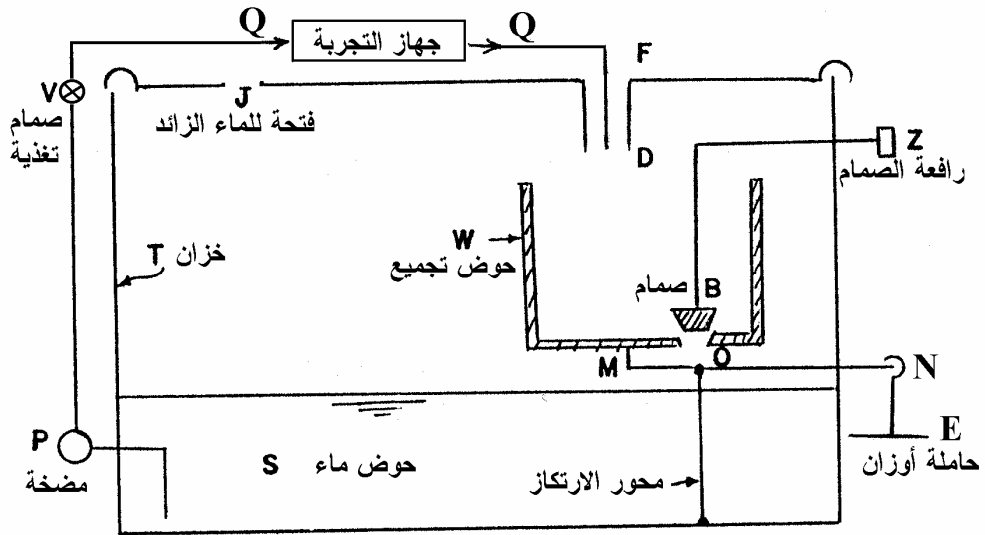


(Hydraulic Bench)

)
 (P) (T) (
 (S)
 (V)
 (W)
 (W) (F) (D)
 (M) (W)
 (W) (E) (N)
 (O)
 (J)
 (B)
 (Z) (W) (W)



()



. (V)

. (F)

:

-

-

-

:

(Z)

(B)

(W)

(N)

(E)

(N)

(N)

(T)

(,)

(,)

/

()

:

Qact

$$Q_{act} = \frac{\forall}{T}$$

(B)

(E)