

**Q.1.** Answer the following

(i) Consider the set

$$E = \{(x, y, z) \in R^3 : xy = 1, 0 \leq z \leq 1\}.$$

Is the set  $E$  connected? For  $p = (1, 1, 0) \in E$ , find the component  $C_p$ . [2]

(ii) Let  $X = D \cup \{(0, \frac{1}{2})\}$  be the subspace of  $R^2$ , where  $D$  is the deleted comb space. Find the path components of  $X$ . [3]

(iii) Give an example of a topological space  $X$  and a point  $x \in X$  such that  $C_x \neq Q_x$ . [3]

(iv) Use the continuity of determinant function to check whether the general linear group  $GL(n, R)$  is connected. [2]

**Solution:** (i) For the space  $E = E_1 \cup E_2$ , where

$$E_1 = \{(x, y, z) \in R^3 : xy = 1, x > 0, 0 \leq z \leq 1\}$$

and

$$E_2 = \{(x, y, z) \in R^3 : xy = 1, x < 0, 0 \leq z \leq 1\}$$

is a separation and therefore  $E$  is not connected. Infact both  $E_1$  and  $E_2$  are connected and are components of  $E$ .  $C_p = E_1$ .

(ii) Let  $p = (0, 1)$ ,  $q = (0, \frac{1}{2})$  and  $x \in D - \{p\}$ . Then the path components of  $X$  are

$$C_p = \{(0, 1)\}, \quad C_q = \left\{ \left(0, \frac{1}{2}\right) \right\}, \quad C_x = D - \{p\}$$

(iii) Consider the subspace  $X = \{(0, 0), (1, 0)\} \cup \{(x, y) \in R^2 : 0 \leq x \leq 1, y = \frac{1}{n}, n \text{ a natural number}\}$  of  $R^2$ . If we denote  $p = (0, 0)$  and  $q = (1, 0)$ . Then we get  $C_p = \{p\}$  and  $Q_p = \{p, q\}$  that is  $C_p \neq Q_p$ .

(iv) The function  $f : GL(n, R) \rightarrow R$  defined by  $f(X) = \det X$  is a continuous function and  $f(GL(n, R)) = R - \{0\}$ . If  $GL(n, R)$  is connected, its continuous image  $R - \{0\}$  is connected which is a contradiction. Hence  $GL(n, R)$  is not connected.

**Q.2.** Answer the following

(i) Show that in a locally connected space  $X$  the components  $C_x$  are open subsets of  $X$ . Is the converse true? (Justify your answer by either giving a proof or a counter example). [3]

(ii) Show that the product  $X \times Y$  is path connected if both  $X$  and  $Y$  are path connected. Is the converse true? [2]

(iii) If  $X$  is locally path connected space, then show that  $P_x = C_x = Q_x$ . [2]

(iv) Show that the subspaces  $X = (0, 1) \cup [2, 3)$  and  $Y = (0, 1) \cup (2, 3)$  of  $R$  are not homeomorphic. [3]

**Solution:** (i) Suppose  $X$  is locally connected and  $y \in C_x$ . Then for any open subset  $U \subset X$  containing  $y$ , as  $X$  is locally connected, there is a connected neighbourhood  $V$  of  $y$  satisfying  $y \in V \subset U$ . However as  $C_x$  is the largest connected subset containing  $y$ , we get  $y \in V \subset C_x$  and this proves  $C_x$  is open subset of  $X$ . The converse is not true for example the component  $C_x = D$  of deleted comb space is open where as  $D$  is not locally connected. (Note: Do not get confused with the characterization of locally connected space where every open set is used that is  $X$  is locally connected if and only if for each open set  $U$  the components of  $U$  are open subsets of  $X$ )

(ii) Take two points  $p = (x_1, y_1)$ ,  $q = (x_2, y_2) \in X \times Y$ . Then as  $X$  and  $Y$  are path connected, for  $x_1, x_2 \in X$  and  $y_1, y_2 \in Y$ , there exists paths  $\alpha : [0, 1] \rightarrow X$  and  $\beta : [0, 1] \rightarrow Y$  such that  $\alpha(0) = x_1, \alpha(1) = x_2$  and  $\beta(0) = y_1, \beta(1) = y_2$  respectively. Then  $\gamma : [0, 1] \rightarrow X \times Y$  defined by  $\gamma(t) = (\alpha(t), \beta(t))$  is the path in  $X \times Y$  that joins  $p$  to  $q$ . This proves that  $X \times Y$  is path connected. The converse is also true.

