*(\xi) dv = \int_M L_r(f) \cdot \xi dv \tag{4.1}$$

where

$$L_r^* \xi = \sum_{i,j,\alpha} T_r^{\alpha}_{ij} \xi_{\alpha,ij}, \quad \xi = \sum_{\alpha} \xi_{\alpha} e_{\alpha} \in \Gamma(T^{\perp}M) \tag{4.2}$$

$\xi_{\alpha,i}$ and $\xi_{\alpha,ij}$ are the first and the second covariant derivative of ξ defined by, respectively

$$\begin{aligned} \sum_i \xi_{\alpha,i} \theta_i &= d\xi_{\alpha} + \sum_{\beta} \xi_{\beta} \theta_{\beta\alpha} \\ \sum_j \xi_{\alpha,ij} \theta_j &= d\xi_{\alpha,i} + \sum_{\beta} \xi_{\beta,i} \theta_{\beta\alpha} + \sum_j \xi_{\alpha,j} \theta_{ji} \end{aligned}$$

Choosing $f = 1$ in (4.1), we get the integral formula

$$\int_M L_r^*(\xi) dv = 0 \tag{4.3}$$

Remark 4.1 By the Lemma 3.1, when r is even, $L_r(f) = \operatorname{div}(T_r \nabla f)$.

In order to prove Theorem 1.2, we first prove the following important lemma:

Lemma 4.1 *Let $x : M \rightarrow R^{n+p}(c)$ be an n -dimensional submanifold of an $(n + p)$ -dimensional space form $R^{n+p}(c)$. Suppose $\{e_i\}$ is a local orthonormal basis for TM and $\{e_{\alpha}\}$ is a local orthonormal basis for the normal bundle of $x : M^n \rightarrow R^{n+p}(c)$. For any integer $r \in \{0, 1, \dots, n - 1\}$, when r is even, we have*

$$L_r(x) = (r + 1)S_{r+1} - c \cdot (n - r)S_r x \tag{4.4}$$

$$L_r(e_{\alpha}) = - \sum_{i,j,k} T_{rj}^i h_{ik,j}^{\alpha} e_k - \sum_{i,j,k,\beta} T_{rj}^i h_{ik}^{\alpha} h_{kj}^{\beta} e_{\beta} + c \cdot \sum_{ij} T_{rj}^i h_{ij}^{\alpha} x. \tag{4.5}$$

Remark 4.2 When $p = 1$, above Lemma 4.1 was proved by Reilly [21] (also see Rosenberg [23], Barbosa-Colares [5] or Alencar-Rosenberg-Santos [4]).

Proof For $c = 0$, let a be a fixed vector in R^{n+p} ; when $c > 0$, let a be a fixed vector in R^{n+p+1} ; when $c < 0$, let a be a fixed vector in R_1^{n+p+1} . We define the following height functions in the a direction on M ,

$$f = \langle x, a \rangle \tag{4.6}$$

$$g_{\alpha} = \langle e_{\alpha}, a \rangle \tag{4.7}$$

for a fixed normal vector e_{α} . From the Definition (2.10) of f_i , we have by use of the structure equation (2.1)

$$f_i = \langle e_i, a \rangle. \tag{4.8}$$

From the Definition (2.10) of f_{ij} , we have by use of the structure equation (2.2)

$$f_{ij} = \sum_{\alpha} h_{ij}^{\alpha} \langle e_{\alpha}, a \rangle - c \delta_{ij} \langle x, a \rangle \tag{4.9}$$

From arbitrary property of a in (4.9), we have

$$x_{ij} = \sum_{\alpha} h_{ij}^{\alpha} e_{\alpha} - c \delta_{ij} x \tag{4.10}$$

Define the first derivative $g_{\alpha,i}$ of g_{α} by

$$\sum_i g_{\alpha,i} \theta_i = dg_{\alpha} + \sum_{\beta} g_{\beta} \theta_{\beta\alpha}. \tag{4.11}$$

We have by use of (2.3)

$$g_{\alpha,i} = - \sum_j h_{ij}^{\alpha} (e_j, a). \tag{4.12}$$

Taking covariant derivatives on both sides of (4.12) in the e_j direction, we have by use of (4.9)

$$g_{\alpha,ij} = - \sum_k h_{ikj}^{\alpha} (e_k, a) - \sum_{k,\beta} h_{ik}^{\alpha} h_{kj}^{\beta} (e_{\beta}, a) + c \cdot h_{ij}^{\alpha} (x, a). \tag{4.13}$$

where the second derivative $g_{\alpha,ij}$ of g_{α} is defined by

$$\sum_j g_{\alpha,ij} \theta_j = dg_{\alpha,i} + \sum_j g_{\alpha,j} \theta_{ji} + \sum_{\beta} g_{\beta,i} \theta_{\beta\alpha}. \tag{4.14}$$

From arbitrary property of a in (4.13), we have

$$e_{\alpha,ij} = - \sum_k h_{ikj}^{\alpha} e_k - \sum_{k,\beta} h_{ik}^{\alpha} h_{kj}^{\beta} e_{\beta} + c \cdot h_{ij}^{\alpha} x, \tag{4.15}$$

where the covariant derivative h_{ijk}^{α} of the second fundamental form h_{ij}^{α} is defined by (2.8). So we have by use of (3.4) and Lemma 3.3

$$\begin{aligned} L_r(x) &= \sum_{ij} T_{rj}^i x_{,ij} = \sum_{ij} T_{rj}^i (h_{ij}^{\alpha} e_{\alpha} - c \delta_{ij} x) \\ &= (r + 1) \mathbf{S}_{r+1} - c \cdot (n - r) S_r x, \end{aligned}$$

$$\begin{aligned} L_r(e_{\alpha}) &= \sum_{ij} T_{rj}^i e_{\alpha,ij} = \sum_{ij} T_{rj}^i \left(- \sum_k h_{ikj}^{\alpha} e_k - \sum_{k,\beta} h_{ik}^{\alpha} h_{kj}^{\beta} e_{\beta} + c \cdot h_{ij}^{\alpha} x \right) \\ &= - \sum_{ij,k} T_{rj}^i h_{ikj}^{\alpha} e_k - \sum_{ij,k,\beta} T_{rj}^i h_{ik}^{\alpha} h_{kj}^{\beta} e_{\beta} + c \cdot \sum_{ij} T_{rj}^i h_{ij}^{\alpha} x. \quad \square \end{aligned}$$

Proof of Theorem 1.2 We complete the proof of Theorem 1.2 by use of (4.4) and the definition of r -minimal submanifold.

Remark 4.3 As a direct application of (4.4), we can easily get the following integral formulas of Minkowski-Hsiung’s type.

Corollary 4.1 *M be an n -dimensional compact without boundary submanifold in an $(n + p)$ -dimensional space form $R^{n+p}(c)(c \neq 0)$, then we have for any even integer $r \in \{0, 1, \dots, n - 1\}$*

$$\int_M \{ (r + 1) \mathbf{S}_{r+1}(a) - c \cdot (n - r) S_r(x, a) \} dv = 0, \tag{4.16}$$

where a is any fixed vector in R^{n+p+1} in case $c > 0$ and in R_1^{n+p+1} in case $c < 0$.

5 The first variational formula, proof of Theorem 1.1 and some examples of r -minimal submanifolds

Let $x_0 : M \rightarrow R^{n+p}(c)$ be an n -dimensional compact, possibly with boundary, submanifold of an $(n + p)$ -dimensional space form $R^{n+p}(c)$. For each even integer $r \in \{0, 1, \dots, n - 1\}$ we define

$$J_r = \int_M F_r(S_0, S_2, \dots, S_r) dv_g \tag{5.1}$$

where function F_r are defined inductively by

$$\begin{cases} F_0 = 1 \\ F_r = S_r + \frac{(n-r+1)c}{r-1} F_{r-2}, \quad \text{for } 2 \leq r \leq n - 1. \end{cases} \tag{5.2}$$

In order to calculate the Euler–Lagrange equation of $J_r(t)$, we first calculate the derivative of $S_r(t)$ with respect to t .

Proposition 5.1 *Let M be an n -dimensional compact, possibly with boundary, submanifold in an $(n + p)$ -dimensional space form $R^{n+p}(c)$. Assume that r is even and $r \in \{0, 1, \dots, n - 1\}$, we have*

$$\begin{aligned} \frac{\partial S_r}{\partial t} &= \sum_{\alpha} L_{r-1}^*(V_{\alpha} e_{\alpha}) + \sum_i S_{r,i} V_i + c \cdot (n - r + 1) \mathfrak{S}_{r-1}(V) \\ &\quad - (r + 1) \mathfrak{S}_{r+1}(V) + S_r \mathfrak{S}_1(V), \end{aligned} \tag{5.3}$$

$$\frac{\partial}{\partial t} \int_{M_t} S_r dv_{g_t} = \int_{M_t} \langle -(r + 1) \mathfrak{S}_{r+1} + c \cdot (n - r + 1) \mathfrak{S}_{r-1}, V \rangle dv_{g_t} \tag{5.4}$$

where $V = \sum_i V_i e_i + \sum_{\alpha} V_{\alpha} e_{\alpha}$ is the variational vector field of $x_0 : M^n \rightarrow R^{n+p}(c)$, $S_{r,i}$ is the first covariant derivative of S_r in the e_i direction.

Remark 5.1 We note that (5.4) was proved by Li by a different method [16] in different settings. When $p = 1$, for any integer r , (5.3) and (5.4) were got by Reilly [21] (also see Rosenberg [23], Barbosa–Colares [5] etc.)

Let $x : M \times R \rightarrow R^{n+p}(c)$ be a smooth variation of x_0 such that $x(\cdot, t) = x_0$. Along $x : M \times R \rightarrow R^{n+p}(c)$, we choose a local orthonormal basis $\{e_A\}$ for $TR^{n+p}(c)$ with dual basis $\{\omega_A\}$, such that $\{e_i(\cdot, t)\}$ forms a local orthonormal basis for $x_t : M \times \{t\} \rightarrow R^{n+p}(c)$. Since $T^*(M \times R) = T^*M \oplus T^*R$, the pullback of $\{\omega_A\}$ and $\{\omega_{AB}\}$ on $R^{n+p}(c)$ through $x : M \times R \rightarrow R^{n+p}(c)$ have the decomposition

$$x^* \omega_{\alpha} = V_{\alpha} dt, \quad x^* \omega_i = \theta_i + V_i dt, \tag{5.5}$$

$$x^* \omega_{ij} = \theta_{ij} + a_{ij} dt, \quad x^* \omega_{i\alpha} = \theta_{i\alpha} + a_{i\alpha} dt, \quad x^* \omega_{\alpha\beta} = \theta_{\alpha\beta} + a_{\alpha\beta} dt, \tag{5.6}$$

where $\{V_i, V_\alpha, a_{ij}, a_{i\alpha}, a_{\alpha\beta}\}$ are local functions on $M \times R$ with $a_{ij} = -a_{ji}, a_{\alpha\beta} = -a_{\beta\alpha}$ and

$$V = \frac{d}{dt} \Big|_{t=0} x_t = \sum_i V_i dx_0(e_i) + \sum_\alpha V_\alpha e_\alpha, \tag{5.7}$$

is the variational vector field of $x_t: M \rightarrow R^{n+p}(c)$. We note that the one forms $\{\theta_i, \theta_{ij}, \theta_{i\alpha}, \theta_{\alpha\beta}\}$ are defined on $M \times \{t\}$, for $t = 0$, they reduce to the forms with the same notation on M .

We denote by d_M the differential operator on T^*M , then we have $d = d_M + dt \frac{\partial}{\partial t}$ on $T^*(M \times R)$.

Lemma 5.1 *Under the above notations, we have*

$$\frac{\partial \theta_i}{\partial t} = \sum_j (V_{i,j} + a_{ij}) \theta_j - \sum_{j,\alpha} h_{ij}^\alpha V_\alpha \theta_j, \tag{5.8}$$

$$a_{i\alpha} = V_{\alpha,i} + \sum_j h_{ij}^\alpha V_j, \tag{5.9}$$

$$\frac{\partial \theta_{i\alpha}}{\partial t} = \sum_j \left(a_{i\alpha,j} + \sum_k a_{ik} h_{jk}^\alpha - \sum_\beta a_{\beta\alpha} h_{ij}^\beta + c \cdot \delta_{ij} V_\alpha \right) \theta_j, \tag{5.10}$$

where h_{ij}^α and the covariant derivatives $V_{i,j}, V_{\alpha,i}$ and $a_{i\alpha,j}$ are defined on $M \times \{t\}$ by

$$\theta_{i\alpha} = \sum_j h_{ij}^\alpha \theta_j, \tag{5.11}$$

$$\sum_j V_{i,j} \theta_j = d_M V_i + \sum_j V_j \theta_{ji}, \tag{5.12}$$

$$\sum_i V_{\alpha,i} \theta_i = d_M V_\alpha + \sum_\beta V_\beta \theta_{\beta\alpha}, \tag{5.13}$$

$$\sum_j a_{i\alpha,j} \theta_j = d_M a_{i\alpha} + \sum_j a_{j\alpha} \theta_{ji} + \sum_\beta a_{i\beta} \theta_{\beta\alpha}. \tag{5.14}$$

Proof These are direct calculations. In fact, substituting (5.5) and (5.6) into the following equations, respectively

$$d(x^* \omega_i) = x^*(d\omega_i) = x^* \left(\sum_j \omega_{ij} \wedge \omega_j + \sum_\alpha \omega_{i\alpha} \wedge \omega_\alpha \right),$$

$$d(x^* \omega_\alpha) = x^*(d\omega_\alpha) = x^* \left(\sum_j \omega_{\alpha j} \wedge \omega_j + \sum_\beta \omega_{\alpha\beta} \wedge \omega_\beta \right),$$

$$d(x^* \omega_{i\alpha}) = x^*(d\omega_{i\alpha}) = x^* \left(\sum_j \omega_{ij} \wedge \omega_{j\alpha} + \sum_\beta \omega_{i\beta} \wedge \omega_{\beta\alpha} - c \cdot \omega_i \wedge \omega_\alpha \right),$$

and comparing the terms in $T^*M \wedge dt$ for each equation on the both sides, we can get (5.8), (5.9) and (5.10), respectively.

Lemma 5.2

$$\begin{aligned} \frac{\partial h_{ij}^\alpha}{\partial t} &= V_{\alpha,ij} + \sum_k \left(a_{ik} h_{kj}^\alpha + a_{jk} h_{ki}^\alpha + h_{ijk}^\alpha V_k \right) \\ &\quad + \sum_\beta a_{\alpha\beta} h_{ij}^\beta + c \cdot \delta_{ij} V_\alpha + \sum_{k,\beta} h_{ik}^\alpha h_{kj}^\beta V_\beta. \end{aligned} \tag{5.15}$$

Remark 5.2 When $p = 1$, Lemma 5.2 was proved by Barbosa–Colares [5] (see Lemma 6.1 of [5]). We note that Lemma 5.2 in case $c = 1$ can be found in [12]. Some interesting results about related variational problems for hypersurfaces in space forms can be found in Reilly [21], Rosenberg [23] and Alencar et al. [1]. We also note that Lemma 5.2 was proved by Hu–Li in [15] for any n -dimensional compact submanifolds in an $(n + p)$ -dimensional Riemannian manifold N^{n+p} .

Proof Differentiating (5.11) with respect to t and using (5.8), (5.10) we get

$$\begin{aligned} \frac{\partial h_{ij}^\alpha}{\partial t} &= a_{i\alpha,j} + \sum_k a_{ik} h_{jk}^\alpha - \sum_\beta a_{\beta\alpha} h_{ij}^\beta + c \cdot \delta_{ij} V_\alpha \\ &\quad - \sum_k \left(h_{ik}^\alpha V_{k,j} + h_{ik}^\alpha a_{kj} \right) + \sum_{k,\beta} h_{ik}^\alpha h_{kj}^\beta V_\beta. \end{aligned}$$

Covariant differentiating (5.9) over $M \times \{t\}$ and using the Codazzi equation (2.7) for $x_t: M \rightarrow R^{n+p}(c)$, we get

$$\begin{aligned} a_{i\alpha,j} &= V_{\alpha,ij} + \sum_k \left(V_{k,j} h_{ik}^\alpha + V_k h_{ikj}^\alpha \right) \\ &= V_{\alpha,ij} + \sum_k \left(V_{k,j} h_{ik}^\alpha + V_k h_{ijk}^\alpha \right). \end{aligned}$$

Combining the above two equations, we prove Lemma 5.2.

Let $x_0: M \rightarrow R^{n+p}(c)$ be an n -dimensional submanifold in an $(n + p)$ -dimensional space form $R^{n+p}(c)$. Suppose $r \in \{0, 1, \dots, n\}$, the definition of S_r for each even integer r is given in (1.4) or (3.3), then we have the following lemma

Lemma 5.3 $S_{r,k} = \sum_{i,j,\alpha} T_{r-1ij}^\alpha h_{ijk}^\alpha$ for a fixed index k .