(iii) We know that in a locally path connected space  $X$ , we have  $P_x = C_x$ . Since a locally path connected space is locally connected we have  $C_x = Q_x$ . Thus in a locally path connected space we have  $P_x = C_x = Q_x$ .

(iv) If  $X = (0, 1) \cup [2, 3)$  and  $Y = (0, 1) \cup (2, 3)$  are homeomorphic, there is a homeomorphism  $f : X \rightarrow Y$  with  $f(2) = a \in Y$ . Thus  $f : X - \{2\} \rightarrow Y - \{a\}$  is also a homeomorphism and which produces a one-to-one correspondence between the sets of components of  $X - \{2\}$  and  $Y - \{a\}$ , which is a contradiction as  $X - \{2\} = (0, 1) \cup (2, 3)$  has two components and  $Y - \{a\}$  has three components. Hence  $X$  is not homeomorphic to  $Y$ .

**Q.3.** (i) Let  $U \subset R^n$  be an open subset and  $p \in U$ . If  $f : U \rightarrow R^m$  is differentiable at  $p$ , then show that there is a **unique**  $T \in L(R^n, R^m)$  such that  $D_p f = T$ . [3]

(ii) Let  $U \subset R^n$  be an open subset and  $p \in U$ . If  $f : U \rightarrow R^m$  is differentiable at  $p$ , find the matrix of  $D_p f$ . [3]

(iii) Assume that the function  $f : R^2 \rightarrow R^3$  defined by  $f(x, y, z) = (\frac{1}{2}(x^2 - y^2), xy, \frac{1}{2}(x^2 + y^2))$  is differentiable at  $p = (1, 1) \in R^2$  and find the rank of  $D_p f$ . [3]

**Solution:** (i) Suppose that there are two  $T_1, T_2 \in L(R^n, R^m)$  satisfying the requirement of differentiability of  $f$  at  $p \in U$ , that is

$$\lim_{X \rightarrow 0} \frac{\|f(p+X) - f(p) - T_1(X)\|}{\|X\|} = 0, \lim_{X \rightarrow 0} \frac{\|f(p+X) - f(p) - T_2(X)\|}{\|X\|} = 0$$

This is equivalent to

$$f(p+X) = f(p) + T_1(X) + \|X\| \epsilon_1(X), f(p+X) = f(p) + T_2(X) + \|X\| \epsilon_2(X)$$

where  $\epsilon_i(X) \rightarrow 0$  as  $X \rightarrow 0$  for  $i = 1, 2$ .

Thus we have for  $t \in R$  and using above relations that

$$\begin{aligned}
\|T_1(X) - T_2(X)\| &= \lim_{t \rightarrow 0} \frac{|t|}{|t|} \|T_1(X) - T_2(X)\| = \lim_{t \rightarrow 0} \frac{1}{|t|} \|T_1(tX) - T_2(tX)\| \\
&= \lim_{t \rightarrow 0} \frac{1}{|t|} \|f(p + tX) - f(p) - \|tX\| \epsilon_1(tX) - f(p + tX) + f(p) + \|tX\| \epsilon_2(tX)\| \\
&= \lim_{t \rightarrow 0} \frac{\|tX\|}{|t|} \|-\epsilon_1(tX) + \epsilon_2(tX)\| = \lim_{t \rightarrow 0} \|X\| \|-\epsilon_1(tX) + \epsilon_2(tX)\| = 0
\end{aligned}$$

Hence  $T_1 = T_2$ .

(ii) Now suppose  $f : U \rightarrow R^m$ , ( $U \subset R^n$  is open subset) is differentiable at  $p \in U$ . Then as the derivative  $D_p f : R^n \rightarrow R^m$  is a linear transformation, we choose the canonical bases  $\{e_1, \dots, e_n\} \subset R^n$  and  $\{E_1, \dots, E_m\} \subset R^m$ , that is  $e_i = (0, \dots, 0, 1, 0, \dots, 0) \in R^n$  that is a vector in  $R^n$  with 1 at  $i^{\text{th}}$  place and 0 at other places, similarly  $E_i = (0, \dots, 0, 1, 0, \dots, 0) \in R^m$ . In order to find the matrix of  $D_p f$ , we need to find the value of  $(D_p f)(e_j)$  and express it as linear combination of the vectors in the basis  $\{E_1, \dots, E_m\}$ . We observe that any  $u = (\lambda_1, \dots, \lambda_m) \in R^m$  is expressed as

$$u = \lambda_1 E_1 + \dots + \lambda_m E_m = \sum_{i=1}^m \lambda_i E_i$$

Using equation (6) we have

$$(D_p f)(e_j) = ((D_p f^1)(e_j), \dots, (D_p f^m)(e_j)) \in R^m$$

and consequently

$$(D_p f)(e_j) = \sum_{i=1}^m (D_p f^i)(e_j) E_i \tag{7}$$

Now as  $f^i : U \rightarrow R$  is differentiable at  $p$ , we can use Proposition-2 to evaluate  $(D_p f^i)(e_j)$  as

$$(D_p f^i)(e_j) = \lim_{t \rightarrow 0} \frac{1}{t} [f^i(p + te_j) - f^i(p)]$$

Note that if  $p = (a_1, \dots, a_j, \dots, a_n)$ , then  $p + te_j = (a_1, \dots, a_j + t, \dots, a_n)$  and consequently

$$\begin{aligned}
\lim_{t \rightarrow 0} \frac{1}{t} [f^i(p + te_j) - f^i(p)] &= \lim_{t \rightarrow 0} \frac{1}{t} [f^i((a_1, \dots, a_j + t, \dots, a_n)) - f^i((a_1, \dots, a_j, \dots, a_n))] \\
&= \frac{\partial f^i}{\partial x^j}(p)
\end{aligned}$$

where  $\frac{\partial f^i}{\partial x^j}(p)$  is the partial derivative of  $f^i$  with respect to the  $j^{\text{th}}$  coordinate at the point  $p$ . Thus we have computed

$$(D_p f^i)(e_j) = \frac{\partial f^i}{\partial x^j}(p)$$

and then by equation (7) we have

$$(D_p f)(e_j) = \sum_{i=1}^m \frac{\partial f^i}{\partial x^j}(p) E_i$$

This gives the  $m \times n$  matrix of the derivative  $D_p f$  as

$$D_p f = \begin{bmatrix} \frac{\partial f^1}{\partial x^1}(p) & \dots & \dots & \frac{\partial f^1}{\partial x^n}(p) \\ \vdots & \ddots & \ddots & \vdots \\ \frac{\partial f^m}{\partial x^1}(p) & \dots & \dots & \frac{\partial f^m}{\partial x^n}(p) \end{bmatrix}$$

(iii) We have  $f^1 = \frac{1}{2}(x^2 - y^2)$ ,  $f^2 = xy$  and  $f^3 = \frac{1}{2}(x^2 + y^2)$ , consequently at the point  $p = (1, 1)$

$$D_p f = \begin{bmatrix} 1 & -1 \\ 1 & 1 \\ 1 & 1 \end{bmatrix}$$

Since the matrix  $\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$  is non-singular,  $\text{Rank} D_p f = 2$ .

**Q.4.** (i) Show that the function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  defined by

$$f(x, y) = e^{2x} \cos x$$

is differentiable at  $p = (a, b) \in \mathbb{R}^2$  and find  $D_p f$ . [4]

(ii) Let  $U, V \subset \mathbb{R}^n$  be an open subsets and  $p \in U$ . If  $f : U \rightarrow V$  is one-one on-to differentiable at  $p$  and  $f^{-1} : V \rightarrow U$  is differentiable at  $q = f(p)$ , then show that  $D_p f$  is non-singular and find  $(D_p f)^{-1}$ . [3]

(iii) Assume that the function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $f(x, y) = (\frac{1}{2}(x^2 - y^2), \frac{1}{2}(x^2 + y^2))$  is differentiable at  $p = (1, 1) \in \mathbb{R}^2$  and show that there exist neighbourhoods  $U$  and  $V$  of  $p$  and  $q = (0, 1)$  respectively, such that  $f : U \rightarrow V$  is one-one and on-to. Is  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  one-one on-to? [3]

**Solution:** (i) Consider the map  $T : \mathbb{R}^2 \rightarrow \mathbb{R}$  defined by  $T(x, y) = xe^{2a}(2 \cos a - \sin a)$  and it is easy to show that  $T$  is a linear transformation and thus  $T \in L(\mathbb{R}^2, \mathbb{R})$ . Using L'Hospital's rule one can show that

$$\lim_{(x,y) \rightarrow (0,0)} \frac{|f(p+X) - f(p) - T(X)|}{\|X\|} = 0$$

where  $X = (x, y)$ . Hence  $f$  is differentiable at  $p$  and  $D_p f = T$ .