Proof

$$\begin{aligned} S_{r,k} &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{i_1 \dots i_r}^{j_1 \dots j_r} (\langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle)_k \\ &= \frac{1}{(r-1)!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{i_1 \dots i_r}^{j_1 \dots j_r} (B_{i_1 j_1}, B_{i_2 j_2}) \cdots (B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}}) h_{i_{r-1} j_{r-1}}^\alpha h_{i_r j_r k}^\alpha \\ &= \sum_{i_r, j_r, \alpha} T_{r-1 i_r j_r}^\alpha h_{i_r j_r k}^\alpha \\ &= \sum_{i,j,\alpha} T_{r-1 ij}^\alpha h_{ijk}^\alpha \end{aligned}$$

□

Proof of Theorem 5.1 From (1.4) and (5.15), we have

$$\begin{aligned}
 \frac{\partial S_r}{\partial t} &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \frac{\partial}{\partial t} (\langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle) \\
 &= \frac{r}{2} \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ \alpha}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle \left(\frac{\partial h_{i_{r-1} j_{r-1}}^\alpha}{\partial t} h_{i_r j_r}^\alpha + h_{i_{r-1} j_{r-1}}^\alpha \frac{\partial h_{i_r j_r}^\alpha}{\partial t} \right) \\
 &= r \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r \\ \alpha}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha \frac{\partial h_{i_r j_r}^\alpha}{\partial t} \\
 &= \frac{1}{(r-1)!} \sum_{\substack{i_1 \dots i_{r-1} i \\ j_1 \dots j_{r-1} j \\ \alpha}} \delta_{j_1 \dots j_{r-1} j}^{i_1 \dots i_{r-1} i} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha \frac{\partial h_{ij}^\alpha}{\partial t} \\
 &= \sum_{i,j,\alpha} T_{r-1}^\alpha{}_{ij} \frac{\partial h_{ij}^\alpha}{\partial t} \\
 &= \sum_{i,j,\alpha} T_{r-1}^\alpha{}_{ij} \left[V_{\alpha,ij} + \sum_k (a_{ik} h_{kj}^\alpha + a_{jk} h_{ki}^\alpha + h_{ijk}^\alpha V_k) + \sum_{k,\beta} h_{ik}^\alpha h_{kj}^\beta V_\beta \right. \\
 &\quad \left. + c \cdot \delta_{ij} V_\alpha + \sum_\beta a_{\alpha\beta} h_{ij}^\beta \right]. \tag{5.16}
 \end{aligned}$$

We are now in a position to compute the terms in the right-hand side of (5.16) one by one.

$$\begin{aligned}
 \sum_{i,j,k,\alpha} T_{r-1}^\alpha{}_{ij} (a_{ik} h_{kj}^\alpha + a_{jk} h_{ki}^\alpha) &= 2 \sum_{i,j,k,\alpha} T_{r-1}^\alpha{}_{ij} h_{kj}^\alpha a_{ik} \\
 &\stackrel{(1)}{=} 2 \sum_{i,k} (S_r \delta_k^i - T_{rk}^i) a_{ik} \\
 &= 0 \tag{5.17}
 \end{aligned}$$

where equality (1) from (3.10) and the last equality of (5.17) from fact $a_{ik} = -a_{ki}$ and $T_{rk}^i = T_{ri}^k$.

We have by use of (3.10), (3.4) and (3.9)

$$\begin{aligned}
 \sum_{\alpha,\beta} \sum_{i,j,k} T_{r-1}^\alpha{}_{ij} h_{ik}^\alpha h_{kj}^\beta V_\beta &= \sum_\beta \sum_{j,k} (S_r \delta_j^k - T_{rj}^k) h_{kj}^\beta V_\beta \\
 &= n \sum_\beta S_r H^\beta V_\beta - \sum_{i,j,\beta} T_{rj}^i h_{ij}^\beta V_\beta \\
 &= S_r \mathfrak{S}_1(V) - (r+1) \mathfrak{S}_{r+1}(V), \tag{5.18}
 \end{aligned}$$

$$\begin{aligned}
 c \cdot \sum_{i,j,\alpha} T_{r-1}^\alpha{}_{ij} \delta_{ij} V_\alpha &= c \cdot \sum_i T_{r-1}^\alpha{}_{ii} V_\alpha \\
 &= c \cdot \sum_{i,j,\alpha} \frac{n-r+1}{r-1} T_{r-2}^j h_{ij}^\alpha V_\alpha \\
 &= c \cdot (n-r+1) \mathfrak{S}_{r-1}(V).
 \end{aligned}
 \tag{5.19}$$

We have by use of (3.2) and $a_{\alpha\beta} = -a_{\beta\alpha}$

$$\begin{aligned}
 &\sum_{\alpha,\beta} \sum_{i,j} T_{r-1}^\alpha{}_{ij} h_{ij}^\beta a_{\alpha\beta} \\
 &= \frac{1}{(r-1)!} \sum_{\substack{i_1 \dots i_{r-1} \\ j_1 \dots j_{r-1} \\ \alpha,\beta}} \delta_{j_1 \dots j_{r-1} i_1}^{i_1 \dots i_{r-1} i_1} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha h_{ij}^\beta a_{\alpha\beta} \\
 &= \frac{1}{(r-1)!} \sum_{\substack{i_1 \dots i_{r-1} \\ j_1 \dots j_{r-1} \\ \alpha,\beta}} \delta_{j_1 \dots j_{r-1} i_1}^{i_1 \dots i_{r-1} i_1} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{ij}^\alpha h_{i_{r-1} j_{r-1}}^\beta a_{\alpha\beta} \\
 &= 0.
 \end{aligned}
 \tag{5.20}$$

Putting (5.17), (5.18), (5.19) and (5.20) into (5.16), we get (5.3) by use Lemma 5.3 and (4.2).

By use of (5.8), we have

Lemma 5.4

$$\frac{\partial}{\partial t} dv_{g_t} = \frac{\partial}{\partial t} (\theta_1 \wedge \cdots \wedge \theta_n) = \sum_i V_{i,i} dv_{g_t} - \langle \mathbf{S}_1, V \rangle dv_{g_t}.
 \tag{5.21}$$

Combining (5.3) with (5.21), we can get (5.4) by use of (4.3). So we complete the proof of Proposition 5.1.

Proof of Theorem 1.1 We prove Theorem 1.1 by inductive method. From Lemma 5.4, we know that Theorem 1.1 is true for $r = 0$. Now we suppose that Theorem 1.1 is true for $r = k - 2$ and $k - 2$ is even, then we have

$$J_{k-2}'(t) = -(k-1) \int_{M_t} \langle \mathbf{S}_{k-1}, V \rangle dv_{g_t}.
 \tag{5.22}$$

By use of (5.4) and (5.22), the following calculation shows us that Theorem 1.1 is true for $r = k = \text{even}$

$$\begin{aligned}
 J_k'(t) &= \frac{d}{dt} \int_{M_t} F_k dv_{g_t} = \frac{d}{dt} \int_{M_t} \left(S_k + \frac{(n-k+1)c}{k-1} F_{k-2} \right) dv_{g_t} \\
 &= \int_{M_t} \langle -(k+1) \mathbf{S}_{k+1} + (n-k+1)c \mathbf{S}_{k-1}, V \rangle dv_{g_t} \\
 &\quad + \frac{(n-k+1)c}{k-1} [-(k-1) \int_M \langle \mathbf{S}_{k-1}, V \rangle dv_{g_t}] \\
 &= -(k+1) \int_{M_t} \langle \mathbf{S}_{k+1}, V \rangle dv_{g_t}.
 \end{aligned}
 \tag{5.23}$$

Thus we complete the proof of Theorem 1.1.

From Theorem 1.1, we know that $J'_r(0) = 0$ if and only if $\mathbf{S}_{r+1} \equiv 0$ on M , which leads us to the following definition.

Definition 5.1 Let M be an n -dimensional submanifold in $R^{n+p}(c)$. Assume that r is even and $r \in \{0, 1, \dots, n - 1\}$, we call M to be an r -minimal submanifold if the $(r + 1)$ th mean curvature vector $\mathbf{S}_{r+1} \equiv 0$ on M .

Remark 5.3 When $p = 1$, let $x_0: M \rightarrow R^{n+1}(c)$ be an n -dimensional compact hypersurface in $R^{n+1}(c)$, Barbosa–Colares [5] (also see [1, 3]) considered the variational problem keeping the balance of volume for any integer r .

Now we would like to present a family of examples of r -minimal submanifolds in space form. For convenience we assume that r is any even integer and $r \in \{0, 1, \dots, n - 1\}$ in the following examples.

Example 5.1 Totally geodesic submanifolds in space form are r -minimal.

Example 5.2 Let C^{n+p} be a (complex) $(n + p)$ -dimensional Euclidean space, assume $x: M \rightarrow C^{n+p}$ is a Kähler submanifold of (complex) dimension n . Then M is r -minimal.

Proof Let $e_A = \{e_1, \dots, e_{n+p}; e_{1^*} = Je_1, \dots, e_{n+p}^* = Je_{n+p}\}$ be a local orthonormal basis for C^{n+p} . We make use the notation of $e_{(A^*)^*} = -e_A, \delta_{A^*C} = -\delta_{AC^*}$ and the indices range convention $A, C, A^*, C^* = 1, \dots, n + p, 1^*, \dots, (n + p)^*$.

We can choose e_A such that, restricted to M , $\{e_1, \dots, e_n; e_{1^*} = Je_1, \dots, e_n^* = Je_n\}$ is a local orthonormal basis for TM . We further use the following convention on the range of indices:

$$\alpha, \beta, \alpha^*, \beta^* = n + 1, \dots, n + p, (n + 1)^*, \dots, (n + p)^*.$$

Then the second fundamental form $B_{A^*C^*}$ and B_{AC} of the immersion x have the following relations (see [15])

$$\begin{aligned} B_{A^*C^*} &= B(e_{A^*}, e_{C^*}) = \sum_{\alpha} (h_{A^*C^*}^{\alpha} e_{\alpha} + h_{A^*C^*}^{\alpha^*} e_{\alpha^*}) \\ &= \sum_{\alpha} (-h_{AC}^{\alpha} e_{\alpha} - h_{AC}^{\alpha^*} e_{\alpha^*}) = -B_{AC}. \end{aligned}$$

Since $\delta_{A^*C^*} = \langle e_{A^*}, e_{C^*} \rangle = \langle Je_A, Je_C \rangle = \langle e_A, e_C \rangle = \delta_{AC}$, by the definition of the generalized Kronecker symbols $\delta_{C_1 \dots C_{r+1}}^{A_1 \dots A_{r+1}}$ in Sect. 3, we have $\delta_{C_1 \dots C_{r+1}}^{A_1 \dots A_{r+1}} = \delta_{C_1^* \dots C_{r+1}^*}^{A_1^* \dots A_{r+1}^*}$.

For any fixed index A_1, \dots, A_r, A , we have

$$\begin{aligned} &\delta_{C_1^* \dots C_r^* C^*}^{A_1^* \dots A_r^* A^*} \langle B_{A_1^* C_1^*}, B_{A_2^* C_2^*} \rangle \cdots \langle B_{A_{r-1}^* C_{r-1}^*}, B_{A_r^* C_r^*} \rangle B_{A^* C^*} \\ &= \delta_{C_1 \dots C_r C}^{A_1 \dots A_r A} \langle -B_{A_1 C_1}, -B_{A_2 C_2} \rangle \cdots \langle -B_{A_{r-1} C_{r-1}}, -B_{A_r C_r} \rangle (-B_{AC}) \\ &= -\delta_{C_1 \dots C_r C}^{A_1 \dots A_r A} \langle B_{A_1 C_1}, B_{A_2 C_2} \rangle \cdots \langle B_{A_{r-1} C_{r-1}}, B_{A_r C_r} \rangle B_{AC} \end{aligned}$$

Thus

$$\begin{aligned}
 \mathbf{S}_{r+1} &= \frac{1}{(r+1)!} \sum_{\substack{A_1 \dots A_r A \\ C_1 \dots C_r C}} \delta_{C_1 \dots C_r C}^{A_1 \dots A_r A} \langle B_{A_1 C_1}, B_{A_2 C_2} \rangle \cdots \langle B_{A_{r-1} C_{r-1}}, B_{A_r C_r} \rangle B_{AC} \\
 &= \frac{1}{(r+1)!} \sum_{\substack{A_1^* \dots A_r^* A^* \\ C_1^* \dots C_r^* C^*}} \delta_{C_1^* \dots C_r^* C^*}^{A_1^* \dots A_r^* A^*} \langle B_{A_1^* C_1^*}, B_{A_2^* C_2^*} \rangle \cdots \langle B_{A_{r-1}^* C_{r-1}^*}, B_{A_r^* C_r^*} \rangle B_{A^* C^*} \\
 &= -\frac{1}{(r+1)!} \sum_{\substack{A_1 \dots A_r A \\ C_1 \dots C_r C}} \delta_{C_1 \dots C_r C}^{A_1 \dots A_r A} \langle B_{A_1 C_1}, B_{A_2 C_2} \rangle \cdots \langle B_{A_{r-1} C_{r-1}}, B_{A_r C_r} \rangle B_{AC} \\
 &= 0
 \end{aligned}$$

Thus $x: M^n \rightarrow C^{n+p}$ is r -minimal. □

Example 5.3 Let $M^n(k)$ and $N^{n+p}(c)$ be n -dimensional and $(n+p)$ -dimensional space forms with constant sectional curvature k and c , respectively. If the immersion $x: M^n(k) \rightarrow N^{n+p}(c)$ is minimal, then x is r -minimal.

Proof By the minimal condition, we have $\sum_i B_{ii} = 0$.

In the present case, from (2.4) we get the Gauss equation

$$\langle B_{ik}, B_{jl} \rangle - \langle B_{il}, B_{jk} \rangle = (k - c)(\delta_{ik}\delta_{jl} - \delta_{il}\delta_{jk})$$

Thus we have

$$\begin{aligned}
 \mathbf{S}_{r+1} &= \frac{1}{(r+1)!} \sum_{\substack{i_1 \dots i_r i \\ j_1 \dots j_r j}} \delta_{j_1 \dots j_r j}^{i_1 \dots i_r i} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle B_{ij} \\
 &= \frac{1}{(r+1)!} \cdot \frac{1}{2^{\frac{r}{2}}} \sum_{\substack{i_1 \dots i_r i \\ j_1 \dots j_r j}} \delta_{j_1 \dots j_r j}^{i_1 \dots i_r i} (\langle B_{i_1 j_1}, B_{i_2 j_2} \rangle - \langle B_{i_1 j_2}, B_{i_2 j_1} \rangle) \cdots (\langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\
 &\quad - \langle B_{i_{r-1} j_r}, B_{i_r j_{r-1}} \rangle) B_{ij} \\
 &= \frac{1}{(r+1)!} \cdot \frac{1}{2^{\frac{r}{2}}} \cdot (k - c)^{\frac{r}{2}} \sum_{\substack{i_1 \dots i_r i \\ j_1 \dots j_r j}} \delta_{j_1 \dots j_r j}^{i_1 \dots i_r i} (\delta_{i_1 j_1} \delta_{i_2 j_2} - \delta_{i_1 j_2} \delta_{i_2 j_1}) \cdots (\delta_{i_{r-1} j_{r-1}} \delta_{i_r j_r} \\
 &\quad - \delta_{i_{r-1} j_r} \delta_{i_r j_{r-1}}) B_{ij} \\
 &= \frac{(k - c)^{\frac{r}{2}}}{(r+1)!} \sum_{\substack{i_1 \dots i_r i \\ j_1 \dots j_r j}} \delta_{j_1 \dots j_r j}^{i_1 \dots i_r i} \delta_{i_1 j_1} \delta_{i_2 j_2} \cdots \delta_{i_{r-1} j_{r-1}} \delta_{i_r j_r} B_{ij} \\
 &= \frac{(k - c)^{\frac{r}{2}}}{(r+1)!} (n - r)(n - r + 1) \cdots (n - 1) \sum_{ij} \delta_{ij} B_{ij} \\
 &= \frac{(k - c)^{\frac{r}{2}}}{(r+1)!} (n - r)(n - r + 1) \cdots (n - 1) \sum_i B_{ii} \\
 &= 0
 \end{aligned}$$

□

Remark 5.4 In particular, the submanifold $x : S^n \left(\sqrt{\frac{2(n+1)}{n}} \right) \rightarrow S^{n+p}(1)$ with $p = \frac{1}{2}(n - 1)(n + 2)$ is r -minimal. (see [13])

Example 5.4 $M_r = S^1 \left(\sqrt{\frac{r+1}{n}} \right) \times S^{n-1} \left(\sqrt{\frac{n-r-1}{n}} \right) \rightarrow S^{n+1}(1)$ is r -minimal. Among these r -minimal hypersurfaces, the only minimal hypersurface is the case with $r = 0$.

Proof Suppose $M_r = S^1(a) \times S^{n-1}(b)$ is an n -dimensional compact r -minimal hypersurface in S^{n+1} , then $a^2 + b^2 = 1$.

Assume that two distinct principal curvatures of M_r are λ (multiplicity 1) and μ (multiplicity $n - 1$). Then (see [13]) we have

$$1 + \lambda\mu = 0. \tag{5.24}$$

By the condition of r -minimal, we have $\binom{n-1}{r}\lambda\mu^{r-1} + \binom{n-1}{r+1}\mu^r = 0$, i.e.

$$(1 + r)\lambda + (n - r - 1)\mu = 0 \tag{5.25}$$

We have by combining (5.24) and (5.25)

$$\lambda = \sqrt{\frac{n - r - 1}{r + 1}}, \quad \mu = -\sqrt{\frac{r + 1}{n - r - 1}}.$$

Then

$$a^2 = \frac{1}{1 + \lambda^2} = \frac{r + 1}{n}, \quad b^2 = \frac{1}{1 + \mu^2} = \frac{n - r - 1}{n},$$

$$M_r = S^1 \left(\sqrt{\frac{r + 1}{n}} \right) \times S^{n-1} \left(\sqrt{\frac{n - r - 1}{n}} \right).$$

If M_r is minimal, we have

$$nH = \sqrt{\frac{n - r - 1}{r + 1}} - (n - 1)\sqrt{\frac{r + 1}{n - r - 1}} = 0.$$

We obtain $r = 0$. □

Example 5.5 $C_{n,n} = S^n(\frac{1}{\sqrt{2}}) \times S^n(\frac{1}{\sqrt{2}}) \rightarrow S^{2n+1}(1)$ is r -minimal.