(ii) We have  $f \circ f^{-1} = I$  and  $f^{-1} \circ f = I$ . Then letting  $f(p) = q$  and using Chain rule we have  $D_p (f^{-1} \circ f) = I$  and  $D_q (f \circ f^{-1}) = I$  which gives

$$D_q f^{-1} \circ D_p f = I \text{ and } D_p f \circ D_q f^{-1} = I$$

that is the linear transformation  $D_p f$  is invertible and its inverse is given by

$$(D_p f)^{-1} = D_q f^{-1}$$

In particular we see that  $\det(D_p f) \neq 0$  at each point  $p$ .

(iii) We have  $f$  differentiable at  $p = (1, 1)$  and  $f^1 = \frac{1}{2}(x^2 - y^2)$  and  $f^2 = \frac{1}{2}(x^2 + y^2)$  and thus the matrix of  $D_p f$  is given by

$$D_p f = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

We have  $\det D_p f = 2 \neq 0$  and thus by inverse function theorem there exist neighbourhoods  $U$  and  $V$  of  $p$  and  $f(p) = (0, 1) = q$  respectively such that  $f : U \rightarrow V$  is one-one and on-to. Note that  $f(1, 1) = f(-1, -1)$  and therefore,  $f$  is not one-one. Also, for  $(0, -1) \in \mathbb{R}^2$  there is no point in  $\mathbb{R}^2$  such that  $f(x, y) = (0, -1)$  and thus  $f$  is not on-to.

**Q.5.** (i) Let  $U \subset S^2$  be defined by  $U = \{(x, y, z) \in S^2 : x > 0\}$  and  $B_1^2(0) \subset R^2$  be the open ball in  $R^2$  of radius 1 centered at origin. Show that  $(U, \varphi)$  is a chart on  $S^2$ , where  $\varphi : U \rightarrow B_1^2(0)$  is defined by

$$\varphi(x, y, z) = (y, z)$$

Also show that this chart belongs to the differentiable structure of  $S^2$ . [4]

(ii) Let  $f : S^2 \rightarrow R$  be  $f(x, y, z) = z$ , and  $p = (0, 0, 1) \in S^2$ . Show that  $f$  is smooth at  $p$ . Choose a chart  $(U, \varphi)$  around  $p$  on  $S^2$  with local coordinates  $x^1, x^2$  and find the partial derivatives

$$\frac{\partial f}{\partial x^1}(p), \quad \frac{\partial f}{\partial x^2}(p)$$

[4]

(iii) Consider the functions  $f, g : R^2 \rightarrow R$  defined by  $f(x, y) = \frac{1}{2}(x^2 - y^2)$ ,  $g(x, y) = \frac{1}{2}(x^2 + y^2)$ . Show that there exists a chart  $(U, \varphi)$  around  $p = (1, 1) \in R^2$  with local coordinates  $f, g$ . [3]

**Solution:** (i) First note that as  $\pi_1 : R^3 \rightarrow R$ ,  $\pi(x, y, z) = x$  is a continuous function the set  $\pi_1^{-1}(0, \infty) \cap S^2 = U$  is open subset of  $S^2$ . Now as the component functions of  $\varphi$  are continuous, the map  $\varphi : U \rightarrow B_1^2(0)$  is continuous. Moreover, if  $\varphi(x, y, z) = \varphi(a, b, c)$ ,  $(x, y, z), (a, b, c) \in U$ . Then we have  $(y, z) = (b, c)$ , that is  $y = b$  and  $z = c$ . Thus we have  $x^2 = 1 - y^2 - z^2 = 1 - b^2 - c^2 = a^2$  that is  $x = \pm a$ . As both  $x$  and  $a$  are positive, we have  $x = a$  and this proves that  $\varphi$  is one-one. Also for  $(u, v) \in B_1^2(0)$ , as  $u^2 + v^2 < 1$ , we get  $(\sqrt{1 - u^2 - v^2}, u, v) \in U$  and that