We all know that $C_{n,n}$ is minimal in S^{2n+1} and its principal curvatures k_1, \dots, k_{2n} are

$$k_1 = \dots = k_n = 1, \quad k_{n+1} = \dots = k_{2n} = -1.$$

Thus

$$\begin{aligned}
 S_{r+1} &= \sum_{i_1 < i_2 < \dots < i_{r+1}} k_{i_1} k_{i_2} \dots k_{i_{r+1}} \\
 &= \sum_{k=0}^n \binom{n}{k} \binom{n}{r+1-k} 1^k (-1)^{(r+1)-k} + \sum_{k=0}^n \binom{n}{k} \binom{n}{r+1-k} (-1)^k 1^{(r+1)-k} \\
 &= \sum_{k=0}^n \binom{n}{k} \binom{n}{r+1-k} ((-1)^{(r+1)-k} + (-1)^k) \\
 &= 0
 \end{aligned}$$

The last equality is by the fact that $(-1)^{(r+1)-k} + (-1)^k = 0$ when the integer r is even, $k = 0, \dots, r + 1$.

Example 5.6 Let $x: M \rightarrow N^{n+p}(c)$ be an n -dimensional minimal immersion in $(n+p)$ -dimensional space form $N^{n+p}(c)$. If M is an Einstein manifold, then $x: M \rightarrow N^{n+p}(c)$ is 2-minimal.

Proof We have by the assumption

$$\sum_i B_{ii} = 0, \quad R_{ij} = \frac{R}{n} \delta_{ij} \tag{5.26}$$

where R is the scalar curvature of M^n .

Put the condition (5.26) into the Gauss equation (2.5), we have

$$\sum_k \langle B_{ik}, B_{kj} \rangle = \left((n-1)c - \frac{R}{n} \right) \delta_{ij}$$

Then

$$\begin{aligned}
 \mathbf{S}_3 &= \frac{1}{3!} \sum_{\substack{i_1 i_2 i \\ i_1 i_2 j}} \delta_{j_1 j_2 j}^{i_1 i_2 i} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle B_{ij} \\
 &= \frac{1}{3} \sum_{ij} \left[\delta_j^i S_2 - \sum_{\substack{i_1 i_2 \\ i_1 j_2}} \delta_{j_2}^i \delta_{j_1 j}^{i_1 i_2} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \right] B_{ij} \\
 &= \frac{1}{3} \left[S_2 \cdot \sum_i B_{ii} - \sum_{\substack{i_1 i_2 i \\ i_1 j_2 j}} (\delta_{j_1}^{i_1} \delta_j^{i_2} - \delta_j^{i_1} \delta_{j_1}^{i_2}) \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle B_{ij} \right] \\
 &= \frac{1}{3} \left[- \sum_{ij} \left(\sum_k \langle B_{kk}, B_{ij} \rangle - \sum_k \langle B_{jk}, B_{ki} \rangle \right) B_{ij} \right] \\
 &= \frac{1}{3} \sum_{i,j,k} \langle B_{jk}, B_{ki} \rangle B_{ij} \\
 &= \frac{1}{3} \left((n-1)c - \frac{R}{n} \right) \cdot \sum_i B_{ii} \\
 &= 0
 \end{aligned}$$

Therefore $x: M^n \rightarrow N^{n+p}(c)$ is 2-minimal. □

Example 5.7 Let $k_1 > k_2 > \dots > k_g$ be the distinct principal curvatures with multiplicities m_1, \dots, m_g (so that $n = m_1 + m_2 + \dots + m_g$) of n -dimensional isoparametric hypersurfaces M in S^{n+1} . Suppose M is one of the following cases, then M is r -minimal in S^{n+1} .

- (1) If $g = 3$ and $k_1 = \sqrt{3}, k_2 = 0, k_3 = -\sqrt{3}; m_1 = m_2 = m_3 = 2^k (k = 0, 1, 2, 3)$.
- (2) If $g = 4$ and $k_1 = 1 + \sqrt{2}, k_2 = \sqrt{2} - 1, k_3 = 1 - \sqrt{2}, k_4 = -(1 + \sqrt{2})$ with $m_1 = m_2 = m_3 = m_4 = 2$. Now the hypersurfaces are Cartan minimal hypersurface.
- (3) If $g = 6$ and $k_1 = 2 + \sqrt{3}, k_2 = 1, k_3 = 2 - \sqrt{3}, k_4 = -(2 - \sqrt{3}), k_5 = -1, k_6 = -(2 + \sqrt{3}); m_1 = \dots = m_6 = 1$ or 2 .

Firstly, we give an algebraic result. Let M^n be an n -dimensional compact hypersurface of the $(n + 1)$ -dimensional Riemannian manifold N^{n+1} . The principal curvatures of the hypersurface M is denoted by k_1, \dots, k_n . Write

$$S_0 = 1, \quad S_r = \sum_{i_1 < i_2 < \dots < i_r} k_{i_1} k_{i_2} \dots k_{i_r},$$

$$P_0 = n, \quad P_r = \sum_i (k_i)^r \quad (r = 1, 2, \dots, n).$$

We have S_1, \dots, S_n denoted by use of P_1, \dots, P_n

$$S_1 = P_1,$$

$$S_2 = \frac{1}{2!}(-P_2 + P_1^2),$$

$$S_3 = \frac{1}{3!}(2P_3 - 3P_1P_2 + P_1^3),$$

...

$$S_l = \sum_{\substack{t_1+2t_2+\dots+t_l=l \\ 0 \leq t_i}} \frac{(-1)^{t_1+t_2+\dots+t_l+l}}{(t_1!) \dots (t_l!) 2^{t_2} \dots l^{t_l}} P_1^{t_1} P_2^{t_2} \dots P_l^{t_l},$$

...

$$S_n = \sum_{\substack{t_1+2t_2+\dots+t_n=n \\ 0 \leq t_i}} \frac{(-1)^{t_1+t_2+\dots+t_n+n}}{(t_1!) \dots (t_l!) 2^{t_2} \dots n^{t_n}} P_1^{t_1} P_2^{t_2} \dots P_n^{t_n}.$$

Now we consider hypersurfaces (1)–(3) in S^{n+1} above, it is easy to verify that

$$P_1 = P_3 = \dots = P_{r+1} = 0 \tag{5.27}$$

for the even integer r .

On the other side, when $l = r + 1$,

$$S_{r+1} = \sum_{\substack{t_1+2t_2+\dots+(r+1)t_{r+1}=r+1 \\ 0 \leq t_i}} \frac{(-1)^{t_1+t_2+\dots+t_{r+1}+(r+1)}}{(t_1!) \dots (t_{r+1}!) 2^{t_2} \dots (r+1)^{t_{r+1}}} P_1^{t_1} P_2^{t_2} \dots P_{r+1}^{t_{r+1}}. \tag{5.28}$$

We observe that $t_1 + 2t_2 + \dots + (r + 1)t_{r+1} = \sum_{i=0}^{r+1} i \cdot t_i = r + 1$ is odd, then there exists a factor $i \cdot t_i$ such that $i \cdot t_i$ is an odd integer, that is, both i and t_i are odd, we have by (5.27)

$$P_i^{t_i} = 0 \tag{5.29}$$

where $i \in \{0, 1, \dots, r + 1\}$.

Since each term $P_1^{t_1} P_2^{t_2} \dots P_{r+1}^{t_{r+1}}$ of S_{r+1} includes such factor as (5.29), we have $S_{r+1} = 0$, thus we prove that (1)–(3) in example 5.7 are r -minimal.

Remark 5.5 In [19], (1)–(3) in Example 5.7 are given as minimal Willmore hypersurfaces in S^{n+1} .

6 The second variational formula

In this section, suppose $x_0 : M \rightarrow R^{n+p}(c)$ be an n -dimensional compact r -minimal submanifold in $R^{n+p}(c)$ for some even integer $r \in \{0, 1, \dots, n - 1\}$, we will calculate the second variational formula of the functional $J_r(t)$.

Before stating the second variational formula, we still need to introduce some notations when r is even. Define

$$T_{r \ j_{r+1} \ j_{r+2}}^{i_{r+1} \ i_{r+2}} = \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r \ j_{r+1} \ j_{r+2}}^{i_1 \dots i_r \ i_{r+1} \ i_{r+2}} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \tag{6.1}$$

$$T_{r \ j_{r+1} \ j_{r+2} \ j}^{i_{r+1} \ i_{r+2} \ i} = \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r \ j_{r+1} \ j_{r+2} \ j}^{i_1 \dots i_r \ i_{r+1} \ i_{r+2} \ i} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \tag{6.2}$$

Lemma 6.1

$$\begin{aligned} T_{r \ j_{r+1} \ j_{r+2}}^{i_{r+1} \ i_{r+2}} &= \delta_{j_{r+2}}^{i_{r+2}} T_{r \ j_{r+1}}^{i_{r+1}} - \delta_{j_{r+1}}^{i_{r+2}} T_{r \ j_{r+2}}^{i_{r+1}} \\ &\quad - \frac{1}{r-1} \sum_{\alpha} \sum_{\substack{i_{r-1} \ i_r \\ j_{r-1}}} T_{r-2 \ j_{r-1} \ j_{r+1} \ j_{r+2}}^{i_{r-1} \ i_{r+1} \ i_r} h_{i_{r-1} j_{r-1}}^{\alpha} h_{i_r j_{r+2}}^{\alpha}. \end{aligned} \tag{6.3}$$

Proof By Definition (6.1) and the property of $\delta_{j_1 \dots j_r}^{i_1 \dots i_r i_{r+1} i_{r+2}}$, we have

$$\begin{aligned}
 T_r^{i_{r+1} i_{r+2}} &= \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_1 \dots j_r}^{i_1 \dots i_r i_{r+1} i_{r+2}} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \\
 &= \delta_{j_{r+2}}^{i_{r+2}} T_r^{i_{r+1}} - \delta_{j_{r+1}}^{i_{r+2}} T_r^{i_{r+1}} + \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_r}^{i_{r+2}} \delta_{j_1 \dots j_{r-1} j_{r+1} j_{r+2}}^{i_1 \dots i_{r-1} i_r i_{r+1}} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \\
 &\quad \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha h_{i_r j_r}^\alpha - \frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{j_{r-1}}^{i_{r+2}} \delta_{j_1 \dots j_{r-2} j_r j_{r+1} j_{r+2}}^{i_1 \dots i_{r-2} i_{r-1} i_r i_{r+1}} \\
 &\quad \cdot \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \cdots \langle B_{i_{r-3} j_{r-3}}, B_{i_{r-2} j_{r-2}} \rangle h_{i_{r-1} j_{r-1}}^\alpha h_{i_r j_r}^\alpha + \cdots \\
 &= \delta_{j_{r+2}}^{i_{r+2}} T_r^{i_{r+1}} - \delta_{j_{r+1}}^{i_{r+2}} T_r^{i_{r+1}} + \frac{1}{r(r-1)} \sum_{\alpha} \sum_{\substack{i_{r-1} i_r \\ j_{r-1}}} T_{r-2j_{r-1} j_{r+1} j_{r+2}}^{i_{r-1} i_r i_{r+1}} h_{i_{r-1} j_{r-1}}^\alpha h_{i_r i_{r+2}}^\alpha \\
 &\quad - \frac{1}{r(r-1)} \sum_{\alpha} \sum_{\substack{i_{r-1} i_r \\ j_{r-1}}} T_{r-2j_r j_{r+1} j_{r+2}}^{i_{r-1} i_r i_{r+1}} h_{i_{r-1} i_{r+2}}^\alpha h_{i_r j_r}^\alpha + \cdots \\
 &= \delta_{j_{r+2}}^{i_{r+2}} T_r^{i_{r+1}} - \delta_{j_{r+1}}^{i_{r+2}} T_r^{i_{r+1}} - \frac{1}{r(r-1)} \sum_{\alpha} \sum_{\substack{i_{r-1} i_r \\ j_{r-1}}} T_{r-2j_{r-1} j_{r+1} j_{r+2}}^{i_{r-1} i_{r+1} i_r} h_{i_{r-1} j_{r-1}}^\alpha h_{i_r i_{r+2}}^\alpha \\
 &\quad - \frac{1}{r(r-1)} \sum_{\alpha} \sum_{\substack{i_{r-1} i_r \\ j_{r-1}}} T_{r-2j_{r-1} j_{r+1} j_{r+2}}^{i_r i_{r-1} i_{r+1}} h_{i_r i_{r+2}}^\alpha h_{i_{r-1} j_{r-1}}^\alpha + \cdots \\
 &= \delta_{j_{r+2}}^{i_{r+2}} T_r^{i_{r+1}} - \delta_{j_{r+1}}^{i_{r+2}} T_r^{i_{r+1}} - \frac{1}{r(r-1)} \sum_{\alpha} \sum_{\substack{i_{r-1} i_r \\ j_{r-1}}} T_{r-2j_{r-1} j_{r+1} j_{r+2}}^{i_{r-1} i_{r+1} i_r} h_{i_{r-1} j_{r-1}}^\alpha h_{i_r i_{r+2}}^\alpha \\
 &\quad - \frac{1}{r(r-1)} \sum_{\alpha} \sum_{\substack{i_{r-1} i_r \\ j_{r-1}}} T_{r-2j_{r-1} j_{r+1} j_{r+2}}^{i_{r-1} i_{r+1} i_r} h_{i_{r-1} j_{r-1}}^\alpha h_{i_r i_{r+2}}^\alpha + \cdots \\
 &= \delta_{j_{r+2}}^{i_{r+2}} T_r^{i_{r+1}} - \delta_{j_{r+1}}^{i_{r+2}} T_r^{i_{r+1}} - \frac{r}{r(r-1)} \sum_{\alpha} \sum_{\substack{i_{r-1} i_r \\ j_{r-1}}} T_{r-2j_{r-1} j_{r+1} j_{r+2}}^{i_{r-1} i_{r+1} i_r} h_{i_{r-1} j_{r-1}}^\alpha h_{i_r i_{r+2}}^\alpha \\
 &= \delta_{j_{r+2}}^{i_{r+2}} T_r^{i_{r+1}} - \delta_{j_{r+1}}^{i_{r+2}} T_r^{i_{r+1}} - \frac{1}{(r-1)} \sum_{\alpha} \sum_{\substack{i_{r-1} i_r \\ j_{r-1}}} T_{r-2j_{r-1} j_{r+1} j_{r+2}}^{i_{r-1} i_{r+1} i_r} h_{i_{r-1} j_{r-1}}^\alpha h_{i_r i_{r+2}}^\alpha. \quad \square
 \end{aligned}$$

Theorem 6.1 (the second variational formula) *Let M be an n -dimensional compact r -minimal submanifold in $R^{n+p}(c)$ for some even integer $r \in \{0, 1, \dots, n-1\}$, we have*

$$J''(0) = - \int_M \sum_{\alpha} V_{\alpha} \left\{ \frac{1}{r-1} \sum_{\substack{i_{r-1} i_r i \\ j_{r-1} j_r j}} T_{r-2j_{r-1} j_r j}^{i_{r-1} i_r i} h_{i_{r-1} j_{r-1}}^\alpha h_{i_r j_r}^\beta V_{\beta, ij} \right.$$

$$\left. \begin{aligned} & + \sum_{ij} T_{rj}^i V_{\alpha,ij} + c \cdot (n - r)(S_r V_\alpha + \sum_{i,j,\beta} T_{r-1}^\alpha h_{ij}^\beta V_\beta) \\ & - (r + 1) \sum_{i,j,\beta} T_{r+1}^\alpha h_{ij}^\beta V_\beta \end{aligned} \right\} dv \tag{6.4}$$

When $p = 1$, we get by use of (3.9) and (3.10)

Corollary 6.1 (c.f. [5]) *Assume that r is even and $r \in \{0, 1, \dots, n - 1\}$. Let M be an n -dimensional compact r -minimal hypersurface in $R^{n+1}(c)$, then we have*

$$J_r''(0) = -(r + 1) \int_M \lambda [L_r(\lambda) + c \cdot (n - r)S_r \lambda - (r + 2)S_{r+2} \lambda] dv, \tag{6.5}$$

where $V = \lambda e_{n+1}$ and L_r is defined in section 4.

Proof of Theorem 6.1 Because M is r -minimal, thus it satisfies

$$\sum_{ij} T_{rj}^i h_{ij}^\alpha = 0, \quad n + 1 \leq \alpha \leq n + p. \tag{6.6}$$

By use of Theorem 1.1, we have

$$J_r''(0) = -(r + 1) \int_M \left\langle \frac{\partial \mathbf{S}_{r+1}}{\partial t} \Big|_{t=0}, V \right\rangle dv. \tag{6.7}$$

Putting (3.4) into (6.7), we have by use of (6.6)

$$\begin{aligned} J_r''(0) &= -(r + 1) \int_M \left\langle \frac{\partial \mathbf{S}_{r+1}}{\partial t} \Big|_{t=0}, V \right\rangle dV \\ &= - \int_M \left\langle \sum_{i,j,\alpha} \frac{\partial (T_{rj}^i h_{ij}^\alpha e_\alpha)}{\partial t} \Big|_{t=0}, V \right\rangle dV \\ &= - \int_M \left\{ \sum_{i,j,\alpha} \frac{\partial (T_{rj}^i h_{ij}^\alpha)}{\partial t} \Big|_{t=0} V_\alpha \right\} dv. \end{aligned} \tag{6.8}$$