$$\varphi(\sqrt{1 - u^2 - v^2}, u, v) = (u, v)$$

that is  $\varphi$  is on-to. The inverse of  $\varphi$  is given by

$$\varphi^{-1}(u, v) = (\sqrt{1 - u^2 - v^2}, u, v)$$

which is also continuous and consequently  $\varphi$  is a homeomorphism and this proves that  $(U, \varphi)$  is a chart on  $S^2$ . We know that the differentiable structure  $S$  on  $S^2$  is given by the collection  $\{(V, \psi), (W, f)\}$  where  $V = S^2 - \{(0, 0, 1)\}$  and  $W = S^2 - \{(0, 0, -1)\}$  and the maps  $\psi, f$  are defined by

$$\psi(x, y, z) = \left( \frac{x}{1-z}, \frac{y}{1-z} \right), \quad f(x, y, z) = \left( \frac{x}{1+z}, \frac{y}{1+z} \right)$$

with their inverses

$$\psi^{-1}(u, v) = \left( \frac{2u}{1+u^2+v^2}, \frac{2v}{1+u^2+v^2}, \frac{u^2+v^2-1}{1+u^2+v^2} \right)$$

and

$$f^{-1}(u, v) = \left( \frac{2u}{1+u^2+v^2}, \frac{2v}{1+u^2+v^2}, \frac{1-u^2-v^2}{1+u^2+v^2} \right)$$

Observe that  $U \cap V \neq \emptyset$  and  $U \cap W \neq \emptyset$  and we have to check for the smoothness of the maps  $\varphi \circ \psi^{-1}$ ,  $\psi \circ \varphi^{-1}$ ,  $\varphi \circ f^{-1}$  and  $f \circ \varphi^{-1}$ . We have

$$\begin{aligned} \varphi \circ \psi^{-1}(u, v) &= \varphi \left( \frac{2u}{1+u^2+v^2}, \frac{2v}{1+u^2+v^2}, \frac{u^2+v^2-1}{1+u^2+v^2} \right) \\ &= \left( \frac{2v}{1+u^2+v^2}, \frac{u^2+v^2-1}{1+u^2+v^2} \right) \end{aligned}$$

which is clearly a smooth map. Similarly we can show for other three maps  $\psi \circ \varphi^{-1}$ ,  $\varphi \circ f^{-1}$  and  $f \circ \varphi^{-1}$ . Hence  $(U, \varphi) \in S$ .

(ii) We choose a chart  $(U, \varphi)$  on  $S^2$  defined by  $U = \{(x, y, z) \in S^2 : z > 0\}$  and  $\varphi : U \rightarrow B_1^2(0)$  given by  $\varphi(x, y, z) = (x, y)$  where  $B_1^2(0)$  is the open ball of radius 1 centered at origin in  $R^2$ . It is easy to show that this chart is in the differential structure of  $S^2$  with

$$\varphi^{-1}(u, v) = \left(u, v, \sqrt{1 - u^2 - v^2}\right)$$

We have

$$f \circ \varphi^{-1}(u, v) = f\left(u, v, \sqrt{1 - u^2 - v^2}\right) = \sqrt{1 - u^2 - v^2}$$

which is smooth and therefore the function  $f$  is smooth. Now we compute the partial derivatives of  $f$  with respect to the local coordinates  $x^1, x^2$  on  $U$ . We have (note that  $\varphi(p) = (0, 0)$ )

$$\begin{aligned} \frac{\partial f}{\partial x^1}(p) &= \frac{\partial}{\partial u}(f \circ \varphi^{-1})(0, 0) \\ &= \frac{\partial}{\partial u} f\left(u, v, \sqrt{1 - u^2 - v^2}\right)(0, 0) \\ &= \frac{\partial}{\partial u} \left(\sqrt{1 - u^2 - v^2}\right)(0, 0) = 0 \end{aligned}$$

Similarly we compute

$$\frac{\partial f}{\partial x^2}(p) = 0$$

(iii) On  $R^2$  we have the local coordinates  $x, y$  defined on  $R^2$  and we have the functional determinant

$$\frac{D(f, g)}{D(x, y)}(p) = \det \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = 2 \neq 0$$

Hence there exists a chart  $(U, \varphi)$  around  $p$  on  $R^2$  with local coordinates  $f, g$ .