By use of (3.1) and (5.15), we have the following calculation at $t = 0$

$$\begin{aligned}
 \sum_{i,j,\alpha} \frac{\partial(T_{rj}^i h_{ij}^\alpha)}{\partial t} V_\alpha &= \sum_{i,j,\alpha} \left(\frac{\partial T_{rj}^i}{\partial t} h_{ij}^\alpha + T_{rj}^i \frac{\partial h_{ij}^\alpha}{\partial t} \right) V_\alpha \\
 &= \sum_{i,j,\alpha} \frac{\partial}{\partial t} \left(\frac{1}{r!} \sum_{\substack{i_1 \dots i_r \\ j_1 \dots j_r}} \delta_{i_1 \dots i_r}^{j_1 \dots j_r} \langle B_{i_1 j_1}, B_{i_2 j_2} \rangle \dots \langle B_{i_{r-1} j_{r-1}}, B_{i_r j_r} \rangle \right) h_{ij}^\alpha V_\alpha \\
 &\quad + \sum_{i,j,\alpha} T_{rj}^i \frac{\partial h_{ij}^\alpha}{\partial t} V_\alpha \\
 &= \frac{1}{r-1} \sum_{\substack{i_{r-1} i_r \\ j_{r-1} j_r \\ \alpha, \beta}} T_{r-2}^{i_{r-1} i_r} h_{i_{r-1} j_{r-1}}^{i_r} h_{i_r j_r}^\beta \frac{\partial h_{ij}^\alpha}{\partial t} V_\alpha + \sum_{i,j,\alpha} T_{rj}^i \frac{\partial h_{ij}^\alpha}{\partial t} V_\alpha \\
 &= \frac{1}{r-1} \sum_{\substack{i_{r-1} i_r \\ j_{r-1} j_r \\ \alpha, \beta}} T_{r-2}^{i_{r-1} i_r} h_{i_{r-1} j_{r-1}}^{i_r} \frac{\partial h_{ij}^\alpha}{\partial t} h_{i_r j_r}^\beta V_\beta + \sum_{i,j,\alpha} T_{rj}^i \frac{\partial h_{ij}^\alpha}{\partial t} V_\alpha \\
 &= \frac{1}{r-1} \sum_{\substack{i_{r-1} i_r \\ j_{r-1} j_r \\ \alpha, \beta}} T_{r-2}^{i_{r-1} i_r} h_{i_{r-1} j_{r-1}}^{i_r} h_{i_r j_r}^\beta \frac{\partial h_{ij}^\alpha}{\partial t} V_\beta + \sum_{i,j,\alpha} T_{rj}^i \frac{\partial h_{ij}^\alpha}{\partial t} V_\alpha \\
 &= \sum_{i,j,\alpha} \left(\frac{1}{r-1} \sum_{\substack{i_{r-1} i_r \\ j_{r-1} j_r \\ \beta}} T_{r-2}^{i_{r-1} i_r} h_{i_{r-1} j_{r-1}}^{i_r} h_{i_r j_r}^\beta V_\beta + T_{rj}^i V_\alpha \right) \frac{\partial h_{ij}^\alpha}{\partial t} \\
 &= \sum_{i,j,\alpha} \left(\frac{1}{r-1} \sum_{\substack{i_{r-1} i_r \\ j_{r-1} j_r \\ \beta}} T_{r-2}^{i_{r-1} i_r} h_{i_{r-1} j_{r-1}}^{i_r} h_{i_r j_r}^\beta V_\beta + T_{rj}^i V_\alpha \right) \left(V_{\alpha,ij} + c \cdot \delta_{ij} V_\alpha \right. \\
 &\quad \left. + \sum_k (a_{ik} h_{kj}^\alpha + a_{jk} h_{ki}^\alpha + h_{ijk}^\alpha V_k) + \sum_{k,\gamma} h_{ik}^\alpha h_{kj}^\gamma V_\gamma + \sum_\gamma a_{\alpha\gamma} h_{ij}^\gamma \right). \tag{6.9}
 \end{aligned}$$

Now let us compute the terms in the right hand side of (6.9) one by one.

$$\sum_{i,j,\alpha} \left(\frac{1}{r-1} \sum_{\substack{i_{r-1} i_r \\ j_{r-1} j_r \\ \beta}} T_{r-2}^{i_{r-1} i_r} h_{i_{r-1} j_{r-1}}^{i_r} h_{i_r j_r}^\beta V_\beta + T_{rj}^i V_\alpha \right) \left(\sum_k (a_{ik} h_{kj}^\alpha + a_{jk} h_{ki}^\alpha) \right)$$

$$\begin{aligned}
 &= 2 \sum_{j,k} a_{jk} \left(\frac{1}{r-1} \sum_{\substack{i_{r-1}i_r \\ j_{r-1}j_r \\ \alpha,\beta}} T_{r-2}{}^{i_{r-1}i_r i}{}_{j_{r-1}j_r j} h_{i_{r-1}j_{r-1}}{}^\alpha h_{ik}{}^\alpha h_{i_{rj}}{}^\beta V_\beta + \sum_{i,\alpha} T_{rj}{}^i h_{ik}{}^\alpha V_\alpha \right) \\
 &= 2 \sum_{j,k} a_{jk} \sum_{\substack{i_r \\ j_r \\ \beta}} \left(-T_{rj}{}^{i_r k} + \delta_j^k T_{rj}{}^{i_r} - \delta_{j_r}^k T_{rj}{}^{i_r} \right) h_{i_{rj}}{}^\beta V_\beta + 2 \sum_{\alpha} \sum_{i,j,k} a_{jk} T_{rj}{}^i h_{ik}{}^\alpha V_\alpha \\
 &= 2 \sum_{j,k} a_{jk} \left(-(r+1) \sum_{\alpha} T_{r+1kj}{}^\alpha V_\alpha + \delta_j^k \sum_{i_r j_r \beta} T_{rj}{}^{i_r} h_{i_{rj}}{}^\beta V_\beta \right) \\
 &\stackrel{(1)}{=} 0.
 \end{aligned} \tag{6.10}$$

where equality (1) from (3.7) and $a_{jk} = -a_{kj}$.

We have by use of (3.1) and (6.6)

$$\begin{aligned}
 &\sum_{i,j,k,\alpha} \left(\frac{1}{r-1} \sum_{\substack{i_{r-1}i_r \\ j_{r-1}j_r \\ \beta}} T_{r-2}{}^{i_{r-1}i_r i}{}_{j_{r-1}j_r j} h_{i_{r-1}j_{r-1}}{}^\alpha h_{i_{rj}}{}^\beta V_\beta + T_{rj}{}^i V_\alpha \right) h_{ijk}{}^\alpha V_k \\
 &= \sum_{i,j,k,\alpha} (T_{rj}{}^i h_{ij}{}^\alpha)_{,k} V_k V_\alpha \\
 &= 0.
 \end{aligned} \tag{6.11}$$

We have by use of (6.2), (6.1) and (3.8)

$$\begin{aligned}
 &\sum_{i,j,\alpha} \left(\frac{1}{r-1} \sum_{\substack{i_{r-1}i_r \\ j_{r-1}j_r \\ \beta}} T_{r-2}{}^{i_{r-1}i_r i}{}_{j_{r-1}j_r j} h_{i_{r-1}j_{r-1}}{}^\alpha h_{i_{rj}}{}^\beta V_\beta + T_{rj}{}^i V_\alpha \right) \delta_{ij} V_\alpha \cdot c \\
 &= c \cdot \frac{n-r}{r-1} \sum_{\substack{i_{r-1}i_r \\ j_{r-1}j_r \\ \alpha,\beta}} T_{r-2}{}^{i_{r-1}i_r i}{}_{j_{r-1}j_r j} h_{i_{r-1}j_{r-1}}{}^\alpha h_{i_{rj}}{}^\beta V_\alpha V_\beta + c \cdot (n-r) \sum_{\alpha} S_r V_\alpha^2 \\
 &= c \cdot (n-r) \left(\sum_{\substack{ij \\ \alpha,\beta}} T_{r-1}{}^\alpha{}_{ij} h_{ij}{}^\beta V_\alpha V_\beta + \sum_{\alpha} S_r V_\alpha^2 \right)
 \end{aligned} \tag{6.12}$$

We have by use of (6.3) and (6.6)

$$\sum_{i,j,\alpha} \left(\frac{1}{r-1} \sum_{\substack{i_{r-1}i_r \\ j_{r-1}j_r \\ \beta}} T_{r-2}{}^{i_{r-1}i_r i}{}_{j_{r-1}j_r j} h_{i_{r-1}j_{r-1}}{}^\alpha h_{i_{rj}}{}^\beta V_\beta + T_{rj}{}^i V_\alpha \right) h_{ik}{}^\alpha h_{kj}{}^\gamma V_\gamma$$

$$\begin{aligned}
 &= \sum_{i,j,\alpha} \left(\frac{1}{r-1} \sum_{\substack{i_{r-1}i_r \\ j_{r-1}j_r \\ \beta}} T_{r-2}^{i_{r-1}i_r} h_{i_{r-1}j_{r-1}}^\alpha h_{ik}^\alpha h_{i_{r-1}j_r}^\beta h_{kj}^\gamma V_\beta V_\gamma + \sum_{k,\gamma} T_{rj}^i h_{ik}^\alpha h_{kj}^\gamma V_\alpha V_\gamma \right) \\
 &= \sum_{\beta,\gamma} \sum_{\substack{i_r k \\ j k}} (-T_{rj}^{i_r k} + \delta_j^k T_{rj}^{i_r} - \delta_{jr}^k T_{rj}^{i_r}) h_{i_r j}^\beta h_{kj}^\gamma V_\beta V_\gamma + \sum_{\alpha,\beta} \sum_{i,j,k} T_{rj}^i h_{ik}^\alpha h_{kj}^\beta V_\alpha V_\beta \\
 &= \sum_{\alpha,\beta} (-(r+1) \sum_{j,k} T_{r+1}^\beta h_{kj}^\alpha V_\beta V_\alpha + \sum_{i,j_r} T_{rj_r}^{i_r} h_{i_r j_r}^\beta n H^\alpha V_\alpha V_\beta) \\
 &= -(r+1) \sum_{\alpha,\beta} \sum_{ij} T_{r+1}^\alpha h_{ij}^\beta V_\alpha V_\beta. \tag{6.13}
 \end{aligned}$$

Putting (6.10), (6.11), (6.12) and (6.13) into (6.9), we get (6.4) from (6.8). Thus we complete the proof of Theorem 6.1.

Definition 6.1 Assume that r is even and $r \in \{0, 1, \dots, n-1\}$, and let M be an n -dimensional compact r -minimal submanifold in an $(n+p)$ -dimensional space form $R^{n+p}(c)$. If $J_r''(0) \geq 0$ for arbitrary variations, we call M to be stable.

7 Proofs of Theorem 1.4 and Theorem 1.5

Proof of Theorem 1.4 Now let $x: M \rightarrow S^{n+p} \hookrightarrow R^{n+p+1}$ be an n -dimensional compact submanifold of an $(n+p)$ -dimensional unit sphere S^{n+p} in R^{n+p+1} . Suppose $\{e_j\}$ is a local orthonormal basis for TM and $\{e_\alpha\}$ is a local orthonormal basis for the normal bundle of $x: M \rightarrow S^{n+p}$. Let E_1, \dots, E_{n+p+1} be a canonical orthonormal basis of R^{n+p+1} . For a fixed $E_A \in R^{n+p+1}$, $1 \leq A \leq n+p+1$, we define

$$f_A = \langle x, E_A \rangle \tag{7.1}$$

$$g_{\alpha A} = \langle e_\alpha, E_A \rangle \tag{7.2}$$

for a normal vector e_α of the immersion $x: M \rightarrow S^{n+p}$, $n+1 \leq \alpha \leq n+p$. Since x is contained in a unit sphere S^{n+p} in R^{n+p+1} , then

$$\begin{cases}
 \sum_{A=1}^{n+p+1} f_A^2 = \sum_A \langle x, E_A \rangle \langle x, E_A \rangle = \|x\|^2 = 1, \\
 \sum_A f_A g_{\alpha A} = \sum_A \langle x, E_A \rangle \langle e_\alpha, E_A \rangle = \langle x, e_\alpha \rangle = 0, \\
 \sum_A g_{\alpha A} g_{\beta A} = \sum_A \langle e_\alpha, E_A \rangle \langle e_\beta, E_A \rangle = \langle e_\alpha, e_\beta \rangle = \delta_{\alpha\beta}, \\
 \sum_A \sum_{\alpha=n+1}^{n+p} g_{\alpha A}^2 = \sum_A \sum_\alpha \langle e_\alpha, E_A \rangle \langle e_\alpha, E_A \rangle = \sum_\alpha \langle e_\alpha, e_\alpha \rangle = p
 \end{cases} \tag{7.3}$$

Let $I(V^\perp) = J_r''(0)$, we now choose a special normal variational vector field

$$V^\perp = V_A^\perp = \sum_\alpha V_\alpha e_\alpha = \sum_\alpha g_{\alpha A} e_\alpha, \tag{7.4}$$

for a fixed index A , $1 \leq A \leq n+p+1$.

From Theorem 6.1, we have the following calculation by use of $c = 1$, (4.15), (7.3), $S_{r+1} \equiv 0$ and Lemma 6.1

$$\begin{aligned} \sum_A I(V_A^\perp) &= - \sum_A \int_M \sum_\alpha \langle e_\alpha, EA \rangle \left\{ \frac{1}{r-1} \sum_{\substack{i_{r-1}i_r i \\ j_{r-1}j_r j}} T_{r-2}^{i_{r-1}i_r i} h_{i_{r-1}j_{r-1}}^\alpha h_{i_r j_r}^\beta \cdot \right. \\ &\quad \cdot \langle e_\beta, EA \rangle_{,ij} + \sum_{i,j} T_{rj}^i \langle e_\alpha, EA \rangle_{,ij} + (n-r) \left(S_r \langle e_\alpha, EA \rangle + \sum_{i,j,\beta} T_{r-1}^{\alpha ij} h_{ij}^\beta \langle e_\beta, EA \rangle \right) \\ &\quad \left. - (r+1) \sum_{i,j,\beta} T_{r+1}^{\alpha ij} h_{ij}^\beta \langle e_\beta, EA \rangle \right\} dv \\ &= - \int_M \left\{ \frac{1}{r-1} \sum_A \sum_{\substack{i_{r-1}i_r i \\ j_{r-1}j_r j}} T_{r-2}^{i_{r-1}i_r i} h_{i_{r-1}j_{r-1}}^\alpha h_{i_r j_r}^\beta \langle e_\alpha, EA \rangle \left(- \sum_k h_{ikj}^\beta \langle e_k, EA \rangle \right. \right. \\ &\quad \left. \left. - \sum_{k,\gamma} h_{ik}^\beta h_{kj}^\gamma \langle e_\gamma, EA \rangle + h_{ij}^\beta \langle x, EA \rangle \right) + \sum_A \sum_{i,j,\alpha} T_{rj}^i \langle e_\alpha, EA \rangle \left(- \sum_k h_{ikj}^\alpha \langle e_k, EA \rangle \right. \right. \\ &\quad \left. \left. - \sum_{k,\gamma} h_{ik}^\alpha h_{kj}^\gamma \langle e_\gamma, EA \rangle + h_{ij}^\alpha \langle x, EA \rangle \right) + (n-r) \left(pS_r + \sum_{i,j,\alpha} T_{r-1}^{\alpha ij} h_{ij}^\alpha \right) \right. \\ &\quad \left. - (r+1) \sum_{i,j,\alpha} T_{r+1}^{\alpha ij} h_{ij}^\alpha \right\} dv \\ &= - \int_M \left\{ - \frac{1}{r-1} \sum_{\substack{i_{r-1}i_r i \\ j_{r-1}j_r j}} T_{r-2}^{i_{r-1}i_r i} h_{i_{r-1}j_{r-1}}^\alpha h_{i_r j_r}^\beta h_{ik}^\alpha h_{ij_r}^\beta h_{ik}^\beta - \sum_{i,j,k,\alpha} T_{rj}^i h_{ik}^\alpha h_{kj}^\alpha \right. \\ &\quad \left. + (n-r)(pS_r + rS_r) - (r+2)(r+1)S_{r+2} \right\} dv \\ &= - \int_M \left\{ \sum_{\substack{i_r i \\ j_r k \\ \beta}} (T_{rj_r k}^{i_r i} - \delta_k^i T_{rj_r}^{i_r} + \delta_{j_r}^i T_{rk}^{i_r}) h_{i_r j_r}^\beta h_{ik}^\beta - \sum_{i,j,k,\alpha} T_{rj}^i h_{ik}^\alpha h_{kj}^\alpha \right. \end{aligned}$$

$$\begin{aligned}
 & \left. \begin{aligned} & + (n - r)(p + r)S_r - (r + 2)(r + 1)S_{r+2} \end{aligned} \right\} dv \\
 & = - \int_M \{(r + 2)(r + 1)S_{r+2} + (n - r)(p + r)S_r - (r + 2)(r + 1)S_{r+2}\} dv \\
 & = - (n - r)(p + r) \int_M S_r dv
 \end{aligned}$$

When $S_r > 0$, we have $I(V^\perp) = J_r''(0) < 0$, i.e. if S_r is positive, there exists no any compact without boundary stable r -minimal submanifold in S^{n+p} , this completes the proof of Theorem 1.4.

Proof of Theorem 1.5 Let M be an n -dimensional compact r -minimal hypersurface in S^{n+1} with $S_r \geq 0$. Suppose M is stable, that is to say, $I(V^\perp) = J_r''(0) \geq 0$ for arbitrary variations. Choosing a special normal variational vector field $V = V_A^\perp = g_{n+1A}e_{n+1}$, we have above

$$\sum_A I(V_A^\perp) = -(n - r)(r + 1) \int_M S_r dv \geq 0. \tag{7.5}$$

By assumption $S_r \geq 0$, we have

$$S_r = 0 \tag{7.6}$$

on M . On the other hand, by assumption condition that M is r -minimal, then

$$S_{r+1} = 0. \tag{7.7}$$

We have the following algebraic inequalities (see [14])

$$H_r H_{r+2} \leq H_{r+1}^2 \tag{7.8}$$

and equality holds in above inequality if and only if $k_1 = \dots = k_n$.

From (7.6) and (7.7), we know that the equality in (7.8) holds, thus $k_1 = \dots = k_n = 0$ on M , we conclude that M is a geodesic sphere.

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